

02/15/2018

(1)

Recap

Subspace, definition of a subspace

3 conditions

OR 1 unified condition

Col A:

$A: m \times n$ matrix

$$A = [\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_n]$$

$$\text{Col } A \equiv \text{span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n\}$$

Nul A:

$\text{Nul } A \equiv$ solution set of $A\vec{x} = \vec{0}$

A basis for a subspace H, 2 conditions

Definition: *) $\{\vec{a}_1, \dots, \vec{a}_p\}$ is linearly independent

*) $\text{Span}\{\vec{a}_1, \dots, \vec{a}_p\} = H$

A basis for Col A

*) Use echelon form to identify pivot columns

*) Take pivot columns of matrix A.

*) DO NOT take pivot columns of echelon form.

Theorem 13: The pivot columns of A form a basis for Col A

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A very simple example.

$$A = \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} \xrightarrow{\text{row reduction}} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$\left\{ \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} \right\}$ is a basis for Col A

$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}$ is NOT a basis for Col A

A basis for Nul A

$\left\{ \text{vectors in the solution set in parametric form} \right\}$

Q: For a given \vec{b} , is \vec{b} in Col A?
How to check?

Q: Is $\text{Col } A = \mathbb{R}^m$? $A = m \times n$ matrix

Q: For a given \vec{u} , is \vec{u} in Nul A?
How to check?

Sec 2.9. Dimension and rank

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dimension of a subspace

rank of a matrix

Theorem 7. of sec 4.4 (Unique representation theorem)

Let $B = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_p\}$ be a basis for a subspace H .

Then, for each \vec{x} in H , there is one and only one set of coefficients $\{c_1, c_2, \dots, c_p\}$ such that

$$\vec{x} = c_1 \vec{b}_1 + c_2 \vec{b}_2 + \dots + c_p \vec{b}_p$$

proof:

"Existence"

$$\text{Span}\{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_p\} = H$$

$$\Rightarrow \vec{x} = c_1 \vec{b}_1 + c_2 \vec{b}_2 + \dots + c_p \vec{b}_p$$

"Uniqueness"

Suppose we also have

$$\vec{x} = d_1 \vec{b}_1 + d_2 \vec{b}_2 + \dots + d_p \vec{b}_p$$

$$\Rightarrow \vec{0} = (c_1 - d_1) \vec{b}_1 + (c_2 - d_2) \vec{b}_2 + \dots + (c_p - d_p) \vec{b}_p$$

$\{\vec{b}_1, \dots, \vec{b}_p\}$ is linearly independent

$$\Rightarrow c_1 = d_1, c_2 = d_2, \dots, c_p = d_p$$

Definition (Coordinate of a vector relative to a basis) (4)

Let $B = \{\vec{b}_1, \dots, \vec{b}_p\}$ be a basis for a subspace H .

Each \vec{x} in H is uniquely represented by

$$\vec{x} = c_1 \vec{b}_1 + \dots + c_p \vec{b}_p$$

The vector

$$[\vec{x}]_B \equiv \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_p \end{bmatrix}$$

is called the coordinate ^{vector} of vector \vec{x} relative to basis B .

*) $[\vec{x}]_B$ is in \mathbb{R}^p

*) $\vec{x} \xleftrightarrow[\text{Unique representation}]{\text{Theorem}} [\vec{x}]_B$

*) $H \xleftrightarrow[\text{one to one correspondence}]{\text{}} \mathbb{R}^p$

Ex. let $\vec{v}_1 = \begin{bmatrix} 1 \\ -4 \\ -3 \end{bmatrix}$, $\vec{v}_2 = \begin{bmatrix} -3 \\ 6 \\ 7 \end{bmatrix}$ and $\vec{x} = \begin{bmatrix} 3 \\ 3 \\ -4 \end{bmatrix}$

let $H = \text{Span}\{\vec{v}_1, \vec{v}_2\}$

$B = \{\vec{v}_1, \vec{v}_2\}$ is a basis for H .

Q: Is \vec{x} in H ?

If so, find $[\vec{x}]_B$

We consider the vector equation.

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 = \vec{x}$$

$$c_1 \begin{bmatrix} 1 \\ -4 \\ -3 \end{bmatrix} + c_2 \begin{bmatrix} -3 \\ 6 \\ 7 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \\ -4 \end{bmatrix}$$

The augmented matrix

$$\left[\begin{array}{cc|c} 1 & -3 & 3 \\ -4 & 6 & 3 \\ -3 & 7 & -4 \end{array} \right] \sim \dots \sim \left[\begin{array}{cc|c} 1 & 0 & -9/2 \\ 0 & 1 & -5/2 \\ 0 & 0 & 0 \end{array} \right]$$

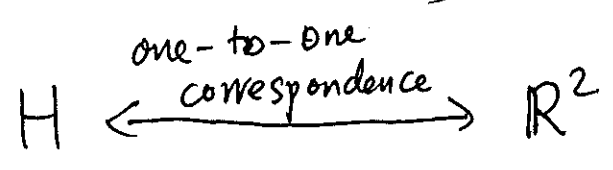
The rightmost column is not a pivot column.

\Rightarrow It is consistent.

A solution. $\begin{cases} c_1 = -9/2 \\ c_2 = -5/2 \end{cases}$

$$[\vec{x}]_B = \begin{bmatrix} -9/2 \\ -5/2 \end{bmatrix}$$

$[\vec{x}]_B$ is in \mathbb{R}^2
 $\vec{v}_1, \vec{v}_2, \vec{x}$ are in \mathbb{R}^3



Definition (dimension of a subspace)

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Special case $\dim \{\vec{0}\} = 0$

For $H \neq \{\vec{0}\}$

$\dim H \equiv$ the number of vectors in
a basis for H

Statement: let H be a subspace of \mathbb{R}^n
Two bases for H must have the same
number of vectors.

proof: Suppose H has two bases

$$\{\vec{a}_1, \dots, \vec{a}_p\}$$

$$\{\vec{b}_1, \dots, \vec{b}_q\}$$

Suppose $q > p$

let $A = [\vec{a}_1 \dots \vec{a}_p]$ $n \times p$

$B = [\vec{b}_1 \dots \vec{b}_q]$ $n \times q$

$\vec{b}_j = A \vec{c}_j$

\vec{c}_j is in \mathbb{R}^p

let $C = [\vec{c}_1 \dots \vec{c}_q] = p \times q$

$\Rightarrow B = AC$
 $n \times q \quad n \times p \quad p \times q$

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$$C: p \times q \quad \underline{q > p}$$

\Rightarrow Columns of C are linearly dependent.

$C\vec{x} = \vec{0}$ has a non-trivial solution.

$$C\vec{d} = \vec{0}, \quad \vec{d} \neq \vec{0}$$

$$B\vec{d} = (AC)\vec{d} = A(C\vec{d}) = A\vec{0} = \vec{0}$$

$\Rightarrow B\vec{x} = \vec{0}$ has a non-trivial solution.

\Rightarrow Columns of B are linearly dependent

\Rightarrow Contradiction

$\Rightarrow q > p$ is impossible.

end of proof

Ex: $\vec{u} \neq \vec{0}$

$$\dim \text{Span} \{ \vec{u} \} = 1$$

$$\dim \text{Span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} \right\} = 2.$$

Definition. (rank of a matrix)

$$\text{rank } A \equiv \dim \text{Col } A$$

$$\begin{aligned} \dim \text{Col } A &= \# \text{ of pivot columns} \\ &= \# \text{ of pivot positions} \end{aligned}$$

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Statement

$$\begin{aligned} \text{rank } A &= \# \text{ of pivot columns in } A \\ &= \# \text{ of pivot positions in } A \end{aligned}$$

Ex $A = \begin{bmatrix} 1 & 3 & -1 & -3 \\ 2 & 6 & 1 & 9 \\ 1 & 3 & -2 & -8 \end{bmatrix}$

Find rank A

row reduction $\rightarrow \begin{bmatrix} 1 & 3 & -1 & -3 \\ 0 & 0 & 3 & 15 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

$$\Rightarrow \text{rank } A = 2$$

Statement

$$A: m \times n$$

$$\dim \text{Nul } A = \# \text{ of free variables}$$

$$= (\# \text{ of variables}) - (\# \text{ of basic variables})$$

$$= n - (\# \text{ of pivot positions in } A)$$

of columns in A

Theorem 14 (The rank theorem)

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$A = m \times n$. We have

*). $\text{rank } A^T = \text{rank } A$ (we will prove this later)

*). $\text{rank } A + \dim \text{Nul } A = n$ ✓

Revisit Theorem 8 (invertible matrix theorem)

$A = n \times n$

All statements below are equivalent.

a) A is invertible

...

c) A has n pivot positions

d) $A\vec{x} = \vec{0}$ has only the trivial solution

e) The columns of A are linearly independent.

⋮

h) The columns of A span \mathbb{R}^n

⋮

l) A^T is invertible.

m). The columns of A form a basis for \mathbb{R}^n

m) \iff e) + h)

n). $\text{Col } A = \mathbb{R}^n$

n) \iff h)

o) $\dim \text{Col } A = n$

o) \iff c)

p) rank $A = n$

p) \iff o)

q) $\text{Nul } A = \{ \vec{0} \}$

q) \iff d)

r) $\dim \text{Nul } A = 0$

r) \iff q)

Theorem 15 (The basis theorem)

Suppose H is a subspace in \mathbb{R}^n and $\dim H = p > 0$

1) If $\{ \vec{b}_1, \dots, \vec{b}_p \}$ in H is linearly independent,

then $\{ \vec{b}_1, \dots, \vec{b}_p \}$ is a basis for H .

2) If $\text{span} \{ \vec{v}_1, \dots, \vec{v}_p \} = H$, then $\{ \vec{v}_1, \dots, \vec{v}_p \}$

is a basis for H .

proof : 1) We need to show $\text{span} \{ \vec{b}_1, \dots, \vec{b}_p \} = H$

Let $\{ \vec{a}_1, \dots, \vec{a}_p \}$ be a basis for H .

Let $A = [\vec{a}_1 \dots \vec{a}_p]$ $n \times p$

$B = [\vec{b}_1 \dots \vec{b}_p]$ $n \times p$

\implies There exists matrix $C = (p \times p)$ such that

$$\boxed{ \begin{matrix} B = AC \\ n \times p \quad n \times p \quad p \times p \end{matrix} }$$

$\{\vec{b}_1, \dots, \vec{b}_p\}$ is linearly independent

$\Rightarrow B\vec{x} = \vec{0}$ has only the trivial solution.

$$B\vec{x} = (AC)\vec{x} = A(C\vec{x})$$

$\Rightarrow C\vec{x} = \vec{0}$ has only the trivial solution.

$\Rightarrow C$ is invertible.

$$\Rightarrow BC^{-1} = A$$

$$\Rightarrow \boxed{A = BC^{-1}}$$

Columns of A are linear combinations of columns of B .

$$\Rightarrow \underline{\text{span}\{\vec{b}_1, \dots, \vec{b}_p\} = H.}$$

2) We need to show $\{\vec{v}_1, \dots, \vec{v}_p\}$ is linearly independent.

Theorem 5 of sec 4.3 (The spanning set theorem)

Consider $H = \text{span}\{\vec{v}_1, \dots, \vec{v}_p\} \neq \{\vec{0}\}$

a). If \vec{v}_p is a linear combination of others, then

$$\text{span}\{\vec{v}_1, \dots, \vec{v}_{p-1}\} = H$$

b). $\{\vec{v}_1, \dots, \vec{v}_p\}$ or a smaller set of $\{\vec{v}_1, \dots, \vec{v}_p\}$ is a basis for H .

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Suppose $\{\vec{v}_1, \dots, \vec{v}_p\}$ is linearly dependent.

\Rightarrow A smaller set of $\{\vec{v}_1, \dots, \vec{v}_p\}$ is a basis.

$\Rightarrow \dim H < p$

\Rightarrow Contradicting with $\dim H = p$

$\Rightarrow \{\vec{v}_1, \dots, \vec{v}_p\}$ must be linearly independent!