

Least-Norm Solutions of Underdetermined Equations

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Winter 2016



Least-Norm Solutions of Underdetermined Equations

- Least-norm solution of underdetermined equations
- Minimum norm solutions via QR factorization
- Derivation via Lagrange multipliers
- Relation to regularized least-squares
- General norm minimization for equality constraints



Underdetermined Linear Eq'ns (1.2)

$y = Ax$ each equation is a spec.

$A \in \mathbb{R}^{m \times n}$ is PAT ($m < n$)

- There are fewer equations than unknowns

- x is underspecified, many choices of x give the same y .

Assume A is full rank (m)

For each $y \in \mathbb{R}^m$ there is an exact solution.



Underdetermined Linear Eq'ns (2.2)

$$\{x \mid Ax = y\} = \{x_p + z \mid z \in N(A)\}$$

x_p = "particular" solution $Ax_p = y$.

In design — great news!

z characterizes available choices within solution

Solution has $\dim N(A) = n - m$ "degrees of freedom"

Choose z to satisfy some other specification
or do optimize among many solutions.



Least-norm Solution (1.3)

$$x_{ln} = A^T (AA^T)^{-1} y \quad \text{least norm soln}$$

right inverse of A

(AA^T) invertible because A full rank

$$LS: y \approx Ax \quad (\text{approx})$$

$$LN: y = Ax \quad (\text{exactly})$$

x_{ln} soln to $y = Ax$ with $\|x\|^2$ min.

$$x_{ln} = (A^T A)^{-1} A^T y$$

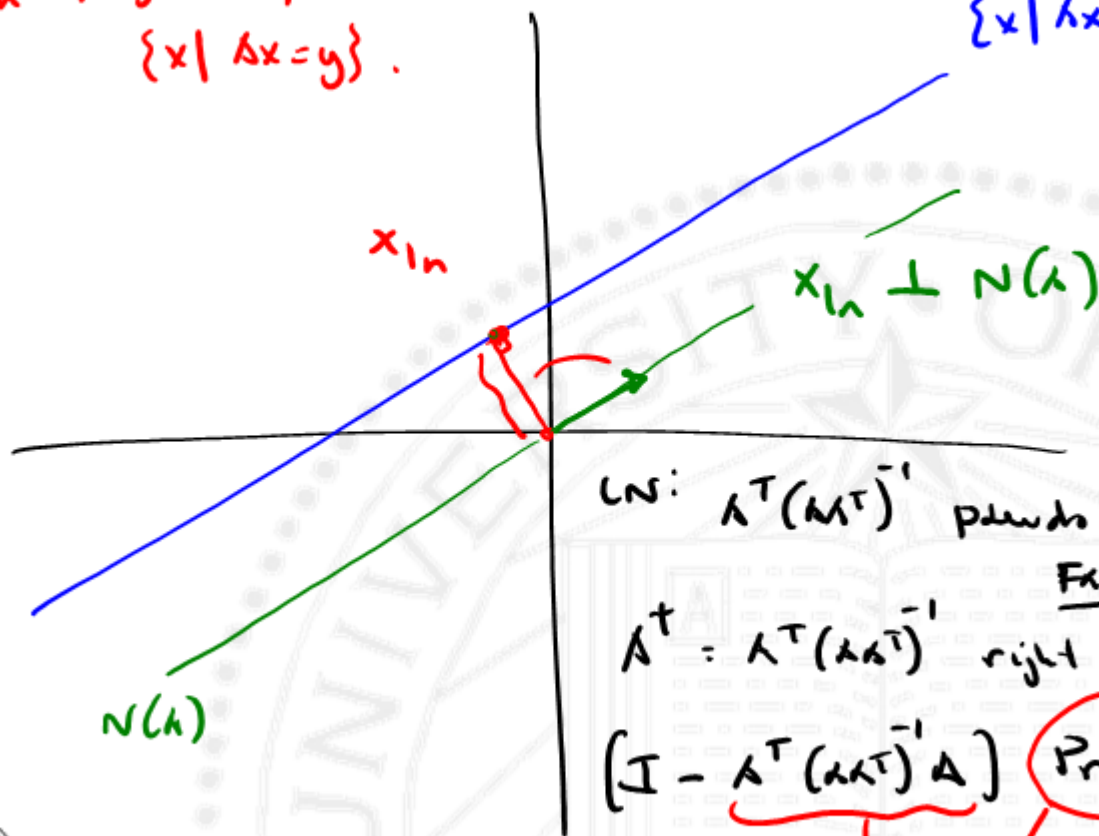
$$\begin{pmatrix} \boxed{1} & \boxed{0} \\ \boxed{0} & \boxed{1} \end{pmatrix}^{-1}$$

$$\begin{pmatrix} \boxed{1} & \boxed{0} \\ \boxed{0} & \boxed{0} \end{pmatrix}$$



x_{ln} projection of $\{0\}$ onto solution set $\{x \mid Ax=y\}$.

$\{x \mid Ax=y\}$



LS: $A^T(AA^T)^{-1}$ pseudo inverse of A

$A^+ = A^T(AA^T)^{-1}$ right inverse of A

$(I - A^T(AA^T)^{-1}A)$ $Pr(N(A))$



Least-norm Solution (2.3)

$$\text{LN} \begin{cases} \min_x \|x\|^2 \\ \text{sub}_j \quad Ax = y \end{cases}$$

$$\text{LS: } \min_x \|Ax - y\|^2$$

$$Ax = y \quad \underline{A(x - x_{1n}) = 0}$$

$$(x - x_{1n})^T x_{1n} = \left[(x - x_{1n})^T A^T \right] (AA^T)^{-1} y$$

$$\underbrace{(A(x - x_{1n}))^T}_{=0} (AA^T)^{-1} y$$

$$(x - x_{1n}) \perp x_{1n}$$



Least-norm Solution (3.3)

$$\begin{aligned}\|x\|^2 &= \|x_{1n} + x - x_{1n}\|^2 = \|x_{1n}\|^2 + 2x_{1n}^T(x - x_{1n}) + \|x - x_{1n}\|^2 \\ &\geq \|x_{1n}\|^2\end{aligned}$$

$$\|x_{1n}\|^2 + \|x - x_{1n}\|^2 \geq \|x_{1n}\|^2$$


x_{1n} has the smallest norm of any solution.
 $y = bx$.



Least-norm Solution via QR (1.3)

Find QR of $A^T \rightarrow A^T = QR$ (G.S on A^T)

$$A^T = QR \quad Q \in \mathbb{R}^{n \times m} \quad Q^T Q = I_m$$

$R \in \mathbb{R}^{m \times m}$  upper triangular, invertible

$$\begin{aligned} x_{ln} &= A^T (Ax^T)^{-1} y = QR (R^T Q^T Q R)^{-1} y = QR (R^T R)^{-1} y \\ &= Q \underbrace{R^{-1}}_{\bar{R}^T} (R^T)^{-1} y = Q \bar{R}^T y \end{aligned}$$

$$\bar{R}^T \triangleq (R^{-1})^T$$

$$\|x_{ln}\| = \|\bar{R}^T y\|$$



Derivation via Lagrange Multipliers


$$\begin{aligned} \min x^T x \\ \text{subj } Ax=y \end{aligned}$$

$$L(x, \lambda) = x^T x + \lambda^T (Ax - y)$$

optimality conditions:

$$\frac{\partial L}{\partial x} = 0 \quad \frac{\partial L}{\partial \lambda} = 0$$

$$\frac{\partial L}{\partial x} = 2x + A^T \lambda = 0 \quad \therefore x = \underbrace{-\frac{A^T \lambda}{2}}$$

$$\frac{\partial L}{\partial \lambda} = Ax - y = 0$$




Derivation via Lagrange Multipliers

$$Ax - y = 0 \quad x = -\frac{A^T \lambda}{2}$$

$$-\frac{AA^T \lambda}{2} - y = 0 \quad \rightarrow \quad \lambda = -2(AA^T)^{-1} y$$

$$x = -\frac{A^T \lambda}{2} = +\frac{A^T (-2(AA^T)^{-1} y)}{2}$$

$$x_{\text{ls}} = A^T (AA^T)^{-1} y$$



if A is FXT full rank ... plenty of solutions

- why do we choose $\min \|x\|^2$

EASY TO CALCULATE

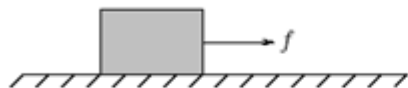
$\min \sum |x_i|$ - 1 norm ~ fuel burn

$\min \max |x_i|$ - ∞ norm ~ thruster size.

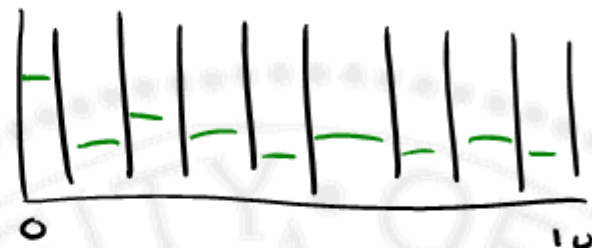
H_2 control (LQR/LQG/LKE)



Lagrange Multiplier: Example (1.3)



y_1 position @ $t=10$
 y_2 velocity @ $t=10$



$$y = Ax \quad \begin{matrix} A \in \mathbb{R}^{2 \times 10} \\ x \in \mathbb{R}^{10} \end{matrix}$$

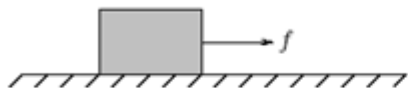
$$A \Rightarrow FxT$$

find best lower trajectory
 mass to $y=1$ $y=0$

$$y_{des} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



Lagrange Multiplier: Example (2.3)

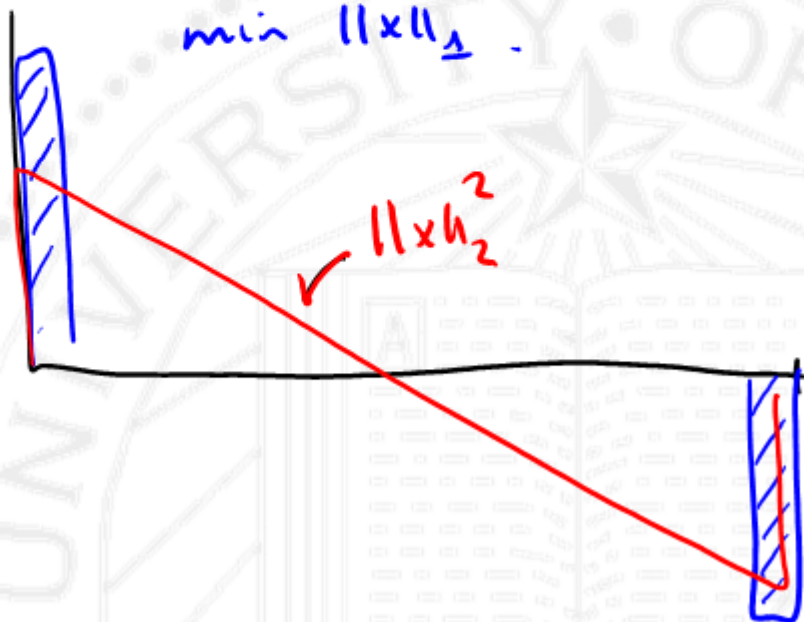


$$x|_n = A^T(AA^T)^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

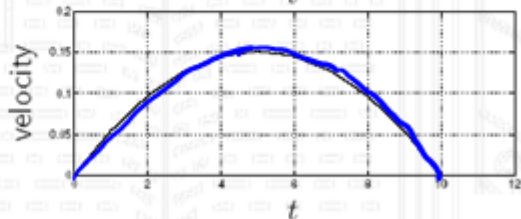
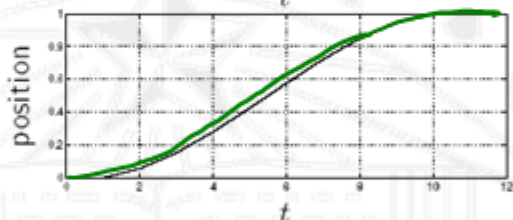
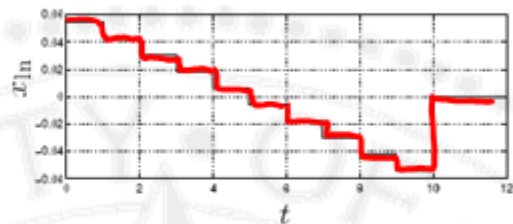
min $\|x\|_1$

$\|x\|_2^2$

10



Lagrange Multiplier: Example (3.3)



Relation to Regularized L-S (1.2)

$$A \in \mathbb{R}^{m \times n} \quad \underline{A} \text{ full rank}$$

$$\text{define } J_1 = \|Ax - y\|^2 \quad J_2 = \|x\|^2 \quad \sigma_1$$

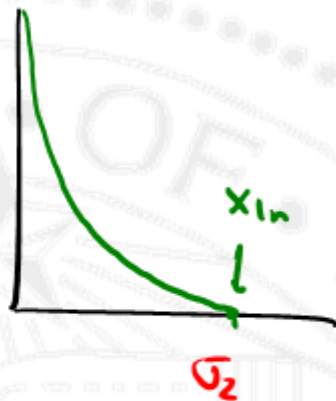
WOLST NORM

$$\min J_2 \text{ w/ } J_1 = \phi.$$

$$\min (J_1 + \mu J_2) = \|Ax - y\|^2 + \mu \|x\|^2$$

$$\underline{x_\mu} = (A^T A + \mu I)^{-1} A^T y$$

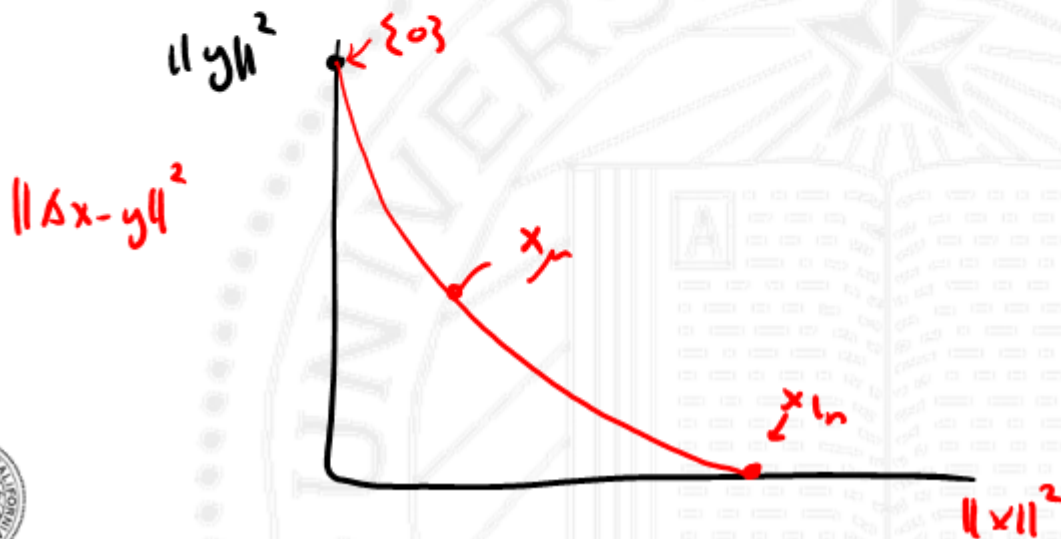
$$x_\mu \rightarrow x_{in} \text{ as } \mu = \phi.$$



Relation to Regularized L-S (2.2)

as $\mu \rightarrow 0$

$$(\lambda^T \lambda + \mu I)^{-1} \lambda^T \rightarrow \lambda^T (\lambda \lambda^T)^{-1} \quad \text{for } \lambda \text{ full rank}$$



General Norm Minimization with Equality Constraints (1.3)

$$\min_x \|Ax - b\|$$

$$\text{subj. } Cx = d$$



$$\min \frac{1}{2} \|Ax - b\|^2$$

$$\text{subj. } Cx = d$$



General Norm Minimization with Equality Constraints (2.3)

$$L(x, \lambda) = \frac{1}{2} \|Ax - b\|^2 + \lambda^T (Cx - d)$$

$$= \frac{1}{2} x^T A^T A x - b^T A x + \frac{1}{2} b^T b + \lambda^T C x - \lambda^T d$$

$$\frac{dL}{dx} = 0 : A^T A x - A^T b + C^T \lambda = 0 \quad \text{— solve for } \lambda$$

$$\frac{dL}{d\lambda} = 0 : Cx - d$$

↓
solve for x



General Norm Minimization with Equality Constraints (3.3)

$$\begin{bmatrix} A^T A & \vdots & C^T \\ \cdots & \cdots & \cdots \\ C & \vdots & 0 \end{bmatrix} \begin{bmatrix} x \\ \vdots \\ \lambda \end{bmatrix} = \begin{bmatrix} A^T b \\ \vdots \\ d \end{bmatrix} \quad \underline{\text{KKT}}$$

$$\begin{bmatrix} x \\ \vdots \\ \lambda \end{bmatrix} = \begin{bmatrix} A^T A & \vdots & C^T \\ \cdots & \cdots & \cdots \\ C & \vdots & 0 \end{bmatrix}^{-1} \begin{bmatrix} A^T b \\ \vdots \\ d \end{bmatrix}$$



if $(A^T A)$ is invertible

$$x = (A^T A)^{-1} (A^T b - c^T x) \quad Cx = d$$

$$C (A^T A)^{-1} (A^T b - c^T x) = d$$

$$x = [C (A^T A)^{-1} c^T]^{-1} (C (A^T A)^{-1} A^T b - d)$$

solve for $x \rightarrow$ using.



$$\min_x \|Ax - b\|$$

suby. $Cx + d$

LS) $A = I \quad b = y$

$C = A \quad d = y$

$$\begin{bmatrix} I & \vdots & A^T \\ \lambda & \vdots & 0 \end{bmatrix} \begin{bmatrix} x \\ \lambda \end{bmatrix} = \begin{bmatrix} 0 \\ y \end{bmatrix} \rightarrow x_{LS} = A^T (AA^T)^{-1} y$$

LS) $C = \{ \}$

$d = \{ \}$

$$\left[\begin{array}{c|c} A^T A & \begin{bmatrix} x \\ \lambda \end{bmatrix} \\ \hline & \end{array} \right] = \begin{bmatrix} A^T y \\ - \end{bmatrix} \rightarrow x_{LS} = \frac{(A^T A)^{-1} A^T y}{-}$$



Questions?



MIDTERM RULES

24 hour take-home 5 problems.

Open book, open notes, open any lecture
(for any year)

Open everything except,

NO UNLID WERP.

NO PUBLISHED SOLUTIONS

