

$$\dot{x} = Ax \quad \text{no inputs}$$

# Solution via Laplace Transform and Matrix Exponential

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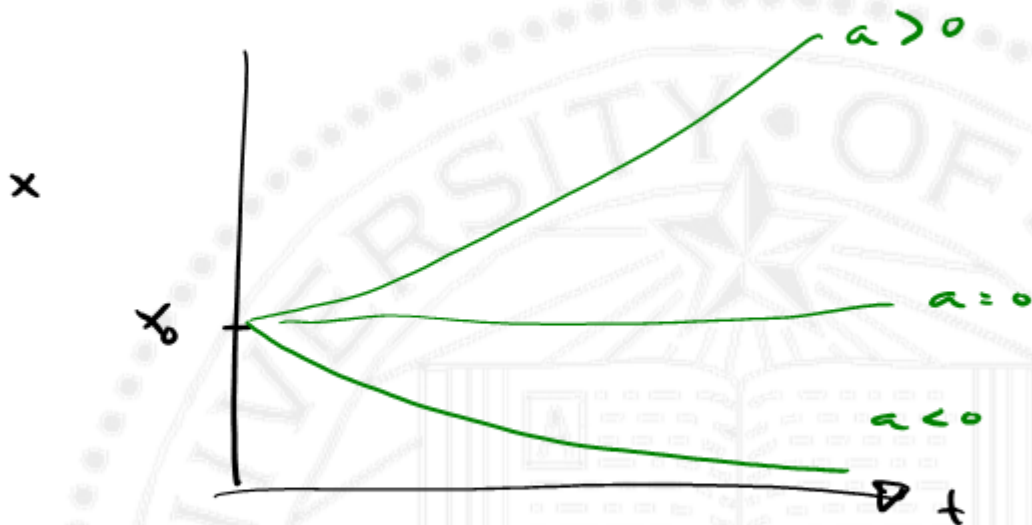
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$$\dot{x} = ax \quad \leftarrow \text{scalar} \quad x(t) = x_0 e^{at}$$



$$\underline{\dot{x}} = A \underline{x} \rightarrow \underline{x}(t) = e^{At} x_0$$



# Solution via Laplace Transform and Matrix Exponential

- Laplace Transform
- Solving  $x' = Ax$  via Laplace Transform
- State transition matrix
- Matrix Exponential
- Qualitative behavior and Stability



## Laplace Transform of a Matrix (1.3)

$$\mathcal{L}\{x(t)\} \triangleq \int_0^{\infty} x(t) e^{-st} dt \triangleq X(s) \quad \begin{array}{l} x: \mathbb{R}_+ \rightarrow \mathbb{R} \\ X: \mathbb{C} \rightarrow \mathbb{C} \end{array}$$

$$\mathcal{L}\{\dot{x}(t)\} = sX(s) - x_0$$

$$\mathcal{L}\{\dot{x} = ax\} = sX(s) - x_0 = aX(s) \rightarrow (s-a)X(s) = x_0$$

$$X(s) = \frac{x_0}{s-a}$$

$$x(t) = \mathcal{L}^{-1}\left\{\frac{x_0}{s-a}\right\} = \underline{x_0 e^{at}}$$



## Laplace Transform of a Matrix (2.3)

$z: \mathbb{R}_+ \rightarrow \mathbb{R}^{p \times q}$  ← trajectory, matrix valued signal

$Z = \mathcal{L}(z)$  where  $Z: D \subseteq \mathbb{C} \rightarrow \mathbb{C}^{p \times q}$

$$Z(s) = \int_0^{\infty} e^{-st} z(t) dt$$

↑ complex

$$Z(s) = \int_0^{\infty} z(t) e^{-st} dt$$

$D \hat{=}$  domain of convergence

$D$  includes at least  $\{s \mid \operatorname{Re}(s) > a\}$

where  $a: |z_{ij}(t)| \leq \alpha e^{at} \quad t > 0 \quad i=1 \dots p \quad j=1 \dots q$



## Laplace Transform of a Matrix (3.3)

$$\mathcal{L}\{g(t)\} = Z(s)$$

$\uparrow$   $\uparrow$   $\mathbb{R}_+ \rightarrow \mathbb{R}^{p \times q}$   
 $\mathbb{C}^{p \times q}$



lower case ( $t$ )  $\leftarrow$  time      upper case ( $s$ )  $\leftarrow$  freq.

## Derivative Property (1.2)

$$\mathcal{L}\{\dot{z}\} = sZ(s) - z(0) \quad \int u dv = uv - \int v du$$

$$\begin{aligned} \mathcal{L}\{\dot{z}\} &= \int_0^{\infty} \underbrace{\dot{z}(t)}_{dv} \underbrace{e^{-st}}_u dt = e^{-st} z(t) \Big|_{t=0}^{\infty} + \int_0^{\infty} z(t) e^{-st} (-s) dt \\ &= 0 - 1 z(0) + s \underbrace{\int_0^{\infty} z(t) e^{-st} dt}_{Z(s)} \end{aligned}$$

$$\mathcal{L}\{\dot{z}\} = sZ(s) - z(0)$$

$$\mathcal{L}\{\ddot{z}\} = s^2 Z(s) - s z(0) - \dot{z}(0)$$





## Laplace transform solution of $\dot{x}=Ax$ (1.3)

$$\mathcal{L}\{\dot{x} = Ax\} = sX(s) - x(0) = AX(s)$$

$$sX(s) - Ax(s) = x(0)$$

$$[sI - A]X(s) = x(0)$$

$$X(s) = [sI - A]^{-1} x(0)$$



# Laplace transform solution of

$$\dot{x} = Ax(1.3)$$

$\dot{x} = Ax$        $\mathcal{L}\{Ax\} = A\mathcal{L}\{x\}$        $A \in \mathbb{R}^{n \times n}$

$sX(s) - x(0) = \overbrace{AX(s)}^{\text{complex } n \times n \text{ matrix}}$

$$(sI - A)X(s) = x(0)$$

$$X(s) = \underbrace{[sI - A]^{-1}}_{\text{Resolvent of } A} x_0$$

$\sim$  1850

$s \in \mathbb{C}$  except for eigenvalues of  $A$ .



## Laplace transform solution of

$$\dot{x} = Ax \quad (2.3)$$

$$[sI - A]^{-1} \leftarrow \text{resolvent}$$

defined  $s \in \mathbb{C}$  except for eigenvalues of  $A$ .

$$\det(sI - A) = 0 \leftarrow \text{eigenvalues of } A$$

$$X(s) = [sI - A]^{-1} x_0$$

$$x(t) = \mathcal{L}^{-1} \{ [sI - A]^{-1} x_0 \}$$



# Laplace transform solution of

$$\dot{x} = Ax \quad (3.3)$$

$$\mathcal{L}^{-1} \{X(s)\} = [\mathcal{L}^{-1}\{sI - A\}^{-1} x_0]$$

$$x(t) = \underbrace{\mathcal{L}^{-1} \{[sI - A]^{-1}\}}_{\Phi(t) \sim \mathbb{R}^{n \times n}} x_0$$



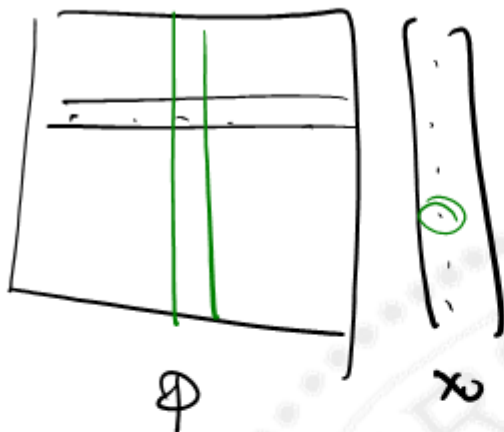
$$x(t) = \Phi(t) x_0$$

$$\Phi(t) \triangleq \mathcal{L}^{-1} \{[sI - A]^{-1}\}$$

↑ state transition matrix



$x(t)$  :



$$\phi(t) \rightarrow 0 \quad \text{as } t \rightarrow \infty$$

STABILITY



# Autonomous LDS example (1.3)

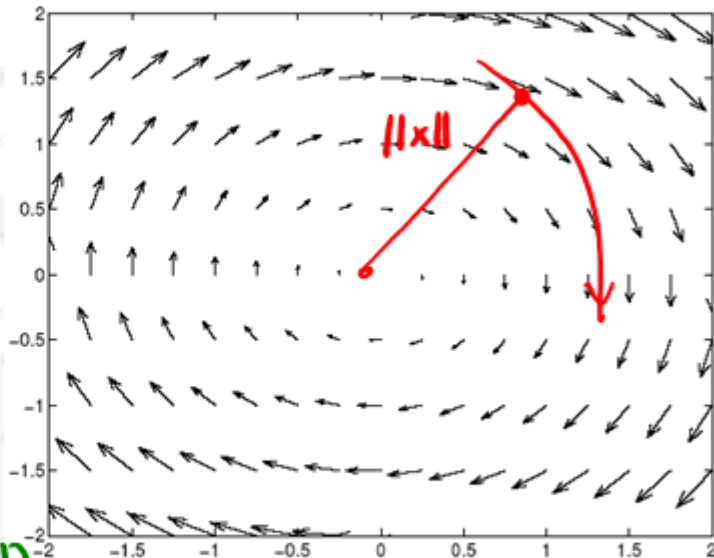
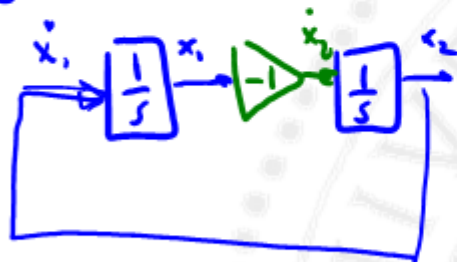
## Harmonic Oscillator

$$\lambda = \pm j$$

$$\dot{x} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} x$$

$$\dot{x}_1 = x_2$$

$$\dot{x}_2 = -x_1$$



$$sI - A = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} s & -1 \\ 1 & s \end{bmatrix}$$

$$(sI - A)^{-1} = \frac{1}{s^2 + 1} \begin{bmatrix} s & 1 \\ -1 & s \end{bmatrix} \rightarrow \mathcal{L}^{-1}\{\} \rightarrow \Phi = \begin{bmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{bmatrix}$$



# Autonomous LDS example (2.3)

## Harmonic Oscillator

$$\dot{x} = ax$$



$$\dot{x} = Ax$$

$$x(t) = \begin{pmatrix} \cos t & \sin t \\ \dots & \dots \\ -\sin t & \cos t \end{pmatrix} x_0$$



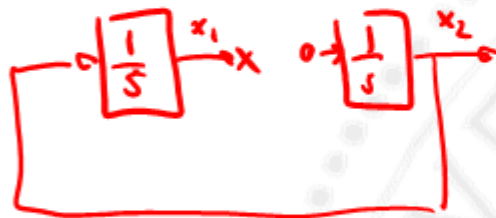
# Autonomous LDS example (1.3)

## Double Integrator

$$\dot{x} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} x$$

$$\underline{\dot{x}_2 = 0}$$

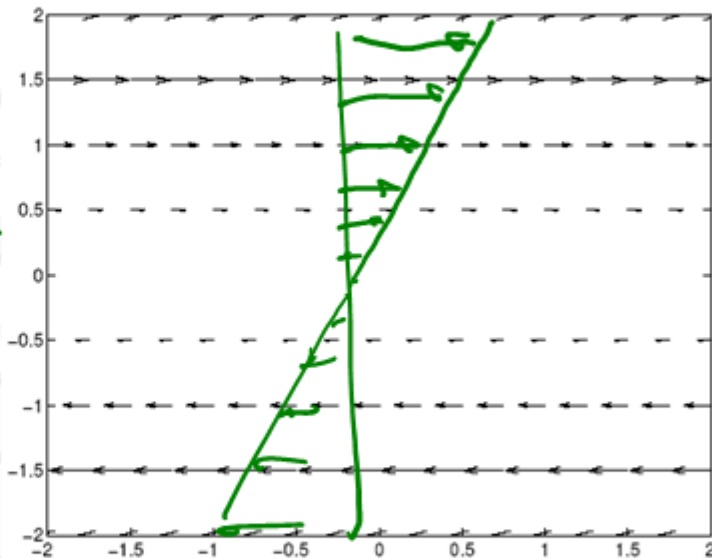
$$\dot{x}_1 = x_2$$



$x_2$

$$sI - A = \begin{bmatrix} s & 0 \\ 0 & s \end{bmatrix} - \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} s & -1 \\ 0 & s \end{bmatrix} \rightarrow (sI - A)^{-1} = \frac{1}{s^2} \begin{bmatrix} s & 1 \\ 0 & s \end{bmatrix} \rightarrow \phi = \int_0^t f(\tau) d\tau = \begin{bmatrix} t & t^2 \\ 0 & t \end{bmatrix}$$





# Autonomous LDS example (2.3)

## Double Integrator

$$x(t) = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix} x_0$$

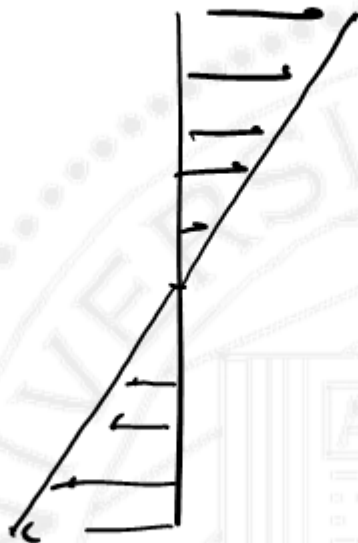
$$\text{eig}(sI - A) = (0, 0)$$

$$\det(sI - A) = 0 \quad \text{when } s = 0. \quad \frac{1}{s} \cdot \frac{1}{s}$$



# Autonomous LDS example (3.3)

## Double Integrator



## Characteristic Polynomial (1.2)

$\chi(s) \triangleq \det(sI - A)$  characteristic polynomial  
of  $A$  [ $\Delta(s)$ ]

$\chi(s)$  is a polynomial of degree  $n$   
(monic polynomial)

$$s^n + (\sum a_{ii}) s^{n-1} + \dots + (\prod a_{ii})$$

$n$  eigenvalues (if we count  
multiplicity of roots)

$$\det \begin{bmatrix} (s - a_{11}) & a_{12} & \dots \\ a_{21} & (s - a_{22}) & \dots \\ \vdots & \vdots & \ddots \end{bmatrix}$$



## Characteristic Polynomial (2.2)

roots of  $X(s)$  are the eigenvalues of  $A$ .

$X(s)$  has only REAL coefficients, eigenvalues are either real, or they come in complex conjugate pairs.



$i, j$  entry of the resolvent  $(sI - A)^{-1}$

Cramer's Rule for matrices  $\frac{\text{adj}(sI - A)}{\det(sI - A)}$

$$(-1)^{i+j} \frac{\det \Delta_{ij}}{\det(sI - A)} \leftarrow \text{degree} < n \quad (n-1)$$
$$\det(sI - A) \leftarrow \chi(s) \leftarrow \text{degree } n$$

$\Delta_{ij} = sI - A$  with  $j^{\text{th}}$  row &  $i^{\text{th}}$  column deleted

rational functions in  $s$ .



## The Matrix Exponential (1.3)

$$\frac{1}{1-c} = 1 + c + c^2 + c^3 + \dots \text{ works if } |c| < 1.$$

$$[I - c]^{-1} = I + c + c^2 + c^3 + \dots \text{ if series converges.}$$

$$[sI - A]^{-1} = \frac{1}{s} [I - \frac{A}{s}]^{-1} = \frac{1}{s} \left[ I + \frac{A}{s} + \frac{A^2}{s^2} + \frac{A^3}{s^3} + \dots \right]$$

$$= \frac{I}{s} + \frac{A}{s^2} + \frac{A^2}{s^3} + \frac{A^3}{s^4} + \dots \text{ converge as long as } |s| \text{ is big enough}$$

$$\phi = \mathcal{L}^{-1} \{ (sI - A)^{-1} \} = \mathcal{L}^{-1} \left\{ \frac{I}{s} + \frac{A}{s^2} + \frac{A^2}{s^3} + \dots \right\}$$



$$1 + at + \frac{a^2 t^2}{2!} + \frac{a^3 t^3}{3!} + \dots = e^{at}$$

## The Matrix Exponential (2.3)

$$\phi = \mathcal{L}^{-1}\{[sI - A]^{-1}\} = \mathcal{L}^{-1}\left\{\frac{I}{s} + \frac{A}{s^2} + \frac{A^2}{s^3} + \dots\right\}$$

$$= \mathcal{L}^{-1}\left\{\frac{I}{s}\right\} + \mathcal{L}^{-1}\left\{\frac{A}{s^2}\right\} + \mathcal{L}^{-1}\left\{\frac{A^2}{s^3}\right\} + \dots$$

$$= I \mathcal{L}^{-1}\left\{\frac{1}{s}\right\} + A \mathcal{L}^{-1}\left\{\frac{1}{s^2}\right\} + A^2 \mathcal{L}^{-1}\left\{\frac{1}{s^3}\right\} + \dots$$

$$= I + At + \frac{A^2 t^2}{2!} + \frac{A^3 t^3}{3!} + \dots \quad M \in \mathbb{R}^{n \times n}$$

MATRIX EXPONENTIAL :

$$e^M = I + M + \frac{M^2}{2!} + \frac{M^3}{3!} + \dots$$



# The Matrix Exponential (3.3)

$$\Phi(t) = \bar{x}^{-1} \{ [e^{(sI-A)t}] \} = e^{At}$$

$$x(t) = e^{At} x_0$$

← non-trivial overloading

$$\exp(A) = \begin{bmatrix} e^{a_{11}} & e^{a_{12}} & \dots \\ \vdots & & \end{bmatrix} \quad \text{element by element}$$

expm(A) ← matrix exponential





# Matrix Exponential Solution of A-LDS (1.5)

$$e^a e^b = e^{(a+b)} \quad \leftarrow \text{scalar world} \quad \begin{array}{l} ab = ba \\ ab = 0 \end{array}$$

$$e^A e^B \neq e^{(A+B)} \quad \leftarrow \text{matrix}$$

$AB = \phi.$   
 $AB \neq BA.$

$$A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$e^A = \begin{bmatrix} 0.59 & 0.84 \\ -0.84 & 0.59 \end{bmatrix} \quad e^B = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$$



## Matrix Exponential Solution of A-LDS (2.5)

$$e^A e^B = \begin{bmatrix} 0.59 & 1.38 \\ -0.89 & -0.30 \end{bmatrix}$$

$$e^{(A+B)} = \begin{bmatrix} 0.16 & 1.90 \\ -0.70 & 0.16 \end{bmatrix}$$

$$e^A e^B = e^{(A+B)} \text{ if } AB = BA$$



# Matrix Exponential Solution of A-LDS (3.5)

$$t, s \in \mathbb{R}$$

$$e^{At} \cdot e^{As} = e^{A(s+t)}$$

$$t=1 \quad s=-1$$

$$e^{A(-1)} \cdot e^{A(1)} = e^0 = I.$$

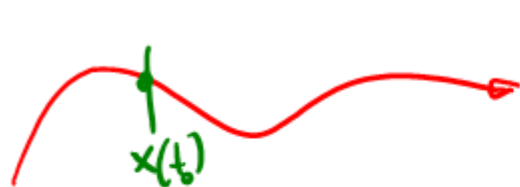
$$(e^{At})^{-1} = e^{-At}$$

$$AtAs = stA^2$$
$$AsAt = stA^2$$

$$e^{At} \text{ non-singular.}$$



# Matrix Exponential Solution of A-LDS (4.5)

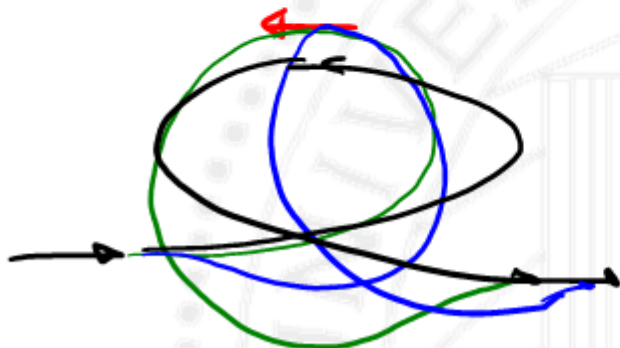


$$\dot{x} = Ax$$

$$x(t_0) \text{ measured}$$

$$x_0 = e^{-A(t-t_0)} x_{t_0}$$

$t = t_0$



# Matrix Exponential Solution of A-LDS (5.5)

$$e^{At} \quad A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad (sI - A)^{-1} = e^{At} = \mathcal{L}^{-1} \left\{ (sI - A)^{-1} \right\}$$

$t=2$

$$= \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$$

$$e^{At} = \underbrace{I + At} + \frac{A^2 t^2}{2!} + \frac{A^3 t^3}{3!} + \dots$$

$$A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad A^2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & t \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

↑

$$\begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix}$$



## Time Transfer Property (1.2)

$$\dot{x} = Bx \quad 0 \leq t < 1$$

$$x(0) = x_0$$

$$\dot{x} = Ax \quad 1 \leq t < \infty$$

$$x(1) = e^{A(t-1)} x(1)$$

$$x(1) = e^{B(1)} x_0$$

$$x(t) = \begin{cases} e^{Bt} x_0 & t < 1 \\ e^{A(t-1)} e^{B} x_0 & t \geq 1 \end{cases}$$

$$\underline{\underline{x(t+\tau) = e^{At} x(\tau)}}$$



## Time Transfer Property (2.2)

$$\dot{x} = Ax \longrightarrow x(t) = \phi(t) x_0 = e^{At} x_0$$

$e^{At}$  propagates initial state into state at time  $t$ .

$$x(t+\tau) = e^{A\tau} x(t) \quad z(t) = x(t+\tau)$$

Forward or Backward in time.



$$\dot{x} = Ax$$

$$\underline{x(t+\tau) = x(t) + \tau \dot{x}(t) = (I + A\tau)x(t)}$$

Forward integrator

$$x(t+\tau) = e^{A\tau} x(t) = \left[ I + A\tau + \frac{A^2\tau^2}{2!} + \dots \right] x(t)$$

$$x(t+\tau) = \left[ I - A\tau \right]^{-1} x(t)$$

$$I + A\tau + \frac{A^2\tau^2}{2} + \frac{A^3\tau^3}{4} + \dots$$

↑





## Sampling a continuous-time system (1.2)

$$\dot{x} = Ax$$

Sample  $x$  at  $t_1 \leq t_2 \leq t_3 \dots$   $z_k \hat{=} x(t_k)$

$$z_{k+1} = e^{A(t_{k+1} - t_k)} z_k$$

$\Delta t = h$

$$t_{k+1} - t_k = h \quad \forall k$$

$$z_{k+1} = e^{Ah} z_k$$

Discrete Version of CDS



# Piecewise Constant System (1.2)

$$A(t) = \begin{cases} A_0 & 0 < t < t_1 \\ A_1 & t_1 < t < t_2 \\ A_2 \\ \vdots \end{cases}$$

jump linear system

power system (small variations)

Hybrid systems

$$x(t) = e^{A_1(t-t_1)} e^{A_2(t_1-t_2)} \cdots e^{A_3(t_2-t_1)} e^{A_4(t_1-t_2)} e^{A_5} x_0$$

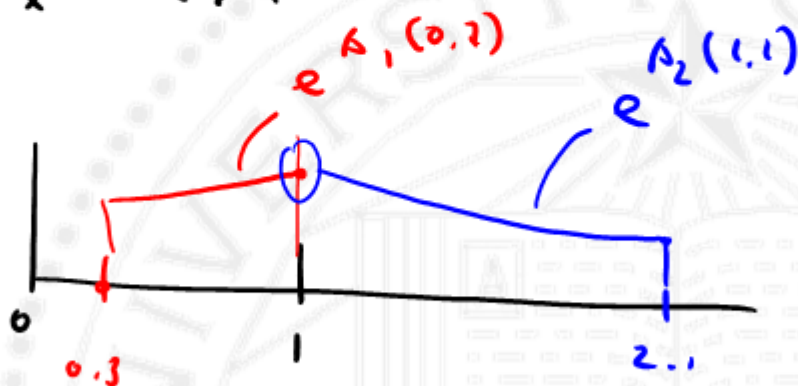

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## Piecewise Constant System (2.2)

$$\dot{x} = A_1 x \quad 0 < t < 1$$

$$\dot{x} = A_2 x \quad t > 1$$



## Qualitative behavior of $x(t)$ (1.3)

$$\dot{x} = Ax \quad x(1) \in \mathbb{R}^n$$

$$x(t) = \underbrace{e^{At}}_{\text{TIME}} x_0$$

$$X(s) = \underbrace{[sI - A]^{-1}}_{\text{Poles}} x_0$$

$i$ th component of  $X_i(s) = \frac{a_i(s)}{X(s) \leftarrow \det(sI - A)}$

$a_i$  polynomial in  $s$ , degree  $< n$

Poles of  $X_i$  are the eigenvalues of  $A$ .



## Qualitative behavior of $x(t)$ (2.3)

Assume we have distinct eigenvalues  $\lambda_i \neq \lambda_j$

$$x_i(t) = \sum_{j=1}^n \beta_{ij} e^{\lambda_j t}$$

$\beta_{ij}$  depends linearly on  $x(0)$

$\dot{x} = Ax$  has a response that is a sum of the (complex) frequencies of  $A$ .



## Qualitative behavior of $x(t)$ (3.3)

Eigenvalues of  $A$  give the exponents that can  
occur in exponentials.

Real Eigenvalues:  $\lambda$  corresponds to exponential  
growth or decay



Complex eigenvalues  $\lambda = \sigma \pm j\omega$   
corresponds to a decaying or growing  
sinusoidal term

$$e^{\sigma t} \cos(\omega t + \phi)$$

Real( $\lambda$ ) exponent envelope    Im( $\lambda$ ) freq. of oscillation



$$\chi(s) = \det(st - A) = \phi$$

## Complex Plane Visualization (1.2)

