

MIDTERM REVIEW

01/NOV/2007

TOPICS

LINEAR FUNCTIONS — $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$

superposition holds $\begin{cases} f(a+b) = f(a) + f(b) \\ f(\alpha a) = \alpha f(a) \end{cases}$

$f \rightarrow y = Ax \quad y \in \mathbb{R}^m, x \in \mathbb{R}^n$

Interpretations —

$$C = AB$$



Dual — Estimation
Control / Design

Vector Spaces

Inner Products

Independence

"onto"

Basis

Range

Dimension

Rank

Norms

Null

Angles

Span



$$\text{Range}\{V\} \quad V = [v_1, v_2]$$

$$\text{Span}\{v_1, v_2\} = \alpha v_1 + \beta v_2 \quad \forall \alpha, \beta \in \mathbb{R}$$

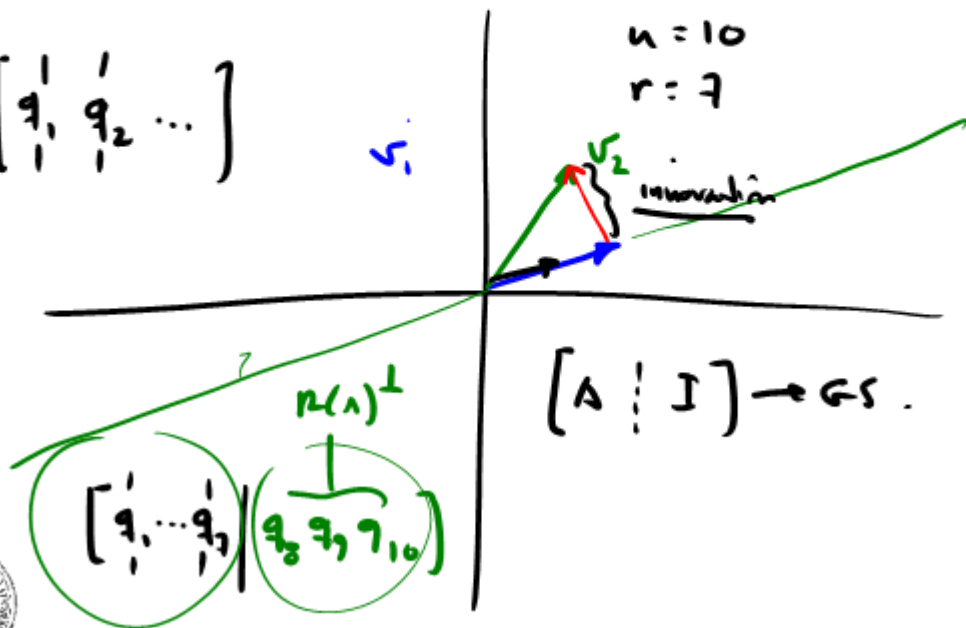
$$\begin{bmatrix} | & | & \dots \\ q_1 & q_2 & \dots \\ | & | & \dots \end{bmatrix}$$

 v_i

$$n = 10$$

$$r = 7$$

innovation



- Left / right inverse
- Orthonormality
 - orthonormal sets of vectors
 - Orthogonal matrix ($\bar{A}^{-1} = A^T$).
- Rotations / Reflections ($\det = \pm 1$).

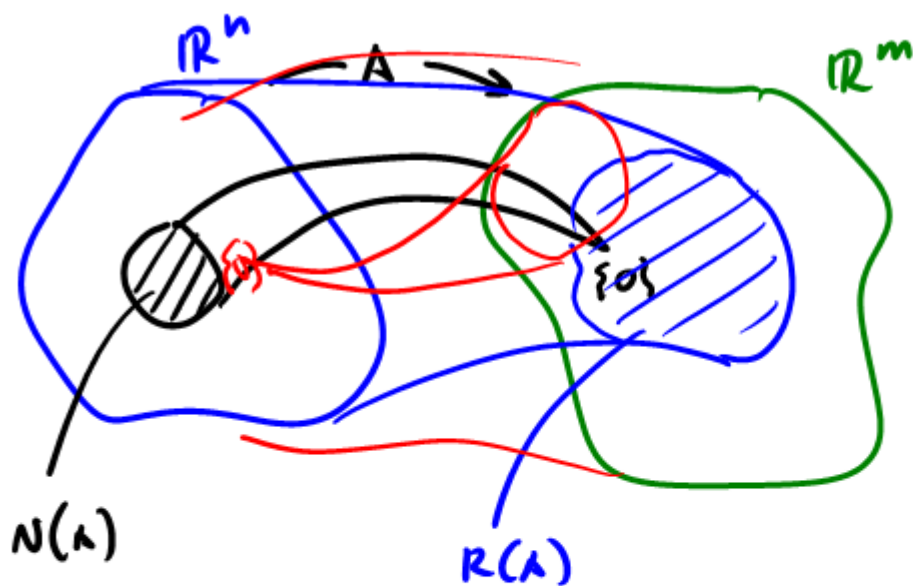
- QR factorization \bar{R}^{-1} exists

- Gram-Schmidt Procedure

- Decompose a matrix $A = QR$

$$A = \begin{matrix} \begin{matrix} \left[\begin{matrix} | & | & | \end{matrix} \right] \\ Q \end{matrix} \begin{matrix} \begin{matrix} \triangle \\ R \end{matrix} \end{matrix} \end{matrix} \begin{matrix} n \\ n \\ n \end{matrix}$$

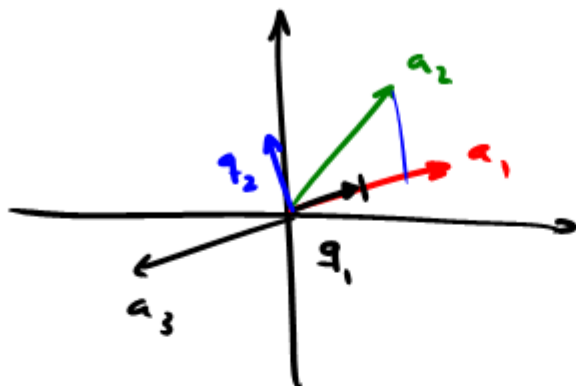




$$R(A) \perp N(A^T) = \mathbb{R}^m$$

$$\begin{aligned} R(A) \perp N(A^T) &\rightarrow \mathbb{R}^m \\ R(A^T) \perp N(A) &\rightarrow \mathbb{R}^n \end{aligned}$$





LEAST SQUARES

$$y = Ax + v$$

↑ measurement

↑ parameters

↙ noise

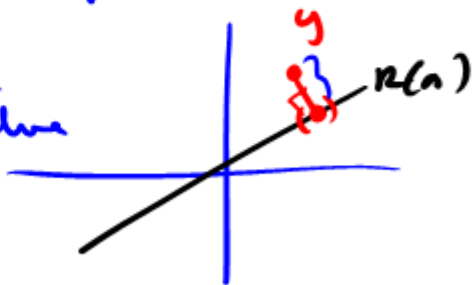
ESTIMATION

$$x_{ls} = (A^T A)^{-1} A^T y$$

$$A^+ \triangleq (A^T A)^{-1} A^T$$

pseudo-inverse
least-squares inverse
of A

- Projection
- Estimation
- Orthogonality of the Residuals
- Geometric Interpretations

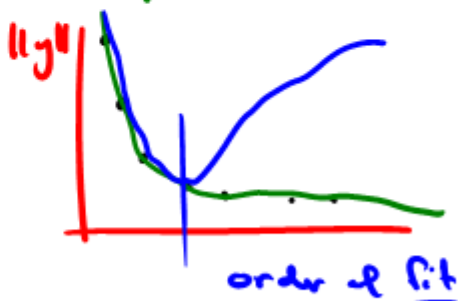


BLUE — Best Linear Unbiased Estimator.

$$y^T \Lambda x + v \quad \underline{\hat{x}} = x_{ls} = x \text{ if } v = \phi.$$

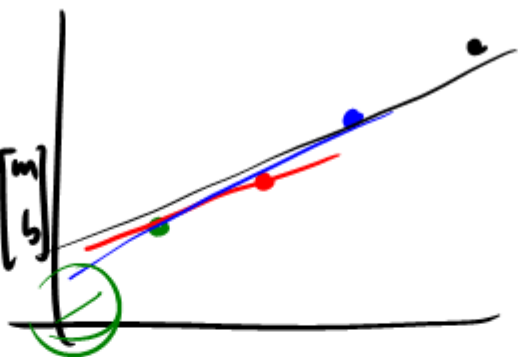
LEAST SQUARES APPLICATIONS

- Growing sets of Regressors (polynomial fitting)
- System Identification
 - Cross Validation
- Growing sets of measurements
FAST UPDATE RES



$$y = mx + b$$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} x_1 & 1 \\ \vdots & \vdots \\ x_n & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix}$$



Extensions to least squares

- Regularized least squares (Tychonov Regularization)

$$(A^T A + \mu I)^{-1} A^T y \quad \leftarrow \text{change is full rank}$$

- Non-linear least squares

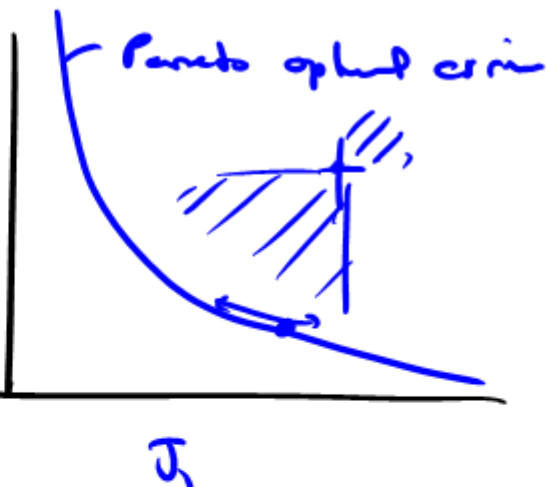
- Linearizing about a point
- Gauss-Newton method



Mixed optimum criteria

$$J_1 + \mu J_2$$

J_2



Solve $y = Ax$ with $\min x^T x$

$$\min x^T x$$

under determined set ($n < p$)

$$\text{sub } Ax - y = 0.$$

$$x_{ls} = A^T (AA^T)^{-1} y$$

right inverse of A .



Lagrange Multipliers

$$L = x^T x + \lambda (Ax - y)$$

$$\begin{aligned} \nabla_x L &= 0 \\ \nabla_\lambda L &= 0 \end{aligned} \quad \rightarrow \text{find solution}$$

$$\left[\begin{array}{l} \min \|Cx + D\| \\ \text{subj } Ax = y \end{array} \right]$$

$$\rightarrow \begin{bmatrix} x \\ \lambda \end{bmatrix} = \begin{bmatrix} A^T A & C^T \\ C & 0 \end{bmatrix}^{-1} \begin{bmatrix} A^T y \\ D \end{bmatrix}$$



$$y \neq Ax$$

$$(y - A\hat{x})^T \hat{x} = \phi$$

$$(\underbrace{I - A(A^T A)^{-1} A^T}) y = \underline{r}$$

$R(A)$

\hat{x}

r

ϕ

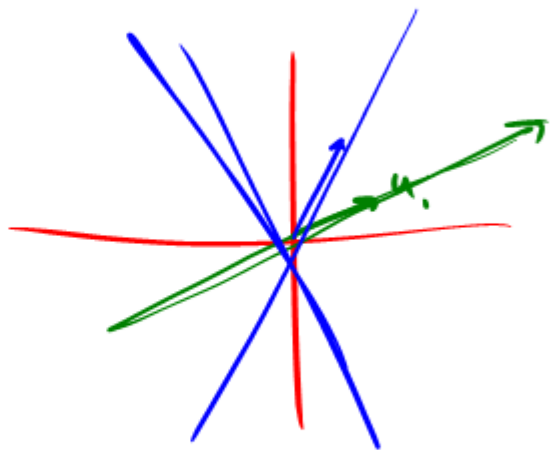


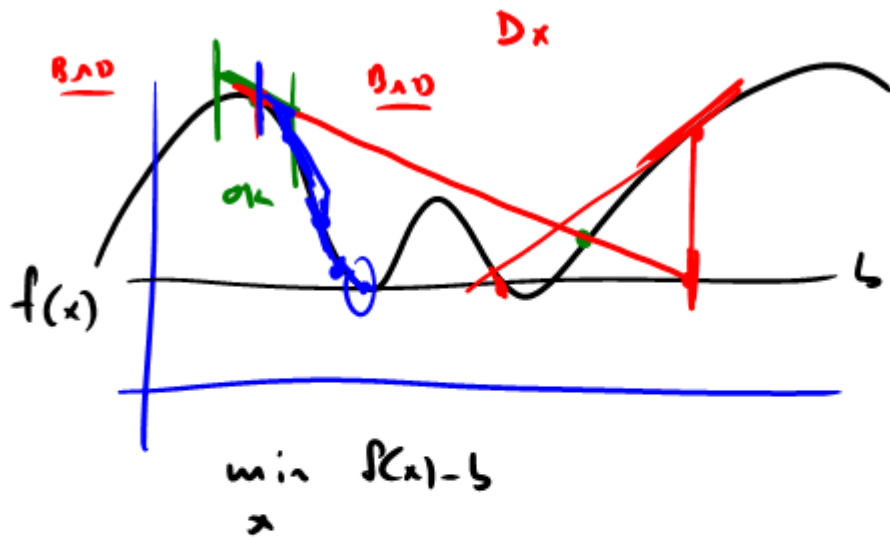
$$(I - U_I U_I^T)$$

$u_i \quad u_i u_i^T = \text{rank}(1) \text{ matrix.}$

$$I - u_i u_i^T \rightarrow$$

$$\left[I - \sum_{i=1}^n u_i u_i^T \right]$$





$$y = A \sin(\omega t + \phi) + D + \dots \quad \text{IEEE 1057}$$



$$y = \hat{A} \sin(\omega t) + \hat{B} \cos(\omega t) + D$$

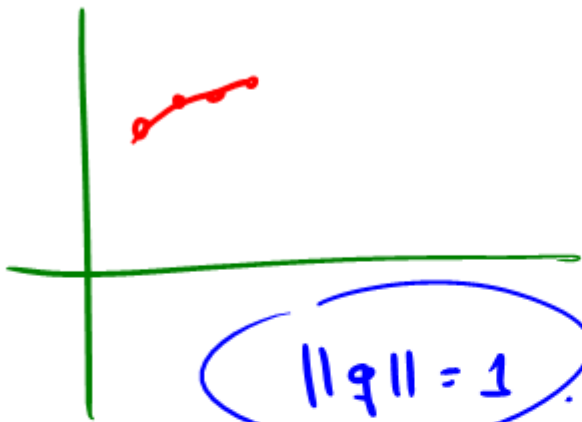
$\frac{\partial F}{\partial \omega}$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} \sin \omega t_1 & \cos \omega t_1 & 1 \\ \vdots & \vdots & \vdots \\ \sin \omega t_n & \cos \omega t_n & 1 \end{bmatrix} \begin{bmatrix} \hat{A} \\ \hat{B} \\ D \end{bmatrix}$$

$\lambda(\omega)$
 $r(\omega)$

$$\omega_0 \rightarrow \omega_0 + \delta\omega \cdot \left(\left(\frac{\partial F}{\partial \omega} \right)^T \left(\frac{\partial F}{\partial \omega} \right)^{-1} \right)^T + \mu \mathbf{I}$$





$$\begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$



SGP



$$\begin{cases} F_{ij} = 1 & \text{if } j \in F_o(i) \\ F_{ij} = \phi & \text{otherwise} \end{cases}$$



$$d_i = \beta_i + \gamma_i C_i^{\text{load}} / x_i$$

$$C_i^{\text{load}} = C_i^{\text{ext}} + \sum_{j \in F_o} C_j^{\text{in}}$$

$$d_i = T$$

$$T = d_i = \beta_i + \gamma_i \frac{C_i^{\text{load}}}{x_i} =$$



$$T = \beta_i + \gamma_i \left[\frac{C_i^{\text{ext}} + \sum_{j \in \text{FO}(i)} C_j^{\text{in}}}{x_i} \right] \quad C_j^{\text{in}} = \alpha_j x_j$$

$$= \beta_i + \gamma_i \left[\frac{C_i^{\text{ext}} + \sum_{j \in \text{FO}(i)} C_j^{\text{in}}}{x_i} \right]$$

$$= \beta_i + \gamma_i \left[\frac{C_i^{\text{ext}} + \sum_{j \in \text{FO}(i)} \alpha_j x_j}{x_i} \right]$$

$$T x_i = \beta_i x_i + \gamma_i \left(C_i^{\text{ext}} + \sum_{j \in \text{FO}(i)} \alpha_j x_j \right)$$



$$T x = \text{diag}(\beta) \circledast x + \text{diag}(\gamma) C^{ext} + \underbrace{\text{diag}(\gamma) F \text{diag}(\alpha)}_{\text{matrix}} \circledast x$$

$$\begin{bmatrix} \beta_1 & & 0 \\ & \ddots & \\ 0 & & \beta_n \end{bmatrix}$$

$$\begin{bmatrix} \gamma_1 & & \\ & \ddots & \\ & & \gamma_n \end{bmatrix}$$

$$\begin{bmatrix} \alpha_1 & & \\ & \ddots & \\ & & \alpha_n \end{bmatrix}$$

$$K = \begin{bmatrix} \beta_1 & & \\ & \ddots & \\ & & \beta_n \end{bmatrix} + \begin{bmatrix} \gamma_1 & & \\ & \ddots & \\ & & \gamma_n \end{bmatrix} F \begin{bmatrix} \alpha_1 & & \\ & \ddots & \\ & & \alpha_n \end{bmatrix}$$

$$T x = \underbrace{K x}_{\text{matrix}} + \begin{bmatrix} \gamma_1 & & \\ & \ddots & \\ & & \gamma_n \end{bmatrix} C^{ext}$$



$$Tx - Kx = \begin{bmatrix} \gamma_1 & & \\ & \ddots & \\ & & \gamma_n \end{bmatrix} C^{ext}$$

$$T > \max_i \rho_i$$

$$(TI - K)x = \begin{bmatrix} \gamma_1 & & \\ & \ddots & \\ & & \gamma_n \end{bmatrix} C^{ext}$$

$$x = \boxed{(TI - K)^{-1}} \begin{bmatrix} \gamma_1 & & \\ & \ddots & \\ & & \gamma_n \end{bmatrix} C^{ext}$$

