

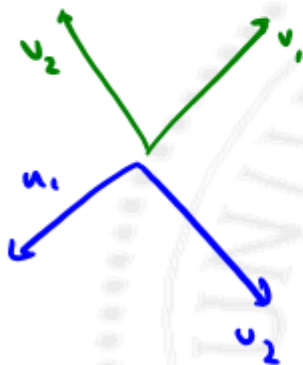
Singular Value Decomposition Applications

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$$A \in \mathbb{R}^{9 \times 9} \rightarrow \text{SVD} \rightarrow \Sigma = \text{diag}(\underbrace{10, 7}_{\substack{\text{rank of } \mathbb{R}^{2 \times 2}}}, \alpha_1, 0, 0.05)$$

$$10 \geq \frac{\|Ax\|}{\|x\|} \geq 0.05$$



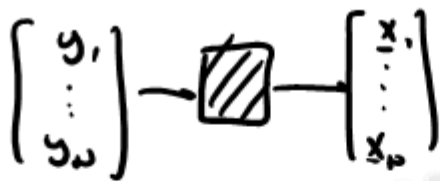
$$y = Ax$$

$$\text{Rank}(A) = 4$$

$$K(A) = \frac{10}{0.05} = 200.$$



$$\dot{x} = Ax$$
$$y = Cx$$



$$G = \begin{bmatrix} c \\ c_1 \\ c_2 \\ \vdots \\ c_{n-1} \end{bmatrix}$$

rank(G) is full

$$\kappa(G) \triangleq \frac{\sigma_{\max}}{\sigma_{\min}}$$

CONDITION # $[1 \rightarrow \infty]$

$$\text{RCOND} \triangleq \frac{\sigma_{\min}}{\sigma_{\max}}$$

$[1 \rightarrow 0]$



Singular Value Decomposition Applications

- Low rank approximation via the SVD
- General pseudo-inverse
- Full SVD
- Image of Unit Ball under linear transformation
- SVD in estimation/inversion
- Sensitivity of linear equations to data error



General Pseudo-Inverse (1.3)

eigenvalues : $A = T \Lambda T^{-1}$ $A \in \mathbb{R}^{n \times n}$

symmetric : $A = Q \Lambda Q^T$ $A = A^T \in \mathbb{R}^{n \times n}$

SVD : $A = U \Sigma V^T$ $A \in \mathbb{R}^{n \times m}$, $\text{rank}(A) = r$

$U^T U = I$ $\begin{pmatrix} 1 & & \\ & \ddots & \\ & & 1 \end{pmatrix}$ $V^T V = I$

$\sigma_1, \sigma_2, \dots, \sigma_r$

A^\dagger defined for skinny, fat, full ranked matrices

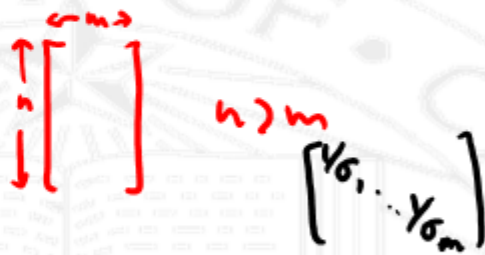


General Pseudo-Inverse (2.3)

if A has an SVD: $A = U \Sigma V^T$
 $\leftarrow \begin{matrix} U \\ \Sigma \end{matrix} \begin{matrix} n \times n \\ r \times r \end{matrix}, \text{ positive}$

$$A^+ = V \bar{\Sigma}^+ U^T \quad \leftarrow \text{pinv}$$

skewing full rank matrix $A \in \mathbb{R}^{n \times m}$



$$A^+ = (A^T A)^{-1} A^T = [(U \Sigma V^T)^T (U \Sigma V^T)]^{-1} (U \Sigma V^T)^T$$

$$= [V \Sigma^T U^T U \Sigma V^T]^{-1} V \Sigma U^T =$$

$$= [V \Sigma^2 V^T]^{-1} V \Sigma U^T = V \bar{\Sigma}^{-2} \boxed{V^T V} \Sigma U^T = \boxed{V \bar{\Sigma}^+ U^T}$$



General Pseudo-Inverse (3.3)

A is full & full rank $\rightarrow A^{\dagger} = A^T(AA^T)^{-1}$ $(AB)^{-1} = B^{-1}A^{-1}$

$$A^{\dagger} = (U\Sigma V^T)^T \left[(U\Sigma V^T \cdot U\Sigma V^T)^T \right]^{-1}$$

$$= V\Sigma U^T \left[U\Sigma V^T U\Sigma U^T \right]^{-1} = V\Sigma U^T \left[U\Sigma^2 U^T \right]^{-1}$$

$$= V\Sigma U^T \left[U \bar{\Sigma}^{-2} U^T \right] = V \Sigma U^T U \bar{\Sigma}^{-2} U^T = \boxed{V \bar{\Sigma}^{-1} U^T}$$



Skinnig full rank: $\begin{bmatrix} A \end{bmatrix} \rightarrow x_{ls} = A^+ y = V \bar{\Sigma}^{-1} U^T y$

Fat full rank: $\begin{bmatrix} A \\ \end{bmatrix} \rightarrow x_{ls} = A^+ y = V \bar{\Sigma}^{-1} U^T y$

In general $x_{ls} = \left\{ z \mid \|Az - y\| = \min_w \|Aw - y\| \right\}$

$x_{pinv} = A^+ y \in X_{ls}$ has the min. norm.



Pseudo-Inverse via Regularization (1.2)

Let $\mu > 0$: x_{μ} is a unique minimizer.

$$\|Ax_{\mu} - y\|^2 + \mu \|x_{\mu}\|^2 \rightarrow x_{\mu} = (A^T A + \mu I)^{-1} A^T y.$$

$$(A^T A + \mu I) > 0.$$

$$x_{\mu} = (V \Sigma^2 V^T + \mu V V^T)^{-1} V \Sigma U^T$$

$$= [V (\Sigma^2 + \mu I) V^T]^{-1} V \Sigma U^T$$

$$= V (\Sigma^2 + \mu I)^{-1} \Sigma U^T$$

$$V \begin{bmatrix} \frac{\sigma_i}{\sigma_i^2 + \mu} & & \\ & \ddots & \\ & & \frac{\sigma_r}{\sigma_r^2 + \mu} \end{bmatrix} U^T$$



Pseudo-Inverse via Regularization (2.2)

$$\lim_{\mu \rightarrow 0} \frac{1}{\mu} \left[\begin{array}{c} \frac{\sigma_i}{\sigma_i^2 + \mu} \\ \vdots \\ \frac{\sigma_r}{\sigma_r^2 + \mu} \end{array} \right] U^T \rightarrow \underline{A^\dagger = V \Sigma^{-1} U^T}$$



Full SVD (1.3)

$$A \in \mathbb{R}^{m \times n}$$

$$\text{rank}(A) = r$$

$$m > n$$

$$A = U, \Sigma, V_1^T = [u_1 \dots u_r] \begin{bmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r \end{bmatrix} \begin{bmatrix} v_1^T \\ \vdots \\ v_r^T \end{bmatrix}$$

$$U = [u_1; u_2] \in \mathbb{R}^{m \times m}$$

$$R(U) = \mathbb{R}^m$$

$$V = [v_1; v_2] \in \mathbb{R}^{n \times n}$$

$$R(V_1) = N(A)^\perp$$

$$\Sigma = \begin{bmatrix} \overset{r \times r}{\Sigma} & \overset{r \times (n-r)}{0} \\ \underset{(m-r) \times r}{0} & \underset{(m-r) \times (n-r)}{0} \end{bmatrix}$$



Full SVD (2.3)

$$A = [u_1 | u_2] \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1^T \\ v_2^T \end{bmatrix} = U \Sigma V^T$$

Σ^{-1} no longer allowed

σ_1 unambiguous

σ_{\min} ? σ_r or ϕ .

$$\text{SVD}(A) = U \Sigma V^T$$

$$\text{SVD}(A, \underbrace{1 \dots 1}_r) = [u_1 | u_2] \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1^T \\ v_2^T \end{bmatrix}$$



Full SVD (3.3)

$$y = Ax$$



$$A = U\Sigma V^T$$

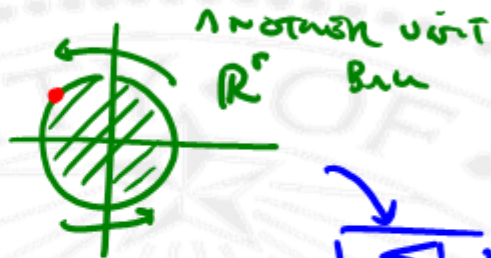
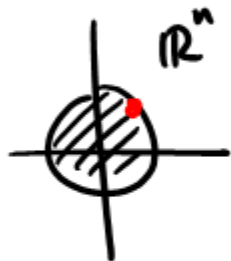
$$\{x \mid \|x\| \leq 1\} \rightarrow$$



Unit Ball under Linear Transformation (1.3)

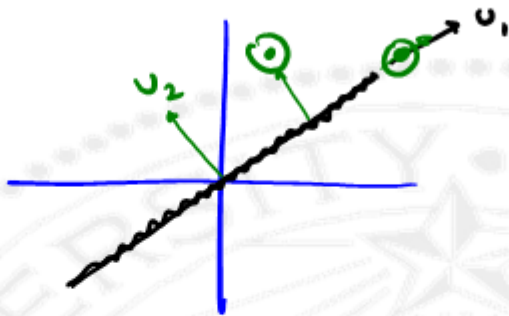
$$\{x \mid \|x\| \leq 1\}$$

$$\|V^T x\| = \|x\|$$



Unit Ball under Linear Transformation (2.3)

$$\Sigma = \begin{pmatrix} 2 & \\ & \frac{1}{1000} \end{pmatrix}$$



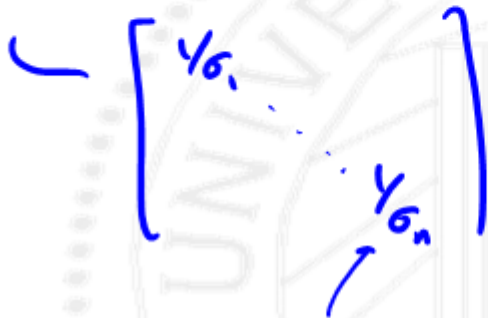
$$\Sigma = \begin{pmatrix} 16 & \\ & 0.01 \end{pmatrix}$$



Unit Ball under Linear Transformation (3.3)

$$A = U \Sigma V^T$$

$$A^T = V \Sigma^{-1} U^T$$



SVD in estimation/inversion (1.3)

$$y = Ax + v$$

$y \in \mathbb{R}^m$ measurement

$x \in \mathbb{R}^n$ vector to be estimated

$v \in \mathbb{R}^m$ is our noise $\|v\| < \alpha$.

$$\hat{x} = A^+ y$$

$$\hat{x} = B y$$

$BA = I$ underdetermined solution

$\hat{x} = x$ if $v=0$.

$$\tilde{x} \triangleq \hat{x} - x = B(Ax + v) - x = BAx + Bv - x = Bv$$

$$\tilde{x} \in \Sigma_{v \in B} = \{ Bv \mid \|v\| \leq \alpha \}$$

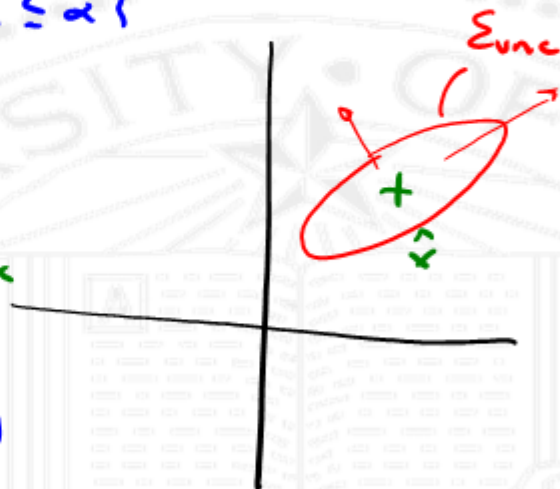


SVD in estimation/inversion (2.3)

$$\tilde{x} \in \Sigma_{unc} = \{Bv \mid \|v\| \leq \alpha\}$$

$$x = \hat{x} - \tilde{x} = \hat{x} + \underline{\Sigma}_{unc}$$

True x lies within the Σ_{unc}
centered @ \hat{x} .



izsin



SVD in estimation/inversion (3.3)

Semi-major axes of Σ_{unc} $\propto \sigma_i u_i$ singular value and right singular vector of B

$$\|\hat{x} - x\| \leq \alpha \|B\| \quad BA = I$$

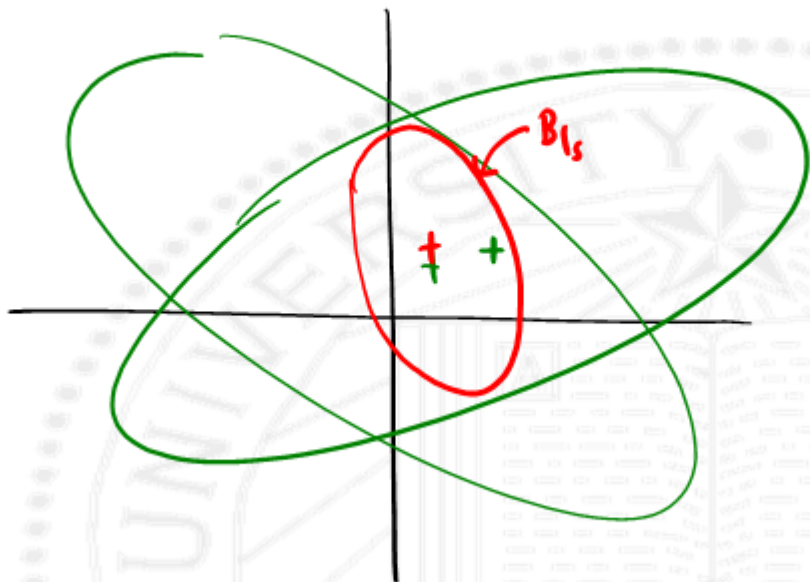
$$B_{ls} = A^T \quad B_{ls} B_{ls}^T = B B^T$$

$$\sigma_i(B_{ls}) \leq \sigma_i(B) \quad i = 1, \dots, n$$

$$\|B_{ls}\| \leq \|B\| \rightarrow \Sigma_{ls} \subseteq \Sigma_{unc_B}$$



Example (1.3)



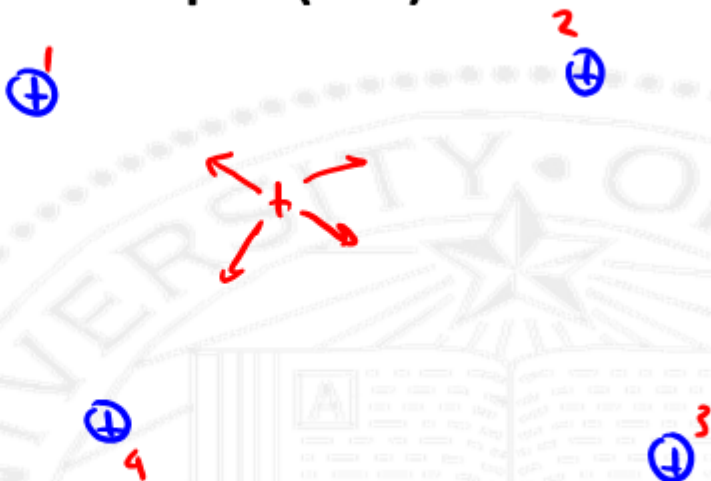
Example (2.3)

$$y_i = -k_i^T x + v_i$$

$$A_1 = \begin{bmatrix} -k_1^T \\ -k_2^T \end{bmatrix}$$

$$A_2 = - \begin{bmatrix} k_1^T \\ \vdots \\ k_n^T \end{bmatrix}$$

$$\alpha = 1$$

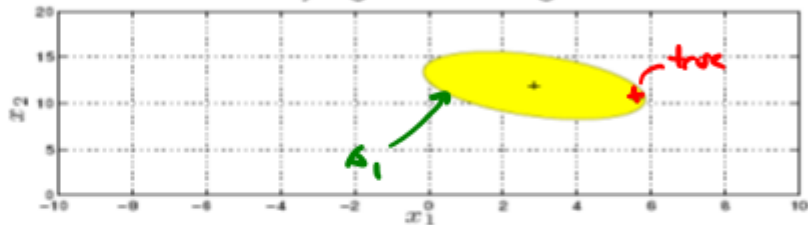


Example (3.3)

only use first
two beams

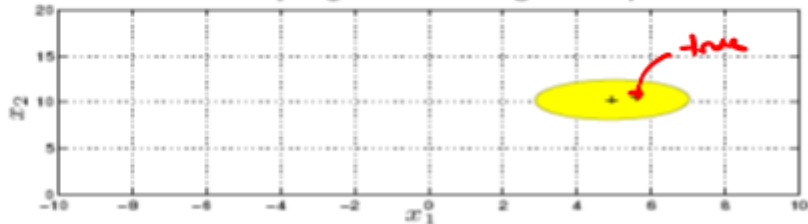


uncertainty region for x using inversion



LS solution

uncertainty region for x using least-squares



Proof of Optimality Property (2.3)

$$BB^T = (B_4 + z)(B_4 + z)^T$$

$$= B_4 B_4^T + \underbrace{B_4 z^T + z B_4^T}_{z B_4^T} + z z^T$$

$$= B_4 B_4^T + z z^T$$

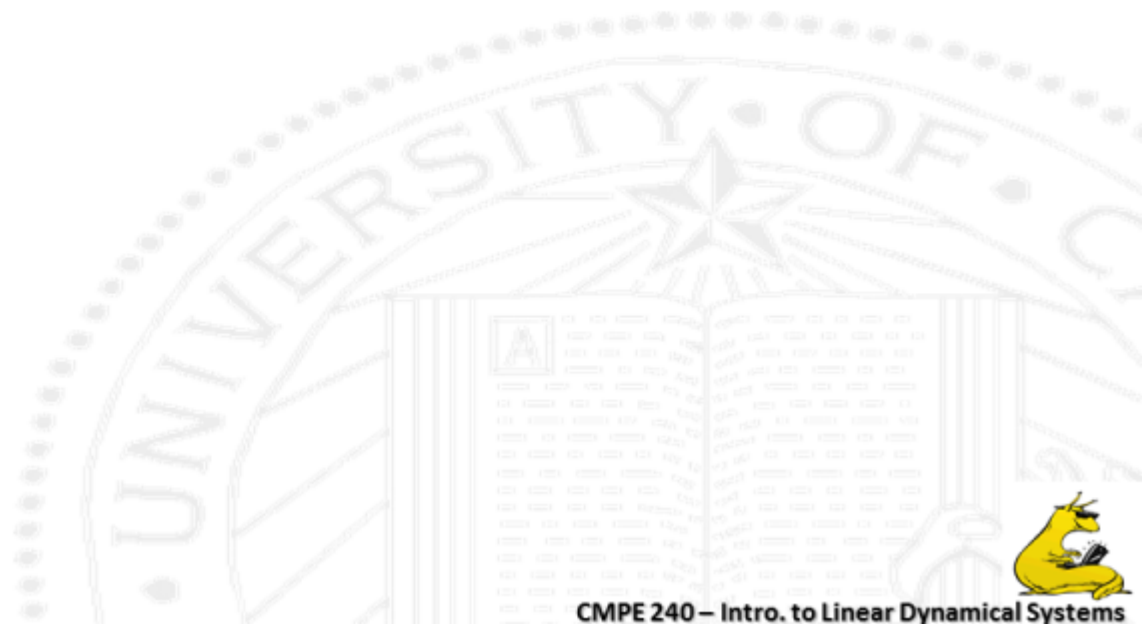
$$z B_4^T = (zu) \bar{\Sigma}^{-1} v^T = 0$$

$$\underline{BB^T = B_4 B_4^T + z z^T}$$

$$\rightarrow B_4 B_4^T \leq BB^T$$



Proof of Optimality Property (3.3)



Sensitivity of Linear Equations to Data Error (1.3)

$$y = Ax \quad A \in \mathbb{R}^{n \times n} \quad \bar{A}^{-1} \text{ exists}$$

$$x = \bar{A}^{-1} y \longrightarrow (x + \delta x) = \bar{A}^{-1} (y + \delta y)$$

$$A = U \Sigma V^T$$

$$\bar{A}^{-1} = V \bar{\Sigma}^{-1} U^T = \underbrace{V R}_{C_2} \underbrace{\bar{\Sigma}^{-1} R U^T}_{C_1}$$

$$R = \begin{bmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ & & & \ddots \end{bmatrix}$$
$$\bar{\Sigma}^{-1} = \begin{bmatrix} 1/\sigma_n & & & \\ & \ddots & & \\ & & 1/\sigma_1 & \\ & & & \ddots \end{bmatrix}$$



Sensitivity of Linear Equations to Data Error (2.3)

$$\|\delta x\| = \|\bar{A}^{-1} \delta y\| \leq \|\bar{A}^{-1}\| \|\delta y\|$$

if $\|\bar{A}^{-1}\|$ is large:

- small errors in y can lead to big errors in x
- can't solve for x given y with small errors
- it may be ill-posed, but in practice is regular.



Sensitivity of Linear Equations to Data Error (3.3)

$$y = Ax \quad \|y\| = \|A\| \|x\|$$

$$\frac{\|\delta x\|}{\|x\|} \leq \underbrace{\|A\| \|A^{-1}\|}_{K(A)} \frac{\|\delta y\|}{\|y\|}$$

perturbation in x is %

perturbation in y is %.

$$\kappa_{\text{cond}} \triangleq \frac{1}{K(A)}$$

$$K(A) = \|A\| \|A^{-1}\| = \frac{\sigma_{\max}(A)}{\sigma_{\min}(A)} \geq 1 \quad \text{"cond"}$$



Relative error in solution $\leq K \cdot$ relative error in data.



Low rank approximations (1.3)

#bits in solution \approx #bits in data $- \log_2 K$

K small $\rightarrow 1$ A "well conditioned"

K large $\rightarrow \infty$ A "ill conditioned"

$$\kappa(A) \triangleq \frac{\sigma_{\max}(A)}{\sigma_{\min}(A)}$$



Low rank approximations (2.3)

$$A \in \mathbb{R}^{m \times n} \quad m > n \quad \text{rank}(A) = r$$

$$A = U \Sigma V^T = \sum_{i=1}^r \sigma_i \underbrace{u_i v_i^T}_{\text{rank 1 matrix expression}}$$

$$\hat{A} \rightarrow \text{rank}(\hat{A}) \leq p < r \quad \text{such that } \hat{A} \approx A$$

$$\min_{\hat{A}} \|A - \hat{A}\|$$

$$\|A\|_{F_2} = \|A(:,i)\|$$

$$\hat{A} = \sum_{i=1}^p \sigma_i u_i v_i^T$$



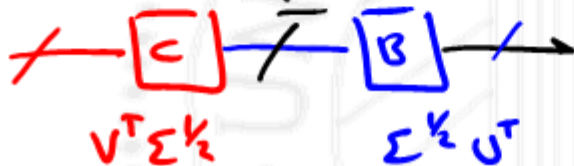
Low rank approximations (3.3)

$$\|A - \hat{A}\| = \left\| \sum_{i=p+1}^r \sigma_i u_i v_i^T \right\| = \sigma_{p+1}$$

$u_i v_i^T$ — in order of importance

$$A = BC$$

100000



Distance to Singularity (1.3)

$$\sigma_i : \sigma_i = \min \{ \|A - B\| \mid \text{rank}(B) \leq (i-1) \}$$

$\{15, 10, 3, 2, 1 \times 10^{-5}\}$

$$y = Ax + v \quad \|v\| \leq \underline{0.01}$$

Small $\sigma_{n,i}$ means that A is close to singular



Distance to Singularity (2.3)

$$y = \underset{\text{regime}}{\underbrace{Ax + v}} \quad \downarrow \text{noise}$$

$$A \in \mathbb{R}^{100 \times 30}$$

$$\Sigma = \{10, 7, 2, \frac{1}{2}, \dots\} \left[\frac{1}{100}, \frac{1}{1000}, \dots \right]$$

$\|x\|$ is on the order of 1

$\|v\|$ is on the order of 0.1

$$\sigma_i u_i v_i^T = 0 \text{ for } i=5 \dots 30.$$

$$y = \sum_{i=1}^4 \sigma_i u_i v_i^T x + v$$

Rank model



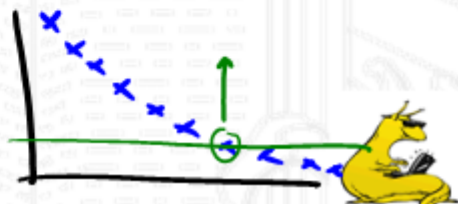
Distance to Singularity (3.3)

$$\{a_1, \dots, a_{100}\} \in \mathbb{R}^{10}$$

stock price data for last 100 days

$$[a_1 \dots a_{100}] = h \in \mathbb{R}^{10 \times 100} \quad \mathbb{R}^2 \rightarrow \mathbb{R}^1$$

$\text{svd}(h) \rightarrow 3$ significant singular values



Questions?





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CMPE 240 – Intro. to Linear Dynamical Systems