

Symmetric Matrices, Quadratic Forms, Matrix Norm, and SVD

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Symmetric Matrices, Quadratic Forms, Matrix Norm, and the SVD

- Singular Value Decomposition
- Eigenvectors of symmetric matrices
- Quadratic Forms
- Inequalities for quadratic forms
- Positive semi-definite matrices
- Norm of a matrix



Eigenvalues of Symmetric Matrices (1.2)

$$A \in \mathbb{R}^{n \times n} \quad A = A^T \quad \text{Symmetric}$$

fact: eigenvalues of A are all real

$$Av = \lambda v \quad v \neq 0 \quad v \in \mathbb{C}^n$$

$$\bar{v}^T Av = \bar{v}^T (\lambda v) = \lambda \bar{v}^T v = \lambda \sum_{i=1}^n |v_i|^2$$

$$\bar{v}^T Av = (Av)^T v = (\lambda v)^T v = \bar{\lambda} \bar{v}^T v = \bar{\lambda} \sum_{i=1}^n |v_i|^2$$

$$\lambda = \bar{\lambda} \quad \text{i.e.: } \lambda \in \mathbb{R} \quad v \in \mathbb{R}^n$$



Eigenvalues of Symmetric Matrices (2.2)

$\dot{x} = Ax$ $A = A^T$ no oscillations "self-adjoint"

choose an orthogonal set of eigenvectors of A ($=A^T$)

q_1, \dots, q_n such that $Aq_i = \lambda_i q_i$ and $q_i^T q_j = \delta_{ij}$

$[q_1 \dots q_n] \triangleq Q$ orthogonal matrix $Q^T = Q^{-1}$

$$Q^{-1} A Q = Q^T A Q = \Lambda$$

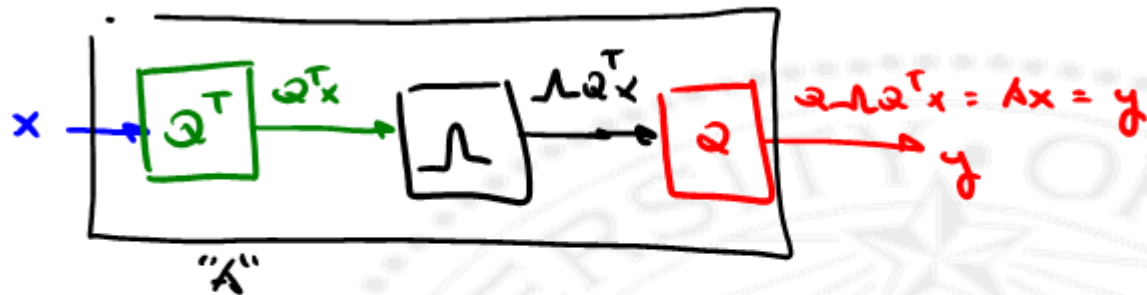
left/right eigenvectors are the same.

$$A = Q \Lambda Q^T = \sum_{i=1}^n \lambda_i \underline{q_i q_i^T}$$

← rank 1 dyadic expansion



Eigenvectors of Symmetric Matrices (1.2)



- Resolve x into q_i coordinates

- Scale those coordinates by λ_i } dilation

- Reconstruct y with basis of q .



Eigenvectors of Symmetric Matrices (2.2)

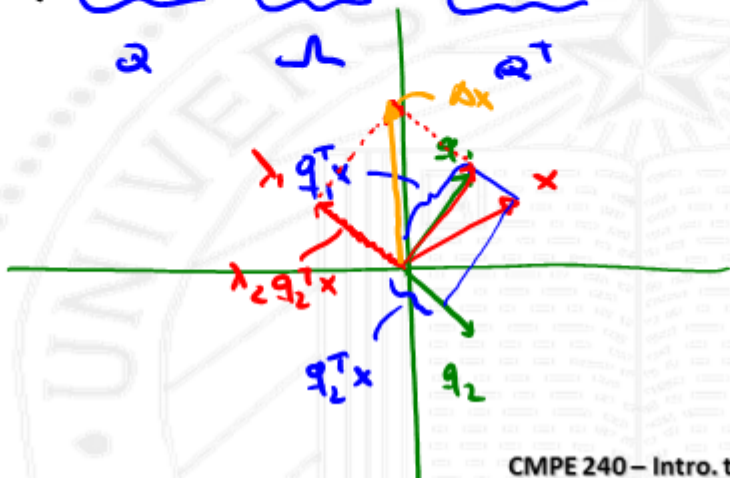
$$A = \sum_{i=1}^n \lambda_i \underbrace{q_i q_i^T}_{n \times n \text{ rank 1 diagonal}}$$

orthogonal projection spanned by
the line q_i



Interpretation (1.3)

$$A = \begin{bmatrix} -\frac{1}{2} & \frac{3}{2} \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix} = \left(\underbrace{\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}}_Q \right) \left(\underbrace{\begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix}}_D \right) \left(\underbrace{\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}}_{P^T} \right)$$



Interpretation (2.3)

λ_i are distinct

suppose v_1, \dots, v_n are a set of linearly independent eigenvectors of A .

$$Av_i = \lambda_i v_i \quad \|v_i\| = 1$$

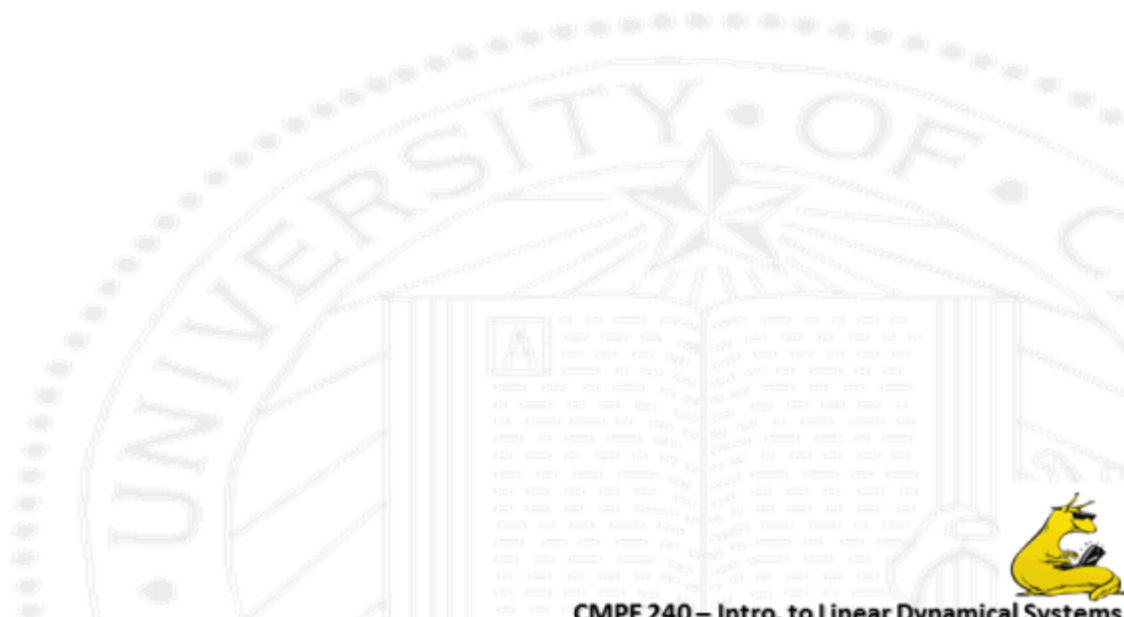
\uparrow
distinct

$$v_i^T (Av_j) = (Av_j)^T v_i = \lambda_j v_j^T v_i = \lambda_i v_i^T v_j$$

$$(\lambda_i - \lambda_j) v_i^T v_j = 0 \quad v_i^T v_j = 0 \quad v_i \perp v_j$$



Interpretation (3.3)



Example (1.5)

$$C_k \dot{v}_k = -i_k$$

$$i = Gv$$

$G \triangleq$ conductance matrix

$$G = G^T \in \mathbb{R}^{n \times n}$$



not necessarily
symmetric

Example (2.5)

$$\dot{v} = -C^{-1}Gv$$

$$x_i = \sqrt{c_i} v_i$$

$$x = C^{1/2} v \quad \rightarrow \quad v = C^{-1/2} x$$

$$\dot{x} = C^{1/2} \dot{v}$$

$$\dot{x} = -C^{1/2} C^{-1} G C^{-1/2} x$$

$$\dot{x} = - \underbrace{C^{-1/2} G C^{-1/2}}_{\text{symmetric}} x$$



$$C = \begin{bmatrix} c_1 & & \\ & \ddots & \\ & & c_n \end{bmatrix}$$
$$C^{1/2} = \begin{bmatrix} \sqrt{c_1} & & \\ & \ddots & \\ & & \sqrt{c_n} \end{bmatrix}$$

$\approx \frac{1}{2} \|x\|^2$ Energy



Example (3.5)

$\bar{C}^{-1/2} G C^{-1/2}$ - symmetric, all eigenvalues are real

so are the eigenvalues of $-\bar{C}'G$

choose eigenvalues to be orthogonal

$\begin{matrix} \text{---} \\ \text{---} \end{matrix}$

} cannot build
an oscillator



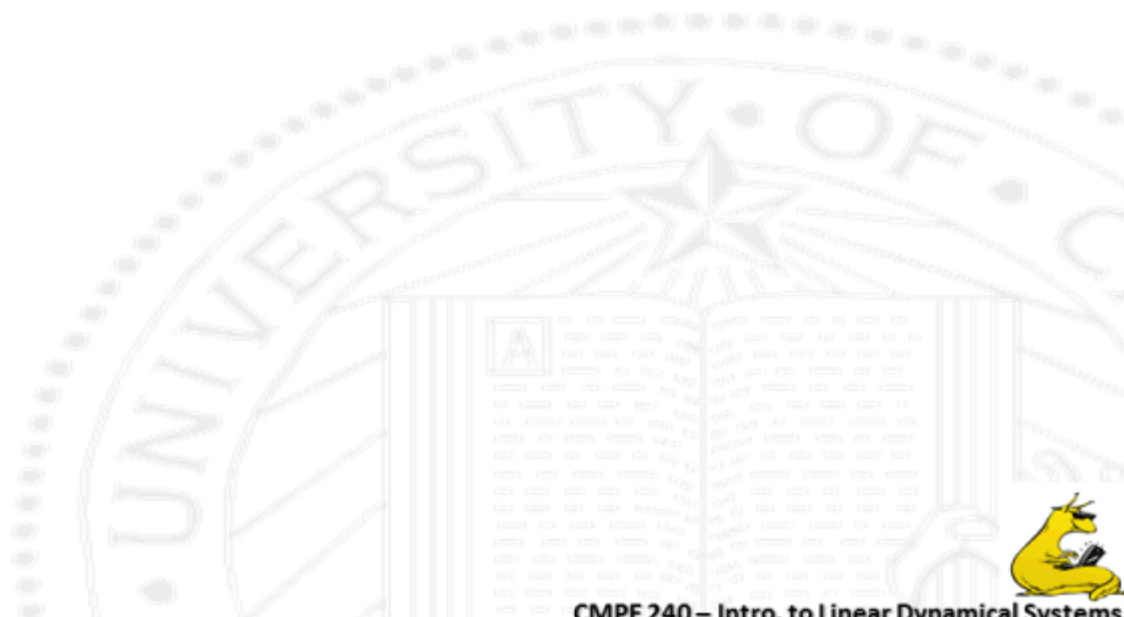
Example (4.5)

$$s_i = C^{-1/2} q_i \quad \text{orthonormal}$$

$$-C^{-1} G s_i = \lambda s_i \quad \longrightarrow \quad s_i \perp s_j \quad s_i^T s_j = \delta_{ij}$$



Example (5.5)



Quadratic Forms (1.3)

$f: \mathbb{R}^n \rightarrow \mathbb{R}$ has the form

$$f(x) = x^T A x = \sum_{i,j=1}^n A_{ij} x_i x_j$$

quadratic form
can assume that $A = A^T$



$$x^T A x = x^T \left(\frac{A + A^T}{2} \right) x$$

symmetric part of A .



Quadratic Forms (2.3)

$$A = \begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix}$$

$$\begin{aligned} x^T A x &= [x_1 \ x_2] \begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = [x_1 \ x_2] \begin{bmatrix} x_1 + 3x_2 \\ 2x_2 \end{bmatrix} \\ &= \underline{x_1^2 + 3x_1 x_2 + 2x_2^2} \end{aligned}$$

$$\frac{A+A^T}{2} = \frac{\begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 3 & 2 \end{bmatrix}}{2} = \begin{bmatrix} 1 & 3/2 \\ 3/2 & 2 \end{bmatrix} \quad x^T \left(\frac{A+A^T}{2} \right) x = [x_1 \ x_2] \begin{bmatrix} 1 & 3/2 \\ 3/2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\begin{aligned} x^T \left(\frac{A+A^T}{2} \right) x &= [x_1 \ x_2] \begin{bmatrix} x_1 + 3/2 x_2 \\ 3/2 x_1 + 2x_2 \end{bmatrix} = x_1^2 + \frac{3}{2} x_1 x_2 + \frac{3}{2} x_1 x_2 + 2x_2^2 \\ &= \underline{x_1^2 + 3x_1 x_2 + 2x_2^2} \end{aligned}$$



Skew symmetric $S^T = -S$

$$[w_x] = \begin{bmatrix} 0 & -w_y & w_z \\ w_y & 0 & -w_x \\ -w_z & w_x & 0 \end{bmatrix}$$

Cross product
matrix

$$x^T S x = x^T (-S^T) x \rightarrow \phi.$$



Quadratic Forms (3.3)

$$\|Bx\|^2 = (Bx)^T(Bx) = x^T \underline{B^T B} x$$

$$\sum_{i=1}^{n-1} (x_{i+1} - x_i)^2 \rightarrow x^T \begin{bmatrix} 1 & -1 & & \\ -1 & 2 & -1 & \\ & -1 & 2 & -1 \\ & & -1 & 1 \end{bmatrix} x$$

already symmetric
measure of how bumpy x is

$$\|Fx\|^2 - \|Gx\|^2 \rightarrow x^T (F^T F - G^T G) x$$



$\{x \mid x^T A x = a\} \rightarrow$ quadratic surface in \mathbb{R}^n

$\{x \mid x^T A x \leq a\} \rightarrow$ quadratic region/volume in \mathbb{R}^n

$\{x \mid x^T x = 1\} \leftarrow$ unit hypersphere in \mathbb{R}^n

$\{x \mid x^T x \leq 1\} \leftarrow$ unit ball.



$$f(x) \doteq x^T A x$$



$$y = Ax$$
$$e_i \rightarrow \boxed{A} \rightarrow a_i \begin{bmatrix} \vdots \end{bmatrix}$$

$$f(e_i) = e_i^T A e_i = A_{ii}$$

$$f(e_i + e_j) = (e_i + e_j)^T A (e_i + e_j) = A_{ii} + 2A_{ij} + A_{jj}$$



Inequalities for Quadratic Forms (1.3)

$$A = A^T \in \mathbb{R}^{n \times n} \quad \Lambda = Q \Lambda Q^T$$

by jst $\rightarrow \lambda_1 \geq \lambda_2 \dots \geq \lambda_n \leftarrow$ smallest

$$x^T A x = x^T Q \Lambda Q^T x = (Q^T x)^T \Lambda (Q^T x)$$

$$y = Q^T x$$

$$= y^T \Lambda y = \sum_{i=1}^n \lambda_i y_i^2$$

$$= \sum_{i=1}^n \lambda_i (q_i^T x)^2$$

$$\|Q^T x\|^2 = \|x\|^2$$

$$\lambda_1 \|x\|^2 \geq x^T A x \geq \lambda_n \|x\|^2$$



Inequalities for Quadratic Forms (2.3)

$$\lambda_{\max} \|x\|^2 \geq x^T A x \geq \lambda_{\min} \|x\|^2$$

$$q_1^T A q_1 = \lambda_{\max} \|q_1\|^2 = \lambda_{\max}$$

$$q_n^T A q_n = \lambda_{\min} \|q_n\|^2 = \lambda_{\min}$$

Gain in quadratic form

$\frac{x^T A x}{\|x\|^2} \triangleq$ Rayleigh quotient

$$\lambda_{\max} \geq \frac{x^T A x}{x^T x} \geq \lambda_{\min}$$



Inequalities for Quadratic Forms (3.3)

$$A = A^T \in \mathbb{R}^{n \times n}$$

A is positive ^{semi} definite if $x^T A x \geq 0 \forall x$

$$A \geq 0$$

$$\min \text{ eig} \left(\frac{A^T + A}{2} \right) \geq 0$$

$A \geq 0$ if and only if $\lambda_{\min}(A) \geq 0$



Positive semi-definite and Positive definite matrices

(1.3)

$A \leq 0$ negative semi-definite $-A \geq 0$

$A < 0$ negative definite $-A > 0$

A is indefinite



Positive semi-definite and Positive definite matrices

(2.3)

$$\text{if } B = B^T \in \mathbb{R}^{n \times n}$$

$$A \geq B \text{ if } \underline{(A-B) \geq 0} \text{ . positive semi-definite}$$

$$A < B \text{ — } (A-B) < 0 \text{ or } (B-A) > 0$$

$$\underline{A > B \text{ — } x^T A x > x^T B x \quad \forall x \neq 0 .}$$



Positive semi-definite and Positive definite matrices

(3.3)

$$A \geq B \quad C \geq D \rightarrow A+C \geq B+D$$

$$B \leq 0 \rightarrow A+B \leq A$$

$$A \geq 0, \alpha \geq 0 \rightarrow \alpha A \geq 0.$$

$$A \geq 0 \rightarrow A^2 \geq 0$$

$$A > 0 \rightarrow A^{-1} > 0$$

$$A \geq B \not\rightarrow B \geq A$$

$$\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \stackrel{?}{\geq} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$

"incomparable"

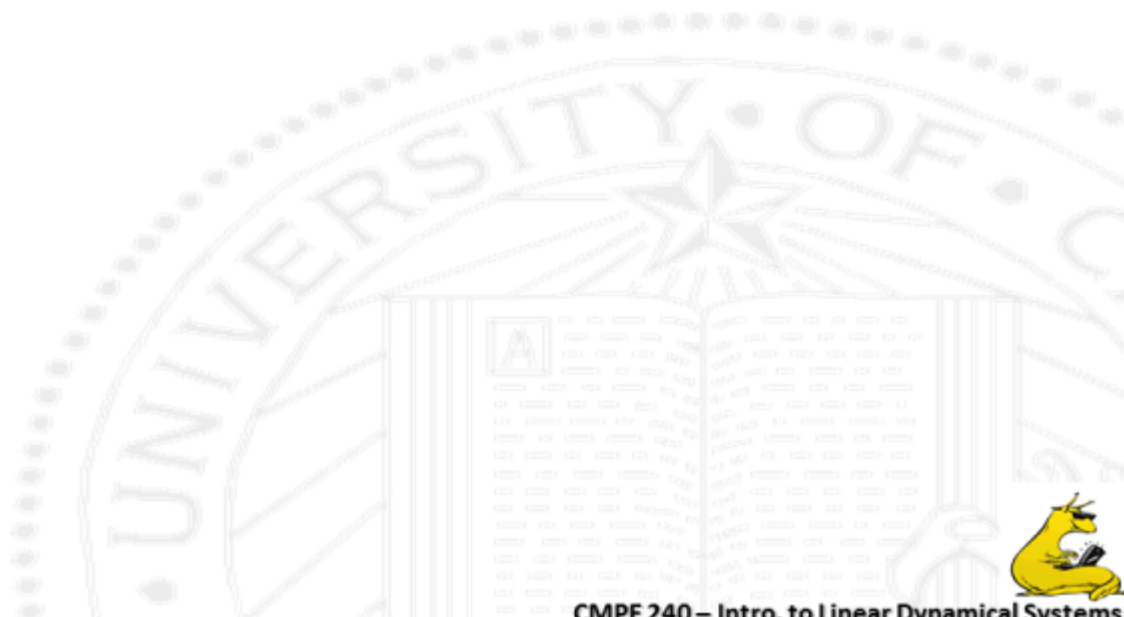


Matrix Inequalities (1.3)

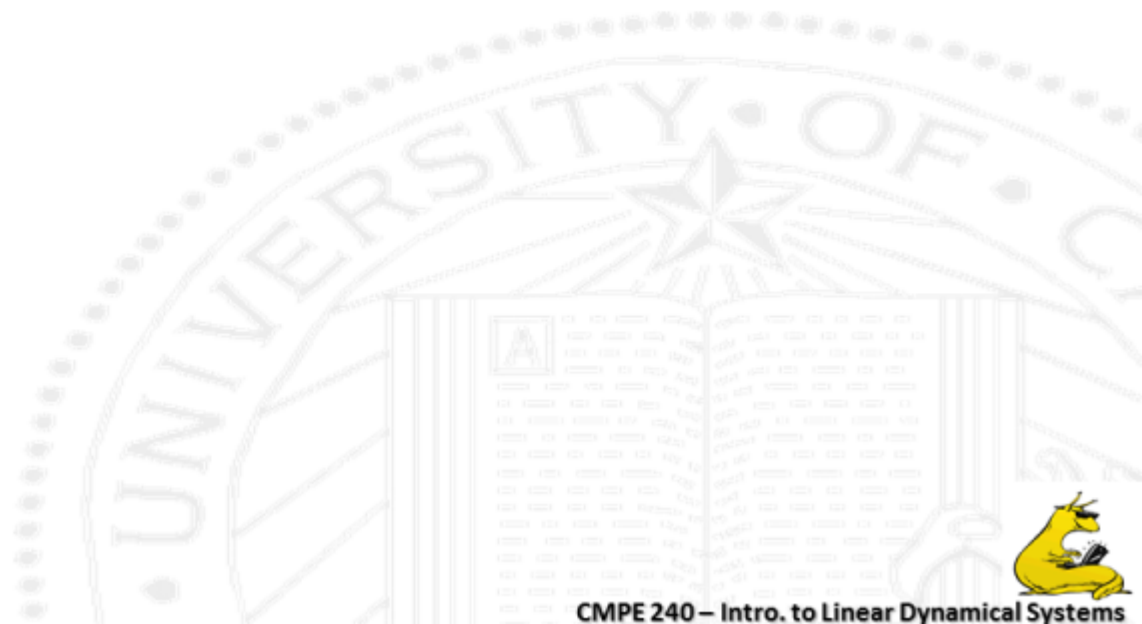
$$x^T A x \leq 1 \rightarrow x^T A^{-1} x \leq 1$$



Matrix Inequalities (2.3)



Matrix Inequalities (3.3)

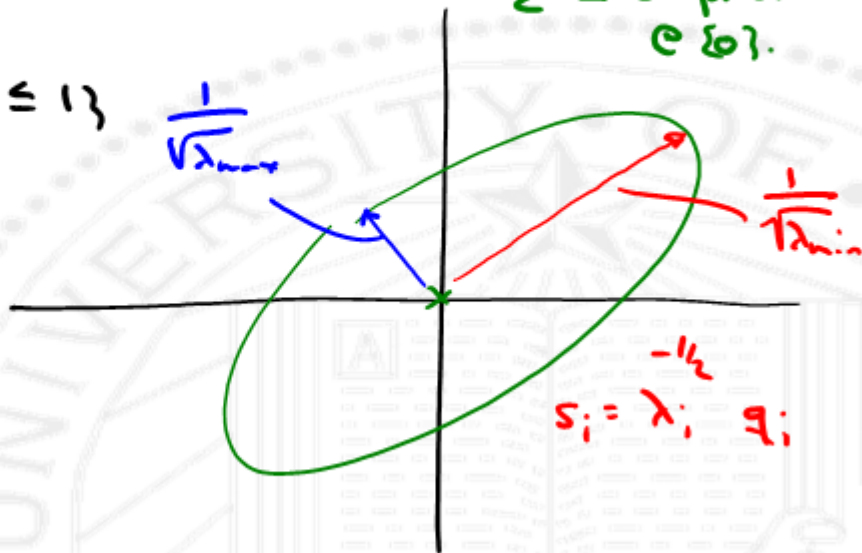


Ellipsoids (1.3)

$$A = A^T > 0$$

$$\Sigma \triangleq \{x \mid x^T A x \leq 1\}$$

$\Sigma \triangleq$ ellipsoid centered @ $\{0\}$.



Ellipsoids (2.3)

eigenvalues - length of semi-major axes

eigenvectors - direction of the semi-major axes

$$\delta_i = \lambda_i^{-1/2} q_i$$

q_1 $x^T K x$ is large elliptical is THIN in that direction

q_n $x^T K x$ is small elliptical is FAT in that direction

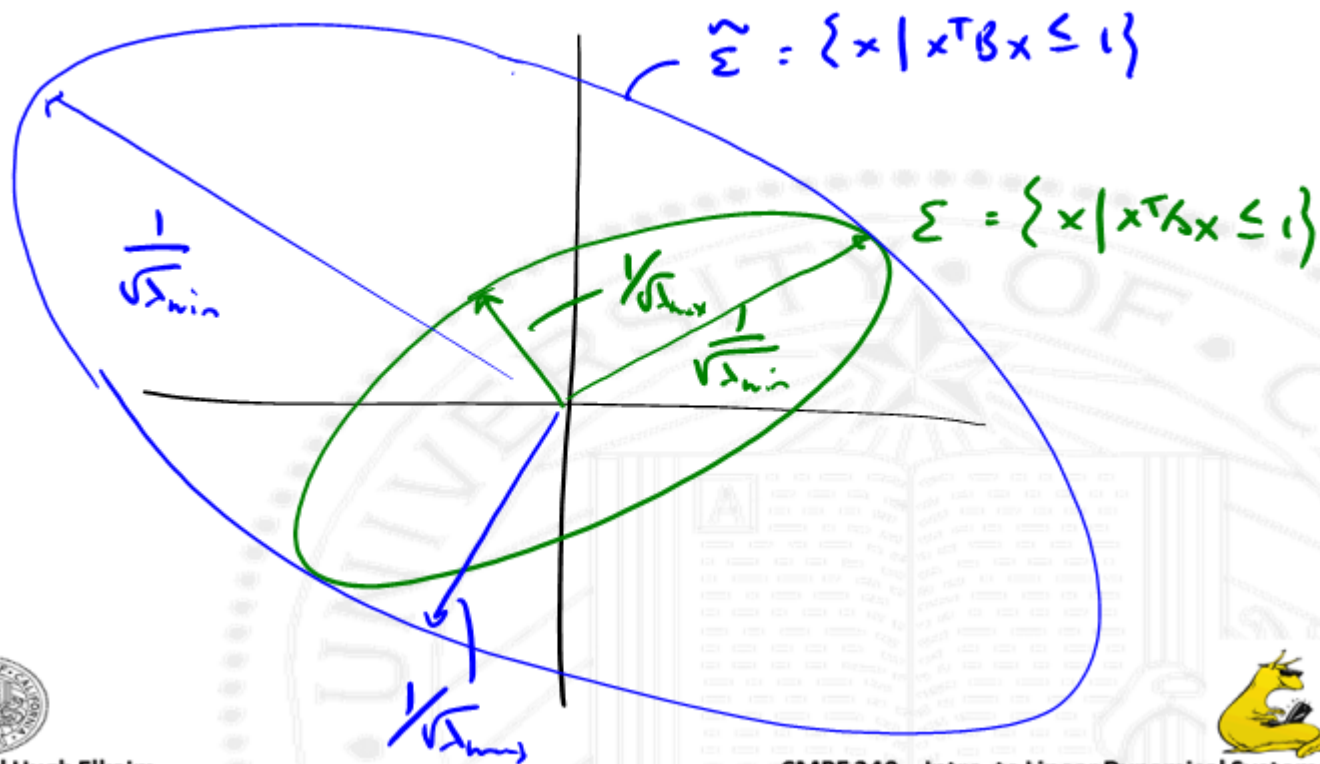


Ellipsoids (3.3)

$\sqrt{\frac{\lambda_{\max}}{\lambda_{\min}}} \triangleq$ maximum eccentricity of A
"condition number"

$$\tilde{\Sigma} = \{ x \mid x^T B x \leq 1 \} \quad B > 0 \quad \Sigma \subseteq \tilde{\Sigma} \quad A \geq B$$





Gain of a Matrix in a Direction (1.3)

$A \in \mathbb{R}^{m \times n}$ not necessarily square or symmetric

$y = Ax$ $x \in \mathbb{R}^n$ $\frac{\|Ax\|}{\|x\|}$ gives an amplification factor.

gain of the matrix A in the direction x .



Gain of a Matrix in a Direction (2.3)

$$\max \frac{\|Ax\|}{\|x\|} \quad x \neq 0.$$

Spectral norm of A .

L_2 norm of A

$$\lambda_{\max}(A^T A)$$

$$\|A\|_2$$



Gain of a Matrix in a Direction (3.3)

$$\max_x \frac{\|Ax\|}{\|x\|} = \lambda_{\max}(A^T A) \quad \begin{matrix} A \in \mathbb{R}^{m \times n} \\ x \in \mathbb{R}^n \end{matrix}$$

subj: $x \neq 0$

Norm of a matrix



$$\sqrt{\lambda_{\max}(A^T A)} \geq \|A\| \geq \sqrt{\lambda_{\min}(A^T A)}$$

$A^T A \in \mathbb{R}^{n \times n}$ is symmetric and square $A^T A \succeq 0$.

so that $\lambda_{\max}, \lambda_{\min} \geq 0$.

max gain $x = q_1$ eig $(A^T A)$ with λ_1

min gain $x = q_n$ eig $(A^T A)$ with λ_n



Matrix Norm (1.4)

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$$

$$e_1 \rightarrow x^T A x \sim 6$$

$$e_2 \rightarrow x^T A x \sim 7$$

$$A^T A = \begin{bmatrix} 36 & 49 \\ 49 & 52 \end{bmatrix} \rightarrow \begin{bmatrix} 0.62 & 0.785 \\ 0.785 & -0.62 \end{bmatrix} \begin{bmatrix} 9.53 & 0 \\ 0 & 0.265 \end{bmatrix} \begin{bmatrix} Q^T \end{bmatrix}$$

$$\|A\| = \sqrt{\lambda_{\max}(A^T A)} = \underline{9.53}$$

$$x = \begin{bmatrix} 0.785 \\ -0.62 \end{bmatrix} \rightarrow \|x\|=1 \rightarrow \|Ax\| \approx 0.5$$

$$x = \begin{bmatrix} 0.62 \\ 0.785 \end{bmatrix} \rightarrow \|x\|=1 \rightarrow \|Ax\| \approx 9.53$$



Matrix Norm (2.4)

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$$

$$0.54 \leq \|A\| \leq 9.53$$

$$x = \begin{bmatrix} 0.785 \\ -0.62 \end{bmatrix}$$

$$\begin{bmatrix} 0.62 \\ 0.785 \end{bmatrix}$$



Matrix Norm (3.4)

consistent with vector norm

$$a \in \mathbb{R}^{n \times 1} \rightarrow \sqrt{\lambda_{\max}(a^T a)} = \sqrt{a^T a} = \|a\|.$$

For any x $\|Ax\| \leq \|A\| \|x\|$. ← along direction of eig($A^T A$).



Matrix Norm (4.4)

$$\| \alpha A \| = |\alpha| \| A \|$$

$$\| A + B \| \leq \| A \| + \| B \|$$

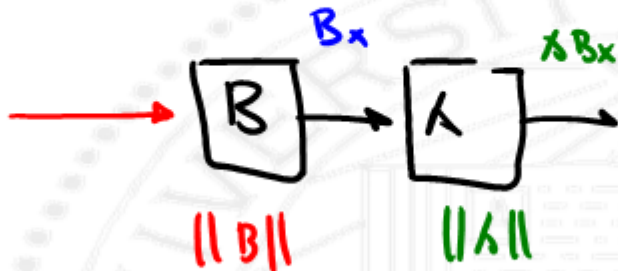
$$\| A \| = 0 \rightarrow A = 0.$$

$$\| AB \| \leq \| A \| \cdot \| B \|$$



Properties of Matrix Norm (1.3)

geometric interpretation $\|AB\| \leq \|A\| \cdot \|B\|$



$$\frac{x^T (AB)^T (AB) x}{x^T x}$$



Properties of Matrix Norm (2.3)

$$A \in \mathbb{R}^{n \times n}$$

$$\longrightarrow A = T \Lambda T^{-1} \text{ eigenbasis/eigenvalues}$$

$$A = A^T \in \mathbb{R}^{n \times n}$$

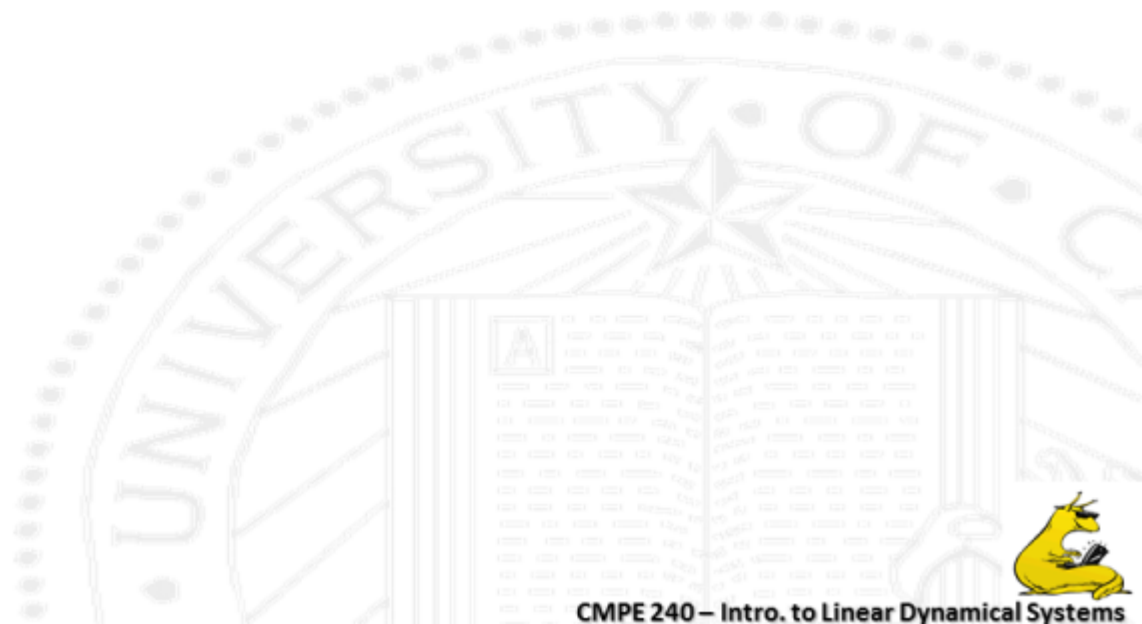
$$\longrightarrow A = Q \Lambda Q^T \text{ , orthonormal eigenbasis}$$

$$A \in \mathbb{R}^{m \times n}$$

$$\longrightarrow \text{SVD: } A = U \Sigma V^T$$



Properties of Matrix Norm (3.3)



Singular Value Decomposition (1.3)

SVD of $A \in \mathbb{R}^{m \times n}$

$$A = U \Sigma V^T$$

$$A \in \mathbb{R}^{m \times n}$$

$$\text{rank}(A) = r$$

$$U \in \mathbb{R}^{m \times r}$$

$$U^T U = I_{r \times r}$$

$$V \in \mathbb{R}^{n \times r}$$

$$V^T V = I_{r \times r}$$

$$\Sigma = \begin{bmatrix} \sigma_1 & & & & & \\ & \ddots & & & & \\ & & \ddots & & & \\ & & & \ddots & & \\ & & & & \ddots & \\ & & & & & \sigma_r & & \\ & & & & & & & 0 & & \\ & & & & & & & & & \ddots \\ & & & & & & & & & & 0 \end{bmatrix}$$

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r$$

SINGULAR VALUES of A \rightarrow



Singular Value Decomposition (2.3)

$$\begin{array}{c} \leftarrow n \rightarrow \\ \uparrow m \\ \left[\begin{array}{c} A \end{array} \right] \\ \downarrow m \end{array} = \begin{array}{c} \leftarrow r \rightarrow \\ \uparrow m \\ \left[\begin{array}{c} U \end{array} \right] \\ \downarrow m \end{array} \begin{array}{c} \leftarrow r, r \rightarrow \\ \uparrow r \\ \left[\begin{array}{c} \Sigma \end{array} \right] \\ \downarrow r \end{array} \begin{array}{c} \leftarrow n \rightarrow \\ \uparrow r \\ \left[\begin{array}{c} V^T \end{array} \right] \\ \downarrow r \end{array} \sim \lambda_i v_i v_i^T
 \end{array}$$

$$U = [u_1 \dots u_r] \quad u_i \in \mathbb{R}^m$$

$$V = [v_1 \dots v_r] \quad v_i \in \mathbb{R}^n$$

$$A = U \Sigma V^T = \sum_{i=1}^r \sigma_i u_i v_i^T$$

rank 1 matrix



Singular Value Decomposition (3.3)

$\sigma_i \triangleq$ singular value of A .

$v_i \triangleq$ right (input) singular vector of A

$u_i \triangleq$ left (output) singular vector of A

$$A^T A = (U \Sigma V^T)^T (U \Sigma V^T) = V \Sigma \underbrace{U^T U}_{I} \Sigma V^T = \underline{V \Sigma^2 V^T}$$

$v_i \triangleq$ eigenvectors of $A^T A$ corresponding to non-zero λ 's.

$$\sigma_i \triangleq \sqrt{\lambda_i(A^T A)} \quad \lambda_i(A^T A) = 0 \quad \forall i > r.$$



Interpretations (1.3)

$$AA^T = (U\Sigma V^D)(U\Sigma V^T)^T = U\Sigma V^T V \Sigma U^T = \underline{U\Sigma^2 U^T}$$

$u_i \triangleq$ eigenvectors of AA^T associated with non-zero λ 's.

$$\text{eig}(AB) = \text{eig}(BA)$$

$$\sigma_i = \sqrt{\lambda_i(AA^T)} \quad \leftarrow \quad \lambda_i(AA^T) = 0 \quad \forall i > n.$$



Interpretations (2.3)

u_i - eigenvectors of (AA^T) LEFT/OUTPUT directions

v_i - eigenvectors of $(A^T A)$ RIGHT/INPUT directions

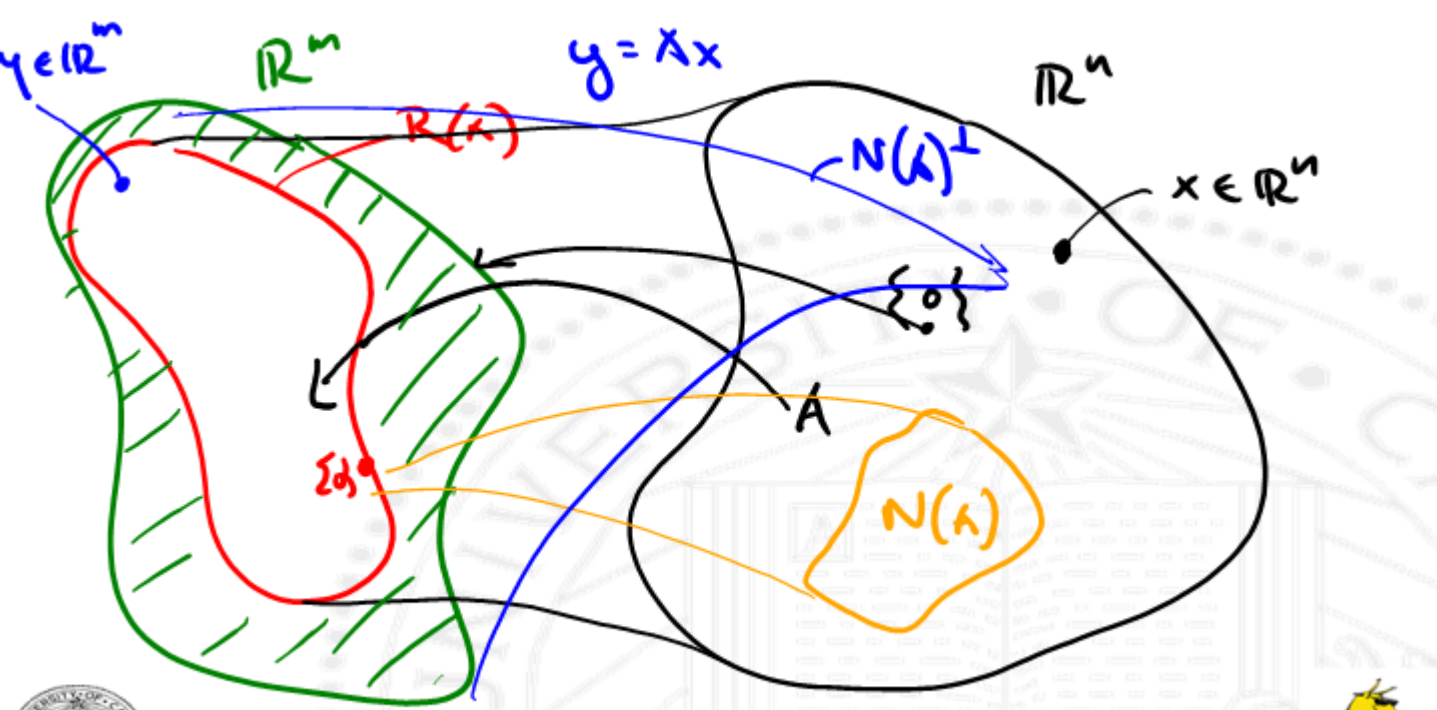
σ_i - eigenvalues of $(A^T A)$ or (AA^T) up to rank of A .

$$\sqrt{\lambda_i(A^T A)} = \sqrt{\lambda_i(AA^T)}$$

$[u_1 \dots u_r]$ - orthonormal basis for $R(A)$

$[v_1 \dots v_r]$ - orthonormal basis for $N(A)^\perp$





Interpretations (3.3)

$$R(\bar{v}) = R(A)$$

$$N(A)^\perp = R(\bar{v})$$

Any linear mapping

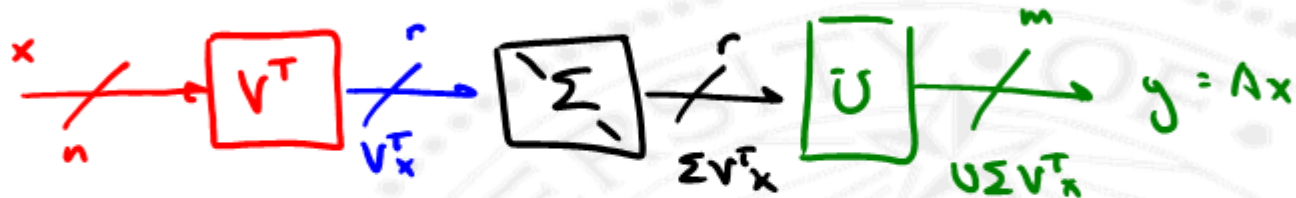
$$y = Ax$$

$$y \in \mathbb{R}^m \quad x \in \mathbb{R}^n$$



$$A = U \Sigma V^T = \sum_{i=1}^r \sigma_i u_i v_i^T$$

$$y = Ax$$



Reshape x
into v input
directions

Dilate
along
coordinate
axes

Reshape the
results along
the output
directions



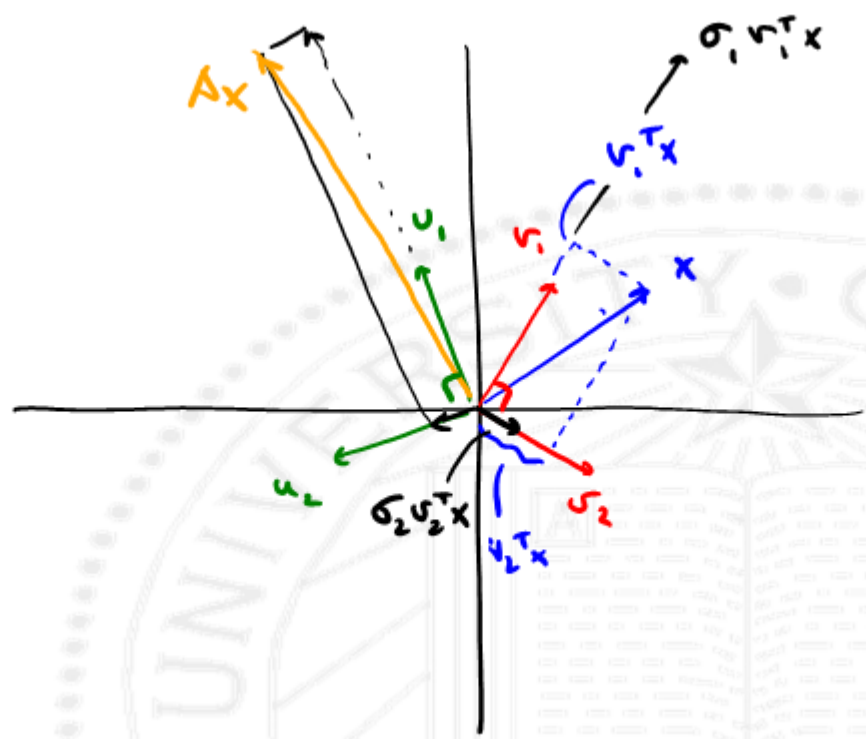
(1) Compute coefficient of x along each input direction

(2) Scale that coefficient by σ_i

(3) Reconstruct y along the output directions



$A \in \mathbb{R}^{2 \times 2}$



Questions?





Gabriel Hugh Elkaim



CMPE 240 – Intro. to Linear Dynamical Systems