

II A famous example, the van der Pol oscillator

① The model

The Van-der-Pol oscillator is one of the most famous examples of a nonlinear oscillator to have a stable limit cycle.

It is used to model many systems in engineering (electric circuits, ...), biological systems (circadian clocks, nervous firing ...), chemistry, etc...

General form of the equation:

$$\frac{d^2 f}{dt^2} + f = \varepsilon(1 - f^2) \frac{df}{dt}$$

note the nonlinear "damping" term.

- for small f , $\sim \varepsilon \frac{df}{dt}$
→ exponential amplification
- for large f $\sim -\varepsilon f^2 \frac{df}{dt}$
→ strong nonlinear damping.

→ We expect f to be amplified until its amplitude reaches about 1, then to stay at that amplitude because of competition between amplification & damping.

→ The oscillator is expected to have a limit cycle, the question is, can we determine what this cycle is?

From here on we assume as initial conditions

$$f(0) = h$$

$$\frac{df}{dt}(0) = 0$$

② Multiscale analysis

Let $T_0 = t$ and $T_1 = \epsilon t$

We saw last chapter that

$$\frac{\partial}{\partial t} = \frac{\partial}{\partial T_0} + \epsilon \frac{\partial}{\partial T_1}$$

$$\frac{\partial^2}{\partial t^2} = \frac{\partial^2}{\partial T_0^2} + 2\epsilon \frac{\partial^2}{\partial T_0 \partial T_1} + \epsilon^2 \frac{\partial^2}{\partial T_1^2}$$

We let $f = f_0 + \epsilon f_1 + \dots$

$$\begin{aligned} \Rightarrow & \left(\frac{\partial^2}{\partial T_0^2} + 2\epsilon \frac{\partial^2}{\partial T_1 \partial T_0} + \epsilon^2 \frac{\partial^2}{\partial T_1^2} \right) (f_0 + \epsilon f_1 + \dots) + (f_0 + \epsilon f_1 + \dots) \\ & = \epsilon (1 - (f_0 + \epsilon f_1 + \dots)^2) \left(\frac{\partial}{\partial T_0} + \epsilon \frac{\partial}{\partial T_1} \right) (f_0 + \epsilon f_1 + \dots) \\ & = \epsilon (1 - f_0^2 - 2\epsilon f_0 f_1 - \epsilon^2 (f_1^2 + 2f_0 f_2 + \dots)) \left(\frac{\partial f_0}{\partial T_0} + \epsilon \left(\frac{\partial f_1}{\partial T_0} + \frac{\partial f_0}{\partial T_1} \right) \right) \end{aligned}$$

So to 0th order we have:

$$\begin{cases} \frac{\partial^2 f_0}{\partial T_0^2} + f_0 = 0 \\ f_0(0,0) = h \\ \frac{\partial f_0}{\partial T_0}(0,0) = 0 \end{cases} \quad \begin{array}{l} \text{as before} \\ \rightarrow \\ \text{with } \begin{cases} A_0(0) = h \\ B_0(0) = 0 \end{cases} \end{array}$$

$$f_0(T_0, T_1) = A_0(T_1) \cos T_0 + B_0(T_1) \sin T_0$$

to 1st order, we have

$$\begin{cases} \frac{\partial^2 f_1}{\partial T_0^2} + f_1 = -2 \frac{\partial^2 f_0}{\partial T_0 \partial T_1} + (1 - f_0^2) \frac{\partial f_0}{\partial T_0} \\ f_1(0,0) = 0 \\ \frac{\partial f_1}{\partial T_0} + \frac{\partial f_0}{\partial T_1} = 0 \end{cases}$$

The equation itself has a RHS that reads

$$-2 \left(-\frac{\partial A_0}{\partial T_1} \sin T_0 + \frac{\partial B_0}{\partial T_1} \cos T_0 \right) + (1 - (A_0 \cos T_0 + B_0 \sin T_0)^2) (-A_0 \sin T_0 + B_0 \cos T_0)$$

$$\begin{aligned} &\Rightarrow 2 \left(\frac{\partial A_0}{\partial T_1} \sin T_0 - \frac{\partial B_0}{\partial T_1} \cos T_0 \right) \\ &+ \left(1 - A_0^2 \cos^2 T_0 - 2A_0 B_0 \cos T_0 \sin T_0 - B_0^2 \sin^2 T_0 \right) (B_0 \cos T_0 - A_0 \sin T_0) \\ &= 2 \left(\frac{\partial A_0}{\partial T_1} \sin T_0 - \frac{\partial B_0}{\partial T_1} \cos T_0 \right) \\ &+ B_0 \cos T_0 - A_0 \sin T_0 - A_0^2 B_0 \cos^3 T_0 + A_0^3 \cos^2 T_0 \sin T_0 \\ &- 2A_0 B_0^2 \cos^2 T_0 \sin T_0 + 2A_0^2 B_0 \cos T_0 \sin^2 T_0 + A_0 B_0^2 \sin^3 T_0 - B_0^3 \sin^2 T_0 \cos T_0 \\ &= \cancel{2 \left[\frac{\partial A_0}{\partial T_1} \sin T_0 - \frac{\partial B_0}{\partial T_1} \cos T_0 \right]} + \cancel{B_0 \cos T_0 - A_0 \sin T_0} \\ &+ \cancel{A_0^2 B_0 \cos^2 T_0 \sin T_0 - A_0 B_0^2 \cos T_0 \sin^2 T_0} \\ &+ \cancel{A_0^3 \cos^3 T_0 - B_0^3 \sin^3 T_0} \end{aligned}$$

Now $\cos^2 T_0 \sin T_0 = \frac{1}{2} (1 + \cos 2T_0) \sin T_0$
 $= \frac{1}{4} \sin T_0 + \frac{1}{4} \sin 3T_0$

similarly, $\cos T_0 \sin^2 T_0 = \frac{1}{4} (\cos T_0 - \cos 3T_0)$

$\cos^3 T_0 = \frac{3}{4} \cos T_0 + \frac{1}{4} \cos 3T_0$, $\sin^3 T_0 = \frac{3}{4} \sin T_0 - \frac{1}{4} \sin 3T_0$

→ the terms that would lead to secular terms in f_0 are:

$$\begin{aligned} &2 \left[\frac{\partial A_0}{\partial T_1} \sin T_0 - \frac{\partial B_0}{\partial T_1} \cos T_0 \right] + B_0 \cos T_0 - A_0 \sin T_0 - \frac{3}{4} A_0^2 B_0 \cos T_0 \\ &+ \frac{A_0^3}{4} \sin T_0 - \frac{A_0 B_0^2}{2} \sin T_0 + \frac{A_0^2 B_0}{2} \cos T_0 + \frac{3}{4} A_0 B_0^2 \sin T_0 - \frac{B_0^3}{4} \cos T_0 \end{aligned}$$

To eliminate them, let

$$\left. \begin{aligned} &2 \frac{\partial A_0}{\partial T_1} - A_0 + \frac{A_0^3}{4} + \frac{A_0 B_0^2}{4} = 0 \quad (1) \\ &-2 \frac{\partial B_0}{\partial T_1} + B_0 - \frac{A_0^2 B_0}{4} - \frac{B_0^3}{4} = 0 \quad (2) \end{aligned} \right\} \begin{array}{l} \text{The compatibility} \\ \text{condition for} \\ A_0(T_1) \text{ and } B_0(T_1) \end{array}$$

→ 2 coupled nonlinear equations... this seems untractable!?

In fact, there is a much better way of dealing with the problem that will lead to an analytical solution without having to use all these nasty trig identities. 12.

Idea: use the exponential notation for f_0 .

we had $f_0(t_0, t_1) = A_0(t_1) \cos t_0 + B_0(t_1) \sin t_0$
 \rightarrow rewrite as $f_0(t_0, t_1) = A_0(t_1) e^{it_0} + A_0^*(t_1) e^{-it_0}$
 $= \text{Re}(A_0(t_1) e^{it_0})$

The RHS of the equation for f_1 then becomes:

$$\begin{aligned}
 & -2 \frac{\partial^2 f_0}{\partial t_0 \partial t_1} + (1 - f_0^2) \frac{\partial f_0}{\partial t_0} \\
 &= -2 \left[i \frac{dA_0}{dt_1} e^{it_0} - i \frac{dA_0^*}{dt_1} e^{-it_0} \right] \\
 &+ \left[1 - A_0^2 e^{2it_0} - 2A_0 A_0^* - A_0^{*2} e^{-2it_0} \right] \left(i A_0 e^{it_0} - i A_0^* e^{-it_0} \right) \\
 &= -2i \left[\frac{dA_0}{dt_1} e^{it_0} - \frac{dA_0^*}{dt_1} e^{-it_0} \right] + i (1 - 2A_0 A_0^*) (A_0 e^{it_0} - A_0^* e^{-it_0}) \\
 &- i A_0^3 e^{3it_0} + i A_0^2 A_0^* e^{it_0} - i A_0^{*2} A_0 e^{-it_0} + A_0^{*3} e^{-3it_0}
 \end{aligned}$$

To eliminate all source of secular term, we simply need to set:

$$\begin{cases}
 -2i \frac{dA_0}{dt_1} + i A_0 (1 - 2A_0 A_0^*) + i A_0^2 A_0^* = 0 \\
 2i \frac{dA_0^*}{dt_1} - i A_0^* (1 - 2A_0 A_0^*) - i A_0^{*2} A_0 = 0
 \end{cases}$$

Since $A_0 A_0^* = |A_0|^2$, we recognize the second equation as the c.c. of the first. The latter simplifies as:

$$\begin{aligned}
 & -2 \frac{dA_0}{dt_1} + A_0 - A_0^2 A_0^* = 0 \\
 \Rightarrow & \frac{dA_0}{dt_1} = \frac{1}{2} A_0 (1 - |A_0|^2)
 \end{aligned}$$

Thus, incidentally, is also a set of coupled nonlinear ODEs (say, one for $\text{Re}(A_0)$ and one for $\text{Im}(A_0)$), but if we write $A_0 = |A_0|e^{i\theta}$ (polar argument form) then

$$\frac{d}{dt_1} (|A_0|e^{i\theta}) = \frac{1}{2}|A_0|e^{i\theta} (1 - |A_0|^2)$$

$$\rightarrow \frac{d|A_0|}{dt_1} e^{i\theta} + i \frac{d\theta}{dt_1} |A_0| = \frac{1}{2}|A_0|e^{i\theta} (1 - |A_0|^2)$$

we see that a solution can be obtained if

$$\begin{cases} \frac{d|A_0|}{dt_1} = \frac{1}{2}|A_0|(1 - |A_0|^2) & \leftarrow \text{this is now a single nonlinear ODE} \\ \frac{d\theta}{dt_1} = 0 & \leftarrow \text{this has the simple solution } \theta = \text{constant} \end{cases}$$

To solve the equation for the norm, note that it is separable: \Rightarrow

$$\frac{d|A_0|}{|A_0|(1 - |A_0|^2)} = \frac{dt_1}{2}$$

Using integral tables (or otherwise) we get

$$\ln \left| \frac{|A_0|^2}{1 - |A_0|^2} \right| = \frac{t_1}{2} + C \quad \leftarrow C \text{ obtained from initial conditions}$$

- Since, at $t_1 = 0$, we need $f_0(0,0) = h$, that is $A_0(0)e^0 + A_0^*(0)e^0 = h \Rightarrow 2\text{Re} A_0 = h$ so

$$|A_0| = \frac{h}{2} \text{ at time } t_1 = 0$$

- with $\frac{\partial f_0}{\partial t_0} = 0 \rightarrow iA_0(0)e^0 - iA_0^*(0)e^0 = 0$
 $\Rightarrow A_0(0) = A_0^*(0) \Rightarrow A_0$ is real.

This implies: $\begin{cases} \theta(0) = 0 \text{ and} \\ |A_0|(0) = \frac{h}{2} \end{cases}$

Plugging this in, we get:

$$\frac{1}{2} \ln \left| \frac{\frac{h^2}{4}}{1 - \frac{h^2}{4}} \right| = 0 + C \Rightarrow C = \ln \sqrt{\frac{h^2}{|4-h^2|}}$$

$$\text{So } \ln \sqrt{\frac{|A_0|^2}{|1-|A_0|^2|}} = \frac{T_1}{2} + \ln \sqrt{\frac{h^2}{|4-h^2|}}$$

$$\Rightarrow \frac{|A_0|^2}{|1-|A_0|^2|} = e^{T_1} \cdot \frac{h^2}{|4-h^2|}$$

This leaves 2 possibilities:

• if $|A_0| < 1$ then:

$$\frac{|A_0|^2}{1-|A_0|^2} = e^{T_1} \frac{h^2}{|4-h^2|}$$

$$\Rightarrow |A_0|^2 = \frac{e^{T_1} \frac{h^2}{|4-h^2|}}{1 + e^{T_1} \frac{h^2}{|4-h^2|}} = \frac{1}{1 + \frac{|4-h^2|}{h^2} e^{-T_1}} \text{ which is always } < 1$$

• if $|A_0| > 1$ then:

$$\frac{|A_0|^2}{|A_0|^2-1} = e^{T_1} \frac{h^2}{|4-h^2|}$$

$$\Rightarrow |A_0|^2 = \frac{1}{1 - \frac{|4-h^2|}{h^2} e^{-T_1}} \text{ which is always } > 1.$$

So finally, we get that: A_0 is real, and $|A_0|$ is given above

$$\begin{aligned} \Rightarrow f_0(t_0, T_1) &= A_0(t_1) e^{it_0} + A_0^*(t_1) e^{-it_0} \\ &= A_0(t_1) (e^{it_0} + e^{-it_0}) \\ &= 2A_0(t_1) \cos t_0 = \frac{2 \cos t_0}{\sqrt{1 \pm \frac{|4-h^2|}{h^2} e^{-T_1}}} \Rightarrow \end{aligned}$$

The correct multiscale expansion for $f(t)$ is (to lowest order in ϵ), 15.

$$f(t) = \frac{2\omega_0 t}{\sqrt{1 \pm \frac{14-h^2}{h^2}} e^{-\epsilon t}}$$

where \pm depends on the size of A_0 .

Note that, as $t \rightarrow \infty$, $f(t) \rightarrow 2\omega_0 t$.

This is not entirely intuitive: based on the simple argument given in the introduction, we might have expected to have $f(t) \rightarrow \omega_0 t$ instead...

However, this is indeed the correct solution.

Its physical interpretation is that the oscillator spends some time of the period being amplified (when $f(t) < 1$) and some time being damped (when $f(t) > 1$), resulting in an overall stable oscillation.

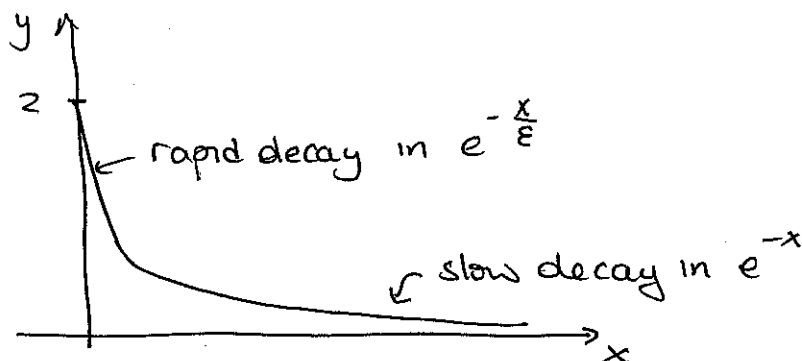
The multi-scale expansion doesn't just apply to oscillators. We now study 2 more examples that also exhibit multi-scale properties without being oscillators.

16. III Examples of multi-scale analysis for singular problems

① Recall the problem from Chapter I:

$$\begin{cases} \varepsilon \frac{dy}{dx} + y = e^{-x} \\ y(0) = 2 \end{cases}$$

We saw that this problem had a boundary layer;



In this case, the multiscale method also works.

This time our "fast variable" is $X_0 = \frac{x}{\varepsilon}$ while our "slow" variable is $X_1 = x$

$$\begin{aligned} \text{In that case } \frac{d}{dx} &= \frac{dX_0}{dx} \frac{\partial}{\partial X_0} + \frac{dX_1}{dx} \frac{\partial}{\partial X_1} \\ &= \frac{1}{\varepsilon} \frac{\partial}{\partial X_0} + \frac{\partial}{\partial X_1} \end{aligned}$$

$$\Rightarrow \text{let } y = y_0 + \varepsilon y_1 + \dots$$

Then we have

$$\begin{cases} \varepsilon \left(\frac{1}{\varepsilon} \frac{\partial}{\partial X_0} + \frac{\partial}{\partial X_1} \right) (y_0 + \varepsilon y_1 + \dots) + (y_0 + \varepsilon y_1 + \dots) = e^{-X_1} \\ y(0, 0) = 2 \end{cases}$$

→ To zeroth order in ε we get

$$\begin{cases} \frac{\partial y_0}{\partial X_0} + y_0 = e^{-X_1} \\ y_0(0, 0) = 2 \end{cases}$$

Since this is a partial differential equation, x_1 is "fixed" when we vary x_0 . The solution is therefore

$$y_0(x_0, x_1) = e^{-x_1} + A_0(x_1) e^{-x_0}$$

where the amplitude $A(x_1)$ remains TBD, but satisfies $y_0(0, 0) = 2 = 1 + A_0(0) \Rightarrow A_0(0) = 1$

To the next order we have

$$\Rightarrow \begin{cases} \frac{\partial y_0}{\partial x_1} + \frac{\partial y_1}{\partial x_0} + y_1 = 0 \\ y_1(0, 0) = 0 \end{cases}$$

$$\Rightarrow \frac{\partial y_1}{\partial x_0} + y_1 = - \left(-e^{-x_1} + \frac{\partial A_0}{\partial x_1} e^{-x_0} \right)$$

$$= e^{-x_1} + \frac{\partial A_0}{\partial x_1} e^{-x_0}$$

To satisfy the compatibility condition, we must not have any term on the RHS that could lead to secular terms in $x_0 \Rightarrow$ we need $\frac{\partial A_0}{\partial x_1} = 0$

This then implies $A_0(x_1) = \text{const} = A_0(0) = 1$

So finally, to the lowest order,

$$y(x) \cong y_0(x_0, x_1) = e^{-x_0} + e^{-x_1}$$

$$\cong e^{-\frac{x}{\varepsilon}} + e^{-x} + \text{h.o.t.}$$

| exact

Comparing this with the solution we had

$$y(x) = \frac{1-2\varepsilon}{1-\varepsilon} e^{-\frac{x}{\varepsilon}} + \frac{e^{-x}}{1-\varepsilon}$$

we see that $y(x) = e^{-\frac{x}{\varepsilon}} + e^{-x}$ is indeed

the correct uniform expansion at this order!

② Another example, this time a 2pt BVP

This method also works for some boundary-value problems, but this time with a lot of care

$$\text{Consider } \begin{cases} \epsilon \frac{d^2 y}{dx^2} + \frac{dy}{dx} + y = 0 \\ y(0) = 0 \\ y(1) = 1 \end{cases}$$

Suppose that (because of the ϵ on the highest-derivative) we have as before $X_0 = \frac{x}{\epsilon}$, $X_1 = x$

$$\text{Then } \frac{d^2}{dx^2} = \frac{1}{\epsilon^2} \frac{\partial^2}{\partial X_0^2} + \frac{2}{\epsilon} \frac{\partial^2}{\partial X_0 \partial X_1} + \frac{\partial^2}{\partial X_1^2}$$

\Rightarrow let $y = y_0 + \epsilon y_1 + \dots$ as usual, then

$$\left\{ \begin{aligned} & \epsilon \left(\frac{1}{\epsilon^2} \frac{\partial^2}{\partial X_0^2} + \frac{2}{\epsilon} \frac{\partial^2}{\partial X_0 \partial X_1} + \frac{\partial^2}{\partial X_1^2} \right) (y_0 + \epsilon y_1 + \dots) \\ & + \left(\frac{1}{\epsilon} \frac{\partial}{\partial X_0} + \frac{\partial}{\partial X_1} \right) (y_0 + \epsilon y_1 + \dots) + (y_0 + \epsilon y_1 + \dots) = 0 \end{aligned} \right.$$

$$y_0(0, 0) = 0 \quad y_1(0, 0) = 0 \quad \dots$$

$$y_0\left(\frac{1}{\epsilon}, 1\right) = 1 \quad y_1\left(\frac{1}{\epsilon}, 1\right) = 0 \quad \dots \quad \begin{array}{l} \text{since } X_0 = \frac{1}{\epsilon} \text{ when } x=1 \\ \text{and } X_1 = 1 \text{ " " " "} \end{array}$$

\Rightarrow To order ϵ^{-1} :

$$\left\{ \begin{aligned} & \frac{\partial^2 y_0}{\partial X_0^2} + \frac{\partial y_0}{\partial X_0} = 0 \quad \rightarrow \text{has solutions} \\ & y_0(0, 0) = 0 \\ & y_0\left(\frac{1}{\epsilon}, 1\right) = 1 \end{aligned} \right. \quad \begin{array}{l} y_0(X_0, X_1) = A(X_1) e^{-X_0} + B(X_1) \\ \implies A(0) + B(0) = 0 \\ \implies A(1) e^{-\frac{1}{\epsilon}} + B(1) = 1 \end{array}$$

To zeroth order

$$\left\{ \begin{aligned} & \frac{\partial^2 y_1}{\partial X_0^2} + 2 \frac{\partial^2 y_0}{\partial X_0 \partial X_1} + \frac{\partial y_1}{\partial X_0} + \frac{\partial y_0}{\partial X_1} + y_0 = 0 \\ & y_1(0, 0) = 0 \\ & y_1\left(\frac{1}{\epsilon}, 1\right) = 0 \end{aligned} \right.$$

$$\Rightarrow \frac{\partial^2 y_1}{\partial x_0^2} + \frac{\partial y_1}{\partial x_0} = - \left[2 \frac{\partial^2 y_0}{\partial x_0 \partial x_1} + \frac{\partial y_0}{\partial x_1} + y_0 \right]$$

$$= - \left[-2 \frac{\partial A}{\partial x_1} e^{-x_0} + \frac{\partial A}{\partial x_1} e^{-x_0} + \frac{\partial B}{\partial x_1} + A e^{-x_0} + B \right]$$

To eliminate all terms that could lead to secular growth in x_0 , we need to eliminate the terms in e^{-x_0} and the terms independent of x_0 :

$$\begin{cases} -2 \frac{\partial A}{\partial x_1} + \frac{\partial A}{\partial x_1} + A = 0 & \Rightarrow \frac{\partial A}{\partial x_1} = -A \\ \frac{\partial B}{\partial x_1} + B = 0 & \Rightarrow \frac{\partial B}{\partial x_1} = -B \end{cases}$$

so $A(x_1) = A(0)e^{-x_1}$ $B(x_1) = B(0)e^{-x_1}$

Applying the BCs we then have:

$$A(0) + B(0) = 0$$

$$A(0)e^{1-\frac{1}{\epsilon}} + B(0)e^{-1} = 1$$

$$\Rightarrow A(0) = -B(0)$$

$$\Rightarrow B(0) [e^{-1} - e^{1-\frac{1}{\epsilon}}] = 1$$

$$\Rightarrow B(0) = \frac{1}{e^{-1} - e^{1-\frac{1}{\epsilon}}} = \frac{e}{1 - e^{2-\frac{1}{\epsilon}}}$$

and finally, $y_0(x_0, x_1) = \frac{e}{e^{2-\frac{1}{\epsilon}} - 1} [e^{x_1-x_0} - e^{-x_1}]$

$$= \frac{e}{e^{2-\frac{1}{\epsilon}} - 1} [e^{x-\frac{x}{\epsilon}} - e^{-x}]$$

For small ϵ , $e^{2-\frac{1}{\epsilon}} \approx e^{-\frac{1}{\epsilon}} \rightarrow 0$ so

$$y(x) \rightarrow -e^{1+x-\frac{x}{\epsilon}} + e^{1-x}$$

This is indeed a uniform expansion of the true solution for small ϵ .