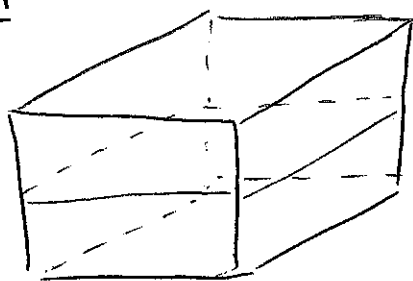


[25]

Problem 1

(a) Mathematical model. [3]

$$\begin{aligned} \bullet \quad \frac{\partial T}{\partial t} &= k \nabla^2 T = \nabla^2 T \quad \text{if } k=1 \\ &= T_{xx} + T_{yy} + T_{zz} \quad \text{in cartesian system} \end{aligned}$$

$$\bullet \quad T = 0 \quad \text{on all sides of cube}$$

$$\bullet \quad T(x, y, z, 0) = \begin{cases} 10 & \text{if } z < \frac{1}{2} \\ 50 & \text{if } z > \frac{1}{2} \end{cases}$$

[2] (b) At time $t=0$, say $T(x, y, z, 0) = 10$ for $z < \frac{1}{2}$ and $x \in (0, 1)$

but $T=0$ at $x=0$ and $x=1$

\rightarrow the system is not independent of x .

• Similarly for y

• System clearly depends on z .

(c) let $T(x, y, z, t) = A(x, y, z) B(t)$

$$\rightarrow \begin{cases} B_t = -\lambda B \\ T_{xx} + A_{yy} + A_{zz} = -\lambda A \end{cases}$$

we expect $\lambda > 0$ to avoid exponentially growing solutions

$$\text{let } A_{xx} + A_{yy} = -A_{zz} - \lambda A$$

$$\text{if } A(x, y, z) = \alpha(x) \beta(y) \gamma(z) \text{ then}$$

$$\gamma(\beta \alpha_{xx} + \alpha \beta_{yy}) = -\alpha \beta \gamma_{zz} - \alpha \beta \gamma \lambda$$

$$\Rightarrow \frac{\alpha_{xx}}{\alpha} + \frac{\beta_{yy}}{\beta} = -\frac{\gamma_{zz}}{\gamma} - \lambda = \text{constant } K$$

$$\Rightarrow \gamma_{zz} = (-\lambda - K) \gamma$$

Then $\frac{dxx}{d} + \frac{\beta yy}{\beta} = K$

2.

$\Rightarrow \frac{dxx}{d} = K - \frac{\beta yy}{\beta} = -C^2$

↑ expect a negative constant to fit BCs (homogeneous, $T=0$ in x)

$\Rightarrow \begin{cases} d_{xx} = -C^2 d \\ \beta_{yy} = (K + C^2) \beta \\ \gamma_{zz} = -(A + K) \gamma \end{cases} \rightarrow [5]$

• To fit the x -boundary conditions we expect $d_n(x) = \sin(n\pi x)$ and $C_n = n\pi$ [2]

• To fit the y -boundary conditions, we need $K + C_n^2 < 0$ too, in which case we pick up another \sin function for β :

$\beta_m(y) = \sin(m\pi y)$

and $K + C_n^2 = -m^2 \pi^2$

so $K_{nm} = -(n^2 + m^2) \pi^2$ [2]

• To fit the z -boundary conditions we need $-A - K$ negative, in which case we pick up a third "sin" function:

$\gamma_l(z) = \sin(l\pi z)$

and $-A - K_{nm} = -l^2 \pi^2$

so $\lambda_{lnm} = (l^2 + n^2 + m^2) \pi^2$ [2]

\Rightarrow finally we get

$T(x, y, z, t) = \sum_{l, n, m} d_{lnm} \sin(n\pi x) \sin(m\pi y) \sin(l\pi z) e^{-\lambda_{lnm} t}$

$- \lambda_{lnm} t$

[2]

How to fit the initial conditions?

3.

We have

$$T(x, y, z, 0) = \sum_{n, m} \alpha_{n, m, l} \sin(n\pi x) \sin(m\pi y) \sin(l\pi z) = \begin{cases} 10 & \text{if } z < \frac{1}{2} \\ 50 & \text{if } z > \frac{1}{2} \end{cases}$$

$$\rightarrow \alpha_{n, m, l} = \frac{\int_0^1 \int_0^1 \int_0^1 \sin(n\pi x) \sin(m\pi y) \sin(l\pi z) \cdot T_0(x, y, z) dx dy dz}{\int_0^1 \int_0^1 \int_0^1 \sin^2(n\pi x) \sin^2(m\pi y) \sin^2(l\pi z) dx dy dz} \quad [2]$$

The integrals separate:

$$\begin{aligned} \int_0^1 \sin(n\pi x) dx &= \frac{-1}{n\pi} [\cos(n\pi x)]_0^1 \\ &= -\frac{1}{n\pi} (\cos(n\pi) - 1) \\ &= -\frac{1}{n\pi} ((-1)^n - 1) = \begin{cases} \frac{2}{n\pi} & n \text{ odd} \\ 0 & n \text{ even} \end{cases} \end{aligned}$$

$$\int_0^1 \sin^2(n\pi x) dx = \frac{1}{2} \quad ; \text{ similarly for } y.$$

$$10 \int_0^{\frac{1}{2}} \sin(l\pi z) dz + \int_{\frac{1}{2}}^1 50 \sin(l\pi z) dz = \frac{-10}{l\pi} [\cos(\frac{l\pi}{2}) - 1] - \frac{50}{l\pi} [\cos(l\pi) - \cos(\frac{l\pi}{2})]$$

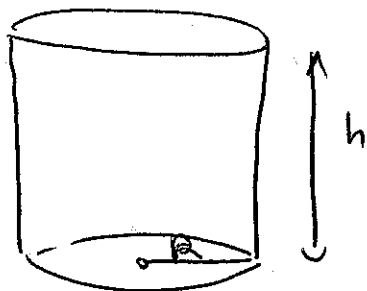
$$\rightarrow \alpha_{n, m, l} = 8 \cdot \left(\frac{1}{n\pi}\right) \left(\frac{1}{m\pi}\right) (1 - \cos(n\pi)) (1 - \cos(m\pi)) \quad [3]$$

$$\cdot \left\{ \frac{10}{l\pi} (1 - \cos(\frac{l\pi}{2})) + \frac{50}{2\pi} (\cos(\frac{l\pi}{2}) - \cos(l\pi)) \right\}$$

Global diffusion timescale: corresponds to τ_{diff} :

$$\tau_{diff} = \frac{1}{A_{diff}} = \frac{1}{3\pi^2} \quad [2]$$

Problem 2: [25]



$$V = 1 \Leftrightarrow \pi R^2 h = 1$$

$$\Leftrightarrow h = \frac{1}{\pi R^2} \quad [1]$$

We solve the same equation, $\frac{\partial T}{\partial t} = \nabla^2 T$ but this time in cylindrical coordinates. $\nabla^2 T =$ see below.

$$T(r, \theta, z, 0) = \begin{cases} 10 & \text{if } z < \frac{h}{2} \\ 50 & \text{if } z > \frac{h}{2} \end{cases} \quad [3]$$

$T = 0$ at $r = R, z = 0, z = h$.

Separation of variables: $T(r, \theta, z, t) = A(r, \theta, z) B(t)$

$$\begin{cases} B_t = -\lambda B \\ \nabla^2 A = -\lambda A \end{cases}$$

Note: In these solutions I forgot that the system is axisymmetric and did it in general case... But you may assume $\frac{\partial}{\partial \theta} = 0$ indeed!

$$\nabla^2 A = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial A}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 A}{\partial \theta^2} + \frac{\partial^2 A}{\partial z^2} = -\lambda A$$

$$\Rightarrow \text{let } A(r, \theta, z) = \alpha(r) \beta(\theta) \gamma(z)$$

$$\Rightarrow \frac{\beta \gamma}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \alpha}{\partial r} \right) + \frac{1}{r^2} \alpha \gamma \frac{\partial^2 \beta}{\partial \theta^2} + \alpha \beta \frac{\partial^2 \gamma}{\partial z^2} = -\lambda A$$

$$\Rightarrow \frac{1}{\alpha} \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \alpha}{\partial r} \right) + \frac{1}{r^2} \frac{1}{\beta} \frac{\partial^2 \beta}{\partial \theta^2} + \frac{1}{\gamma} \frac{\partial^2 \gamma}{\partial z^2} = -\lambda$$

$$\Rightarrow \frac{1}{\alpha} \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \alpha}{\partial r} \right) + \frac{1}{r^2} \frac{1}{\beta} \frac{\partial^2 \beta}{\partial \theta^2} = \underbrace{-\frac{1}{\gamma} \frac{\partial^2 \gamma}{\partial z^2} - \lambda}_{\text{f. of } z \text{ only}} = -K$$

$$\frac{1}{2} \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \alpha}{\partial r} \right) + \frac{1}{r^2} \frac{1}{\beta} \frac{d^2 \beta}{d\theta^2} = -k$$

$$\Rightarrow \frac{r}{2} \frac{d}{dr} \left(r \frac{d\alpha}{dr} \right) + kr^2 \alpha = - \frac{1}{\beta} \frac{d^2 \beta}{d\theta^2} = C$$

$$\Rightarrow \begin{cases} \frac{d^2 \beta}{d\theta^2} = -C\beta \\ r \frac{d}{dr} \left(r \frac{d\alpha}{dr} \right) + kr^2 \alpha = C\alpha \\ \frac{d^2 \gamma}{dz^2} = (-\lambda + k) \gamma \end{cases} \quad [6]$$

• β has to be periodic $\rightarrow C = n^2$ and

$$\beta_n(\theta) = a_n \cos n\theta + b_n \sin n\theta \quad [2]$$

$$\bullet \quad r^2 \frac{d^2 \alpha}{dr^2} + r \frac{d\alpha}{dr} + kr^2 \alpha - n^2 \alpha = 0$$

\rightarrow looks like a Bessel function equation
 provided $x^2 = kr^2 \quad x = \sqrt{k} r$

$$\rightarrow \alpha_{nm}(r) = J_n(\sqrt{k_{nm}} r) \quad [2]$$

To satisfy bcs at $r=R$ then $\sqrt{k_{nm}} R = \text{zero of Bessel } J_n$
 $= z_{n,m} \quad [2]$

$$\rightarrow \alpha_{nm}(r) = J_n\left(\frac{z_{nm} r}{R}\right)$$

$$\bullet \text{ finally: } \frac{d^2 \gamma}{dz^2} = \left[-\lambda + \left(\frac{z_{nm}}{R}\right)^2 \right] \gamma$$

\rightarrow needs to satisfy the BCS so the number
 in brackets has to be $-\frac{\ell^2 \pi^2}{h^2}$

$$[2] \quad \gamma(z) = \sin\left(\frac{\ell \pi z}{h}\right) \Rightarrow -\lambda_{\ell mn} + \left(\frac{z_{nm}}{R}\right)^2 = -\frac{\ell^2 \pi^2}{h^2} \quad [2]$$

so $\lambda_{lmn} = \frac{l^2 \pi^2}{h^2} + \left(\frac{z_{nm}}{R}\right)^2 \rightarrow z_{lmn} = (\lambda_{lmn})^{-1}$ 6.

Note: For axisymmetric case get $\lambda_{lm} = \frac{l^2 \pi^2}{h^2} + \left(\frac{z_{0m}}{R}\right)^2$
 The smallest possible value of λ_{lmn} occurs for $l=1$,
 and the minimum of z_{nm} for n, m spanning
 all possible values

nth zeros of	J_0	J_1	J_2
1	2.4	3.83	:
2	5.52	7.01	:

[2]

→ the lowest one is the first zero of J_0 : 2.404.....

→ λ_{lmn} is minimum for $l=1, n=0, m=1$ (first zero)

$$\lambda_{110} = \frac{\pi^2}{h^2} + \frac{(z_{01})^2}{R^2}$$

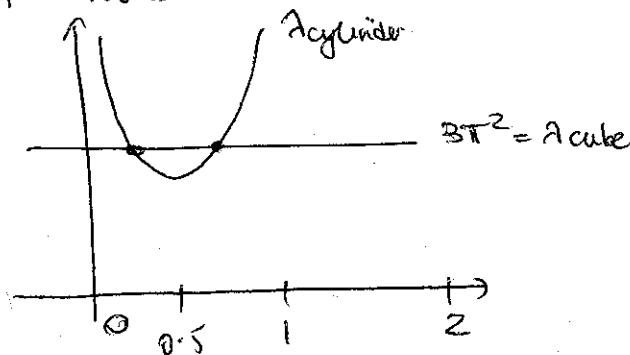
but $h = \frac{1}{\pi R^2} \Rightarrow$

$$\lambda_{110} = \frac{\pi^2}{\left(\frac{1}{\pi R^2}\right)^2} + \frac{(z_{01})^2}{R^2} = \pi^4 R^4 + \frac{(z_{01})^2}{R^2}$$

$\lambda_{cylinder} = \lambda_{cube} \Leftrightarrow$

$$\pi^4 R^4 + \left(\frac{z_{01}}{R}\right)^2 = 3\pi^2 \quad [2]$$

Plot shows



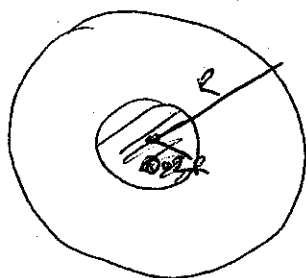
Intersections at

$R = 0.491 \rightarrow \frac{h}{R} = 2.689$

$R = 0.623 \rightarrow \frac{h}{R} = 1.316$

[3]

Problem 3 [25]



$$\left\{ \begin{aligned} \frac{\partial^2 p}{\partial t^2} &= c_0^2 \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial p}{\partial r} \right) \right] \\ p(0.2R, t) &= p(R, t) = 0 \\ c_0 &= 410^6 \text{ cm/s.} \end{aligned} \right.$$

(a) Radial eigenmode satisfies

[2]
$$\frac{c_0^2}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial p}{\partial r} \right) = -\omega^2 p \quad \text{for } r \in (0.2R, R)$$

↑ expect this form of constant for oscillations

[1] This is a regular problem since $r=0$ is not in the domain of interest.

(b) If $c(r) = c_0$ then

$$\frac{d^2 p}{dr^2} + \frac{2}{r} \frac{dp}{dr} = -\frac{\omega^2}{c_0^2} p \Rightarrow r^2 \frac{d^2 p}{dr^2} + 2r \frac{dp}{dr} + \frac{\omega^2}{c_0^2} p r^2 = 0$$

[3] ↪ This is a spherical Bessel function equation for the 0th-order functions, provided $x = \frac{\omega r}{c_0}$ $x = \frac{\omega}{c_0} r$

[2] ↪ the solutions are $j_0(x)$ and $y_0(x)$, so the general solution for p is

[2]
$$p(r) = a j_0\left(\frac{\omega}{c_0} r\right) + b y_0\left(\frac{\omega}{c_0} r\right) \quad \text{a, b to be determined}$$

(c) at $r=R$: $p(R) = 0$

[2]
$$\Rightarrow a j_0\left(\frac{\omega}{c_0} R\right) + b y_0\left(\frac{\omega}{c_0} R\right) = 0$$

at $r = 0.2R$:

$$[2] \Rightarrow a J_0\left(\frac{\omega}{C_0} \cdot \frac{R}{5}\right) + b y_0\left(\frac{\omega}{C_0} \frac{R}{5}\right) = 0$$

This is a system of 2 equations for 2 variables, of the type $MX = 0 \Rightarrow$ only has non-trivial solutions if $\det M = 0 \Rightarrow$

$$J_0\left(\frac{\omega}{C_0} R\right) y_0\left(\frac{\omega}{C_0} \frac{R}{5}\right) - J_0\left(\frac{\omega}{C_0} \frac{R}{5}\right) y_0\left(\frac{\omega}{C_0} R\right) = 0$$

Or, in other words, if $\xi = \frac{\omega R}{C_0}$, then

$$[2] f(\xi) = J_0(\xi) y_0\left(\frac{\xi}{5}\right) - J_0\left(\frac{\xi}{5}\right) y_0(\xi) = 0$$

(d) Plotting $f(\xi)$ yields the first 5 zeros

[5] approximately at $\xi = 4, 8, 12, 15.5$ and 19.5

(e) so the fundamental period of oscillation is:

$$[4] T_1 = \frac{2\pi}{\omega_1} \approx \frac{2\pi R}{4C_0} \approx \frac{\pi}{2} \cdot 310^3 = 4.7110^3 \text{ seconds} \approx 1.3 \text{ hours}$$

$$T_2 = \frac{2\pi}{\omega_2} \approx \frac{2\pi R}{8C_0} \approx \frac{T_1}{2} = 0.65 \text{ hours.}$$

Note: As it happens $J_0(\xi) = \frac{\sin \xi}{\xi}$ and $y_0(\xi) = -\frac{\cos \xi}{\xi}$

$$\text{so } J_0(\xi) y_0\left(\frac{\xi}{5}\right) - J_0\left(\frac{\xi}{5}\right) y_0(\xi) = 0$$

$$\Leftrightarrow \sin(\xi) \cos\left(\frac{\xi}{5}\right) - \sin\left(\frac{\xi}{5}\right) \cos(\xi) = 0$$

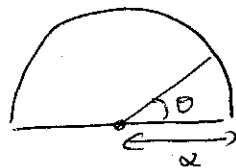
$$\Leftrightarrow \sin\left(\frac{4\xi}{5}\right) = 0 \Rightarrow \frac{4\xi}{5} = n\pi \Rightarrow \boxed{\xi = \frac{5n\pi}{4}}$$

and so $\omega_n = \frac{C_0}{R} \cdot \frac{5n\pi}{4}$ $T_0 = \frac{2\pi}{\omega_1}$

Problem 4

(Textbook 8.5-6) [25].

$$\left\{ \begin{aligned} \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} &= \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} + g(r, \theta, t) \\ \frac{\partial u}{\partial r} &= 0 \quad \text{at } r=a \\ u(r, \theta, t) &= u(r, \pi - \theta) = 0 \\ u(r, \theta, 0) &= H(r, \theta), \quad u_t(r, \theta, 0) = 0 \end{aligned} \right.$$



① let's look for the homogeneous problem first.

$$\frac{1}{c^2} \frac{\partial^2 u}{\partial t^2} = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2}$$

assuming $u(r, \theta, t) = \sum a(t) \phi(r, \theta)$ we have

$$\frac{\phi}{c^2} \frac{d^2 a}{dt^2} = \frac{a}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{a}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$$

$$\rightarrow \frac{1}{ac^2} \frac{d^2 a}{dt^2} = \frac{1}{\phi} \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} \right] = -\lambda$$

$\rightarrow \phi$ is the solution of $\nabla^2 \phi = -\lambda \phi$
 where $\nabla^2 \phi = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2}$

There will be an ∞ of such solutions, referenced by the indices n and m with $\nabla^2 \phi_{nm} = -\lambda_{nm} \phi$;

By Sturm-Liouville theory the ϕ_{nm} are orthogonal,

$$\text{with } \langle \phi_n, \phi_m \rangle = \iint_D \phi_n \phi_m d^2 r = \int_{r=0}^a \int_{\theta=0}^{\pi} r dr d\theta \phi_n \phi_m = 0 \text{ if } n \neq m$$

let's now go back to the original forced problem, and still assume $u(r, \theta, t) = \sum_{n,m} a_{nm}(t) \phi_{nm}(r, \theta)$

$$\begin{aligned} \rightarrow \frac{1}{c^2} \sum_{n,m} \phi_{nm} \frac{d^2 a_{nm}}{dt^2} &= \sum_{n,m} \nabla^2 \phi_{nm} \cdot a_{nm} + g(r, \theta, t) \\ &= - \sum_{n,m} \lambda_{nm} \phi_{nm} a_{nm} + g(r, \theta, t) \end{aligned}$$

so, by projecting onto the ϕ_{nm} we get

$$[4] \quad \frac{1}{c^2} \frac{d^2 a_{nm}}{dt^2} = -\lambda_{nm} a_{nm} + \frac{\int_0^{\alpha} \int_0^{\pi} r dr d\theta g(r, \theta, t) \phi_{nm}(r, \theta)}{\int_0^{\alpha} \int_0^{\pi} \phi_{nm}^2 r dr d\theta}$$

$$= -\lambda_{nm} a_{nm} + \frac{\langle g, \phi_{nm} \rangle}{\langle \phi_{nm}, \phi_{nm} \rangle}$$

At time $t=0$, $u(r, \theta, 0) = H(r, \theta)$ so

$$[2] \quad H(r, \theta) = \sum_{nm} a_{nm}(0) \phi_{nm}(r, \theta)$$

$$\rightarrow a_{nm}(0) = \frac{\langle H, \phi_{nm} \rangle}{\langle \phi_{nm}, \phi_{nm} \rangle}$$

$$u_t(r, \theta, 0) = 0 \quad \text{so}$$

$$[2] \quad 0 = \sum_{nm} a'_{nm}(0) \phi_{nm}(r, \theta) \Rightarrow a'_{nm}(0) = 0$$

(b) let's now solve for ϕ_{nm} and the eigenvalues λ_{nm} .

let $\phi_{nm}(r, \theta) = A(r)B(\theta)$ then

$$\frac{B}{r} \frac{\partial}{\partial r} \left(r \frac{\partial A}{\partial r} \right) + \frac{A}{r^2} \frac{\partial^2 B}{\partial \theta^2} = -\lambda_{nm} AB$$

$$\rightarrow \frac{1}{Ar} \frac{\partial}{\partial r} \left(r \frac{\partial A}{\partial r} \right) + \frac{1}{Br^2} \frac{\partial^2 B}{\partial \theta^2} = -\lambda$$

$$[3] \quad \rightarrow \frac{r}{A} \frac{\partial}{\partial r} \left(r \frac{\partial A}{\partial r} \right) + Ar^2 - \frac{1}{B} \frac{\partial^2 B}{\partial \theta^2} = +n^2$$

$$\rightarrow \frac{d^2 B}{d\theta^2} = -n^2 B$$

$$\rightarrow B_n(\theta) = \begin{cases} \cos n\theta \\ \sin n\theta \end{cases}$$

note: n has to be an integer to satisfy ~~periodicity~~ ~~in θ~~ .

$$\text{Then} \quad \frac{r}{A} \frac{d}{dr} \left(r \frac{dA}{dr} \right) + Ar^2 - n^2 = 0$$

$$\Rightarrow r^2 \frac{d^2 A}{dr^2} + r \frac{dA}{dr} + (Ar^2 - n^2)A = 0$$

$$[3] \quad \Rightarrow A(r) = \begin{cases} J_n(\sqrt{\lambda} r) \\ Y_n(\sqrt{\lambda} r) \end{cases} \quad (\text{see lecture notes})$$

To satisfy the boundary conditions in θ

$$u(r, 0, t) = u(r, \pi, t) = 0$$

with $B_n(\theta) = \alpha_n \cos n\theta + \beta_n \sin n\theta$

we have: $\alpha_n = 0$

$$\beta_n \sin n\pi = 0 \rightarrow \text{works}$$

So $B_n(\theta) = \sin n\theta$

To satisfy the BCs in r :

regularity at $r=0 \Rightarrow Y_n(\sqrt{\lambda} r)$ solution must be discarded

$$\frac{du}{dr} = 0 \text{ at } r=0 \Rightarrow J_n'(\sqrt{\lambda} a) = 0$$

$$\Rightarrow \sqrt{\lambda} a \text{ is a zero of } \frac{dJ_n}{dr}$$

let's call it z_{nm} .

[2]

$$\text{So } \lambda_{nm} = \left(\frac{z_{nm}}{a}\right)^2$$

$$\Rightarrow \text{finally, } \phi_{nm}(r, \theta) = \sin(n\theta) \cdot J_n\left(\frac{z_{nm}}{a} r\right)$$

where z_{nm} is the n^{th} zero of $\frac{dJ_n}{dr}$.

(c) The solution to $f'' = -\omega^2 f + g(t)$ being

$$f(t) = \frac{1}{\omega} \int_0^t g(t') \sin(\omega(t-t')) dt'$$

the solution to the time-dependent problem we have is

$$[4] \quad a_{nm}(t) = \frac{1}{\sqrt{\lambda_{nm}}} \int_0^t \frac{\langle g, \phi_{nm} \rangle}{\langle \phi_{nm}, \phi_{nm} \rangle} \cdot \sin\left(\sqrt{\lambda_{nm}}(t-t')\right) dt' + C_1 \cos(\sqrt{\lambda_{nm}} ct) + C_2 \sin(\sqrt{\lambda_{nm}} ct) \quad C_1, C_2 \text{ integration const}$$

To satisfy the initial conditions:

$$a'_{nm}(t) = \frac{c}{\sqrt{\lambda_{nm}}} \left[\frac{\langle g, \phi_{nm} \rangle}{\langle \phi_{nm}, \phi_{nm} \rangle} \sin(\sqrt{\lambda_{nm}} c (t-t')) + \int_0^t \frac{\langle g, \phi_{nm} \rangle}{\langle \phi_{nm}, \phi_{nm} \rangle} \cos(\sqrt{\lambda_{nm}} c (t-t')) \cdot \sqrt{\lambda_{nm}} \cdot dt' \right] + (-c_1 \sqrt{\lambda_{nm}} c) \sin(\sqrt{\lambda_{nm}} c t) + c_2 \sqrt{\lambda_{nm}} c \cos(\sqrt{\lambda_{nm}} c t)$$

$$\Rightarrow a'_{nm}(0) = 0 \Rightarrow \boxed{c_2 = 0}$$

$$a_{nm}(0) = 0 \Rightarrow \frac{c}{\sqrt{\lambda_{nm}}} \int_0^0 \frac{\langle g, \phi_{nm} \rangle}{\langle \phi_{nm}, \phi_{nm} \rangle} \sin(\sqrt{\lambda_{nm}} c (0-t')) dt' + c_1 = \frac{\langle H \phi_{nm} \rangle}{\langle \phi_{nm}, \phi_{nm} \rangle} \Rightarrow c_1 = \frac{\langle H \phi_{nm} \rangle}{\langle \phi_{nm}, \phi_{nm} \rangle}$$

[5]

So finally:

$$u(r, \theta, t) = \sum_{n,m} \sin(n\theta) \cdot J_n\left(\frac{z_{nm}}{a} r\right) \cdot \left\{ \frac{\langle H \phi_{nm} \rangle}{\langle \phi_{nm}, \phi_{nm} \rangle} \cdot \cos(\sqrt{\lambda_{nm}} c t) + \frac{c}{\sqrt{\lambda_{nm}}} \int_0^t \frac{\langle g, \phi_{nm} \rangle}{\langle \phi_{nm}, \phi_{nm} \rangle} \sin(\sqrt{\lambda_{nm}} c (t-t')) dt' \right\}$$