

PROBLEM

$$\begin{cases} u_t + uv_x = 0 \\ u(x,0) = u_0(x) = \tanh\left(\frac{x}{\epsilon}\right) \end{cases}$$

- Initial condition curve: $t_0(s) = 0$ $x_0(s) = s$ $u_0(s) = u_0(s)$
- Characteristics:

$$\frac{dt}{dz} = 1 \quad \rightarrow \quad t = z + t_0(s) = z$$

$$\frac{dx}{dz} = u \quad \longrightarrow \quad \frac{dx}{dz} = u_0(s) \quad \rightarrow \quad x = u_0(s)z + s$$

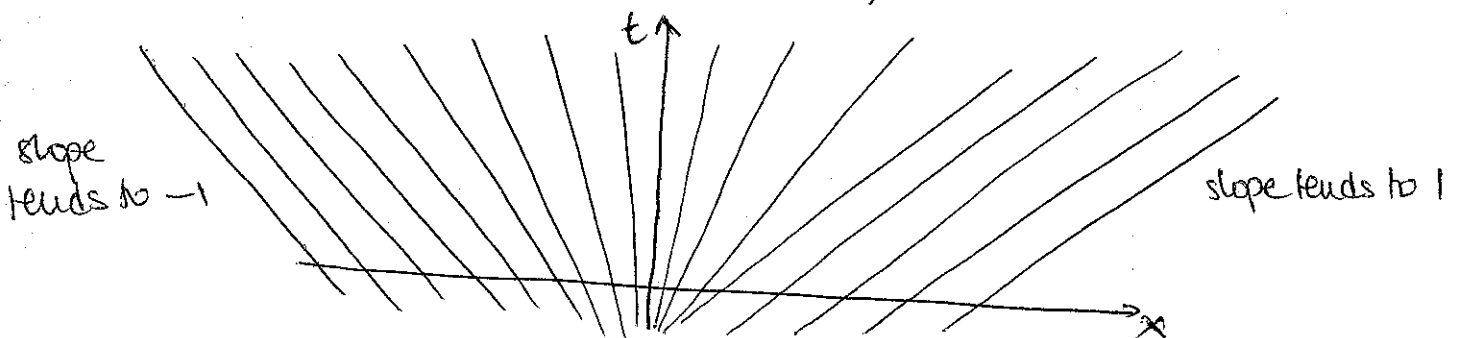
$$\frac{du}{dz} = 0 \quad \Rightarrow \quad u = u_0(s) = \text{constant}$$

\Rightarrow $x = \tanh\left(\frac{s}{\epsilon}\right)t + s$ is the equation
for the characteristics,
in other word

\Rightarrow $t = \frac{x-s}{\tanh\left(\frac{s}{\epsilon}\right)}$ \rightarrow defined everywhere
if $s \neq 0$.

If $s=0$ then the
characteristic is $x=0$.

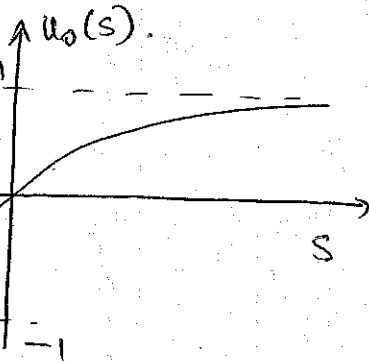
As $s \rightarrow -\infty$, $\tanh\left(\frac{s}{\epsilon}\right) \rightarrow -1$ } slope of
 $s \rightarrow +\infty$, $\tanh\left(\frac{s}{\epsilon}\right) \rightarrow +1$ } characteristic,



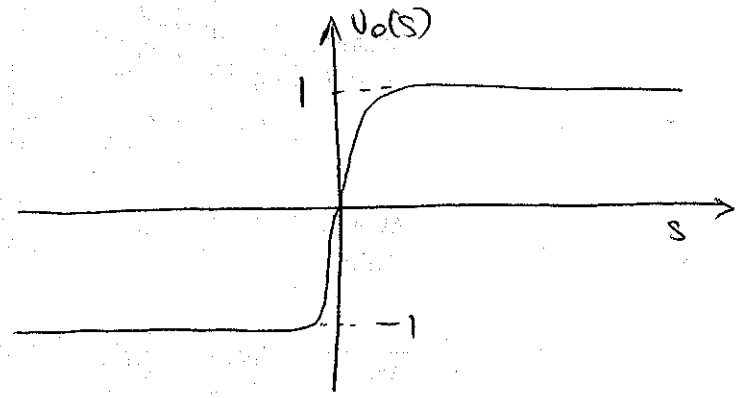
- Implicit solution for $u(x, t)$:

$$u(x, t) = u_0(x - ut) = \tanh\left(\frac{x - ut}{\epsilon}\right)$$

- ϵ large



- ϵ small



if $\epsilon \rightarrow 0$ then $\lim_{\epsilon \rightarrow 0} u_0(s) = \begin{cases} -1 & \text{if } s < 0 \\ 1 & \text{if } s > 0 \end{cases}$

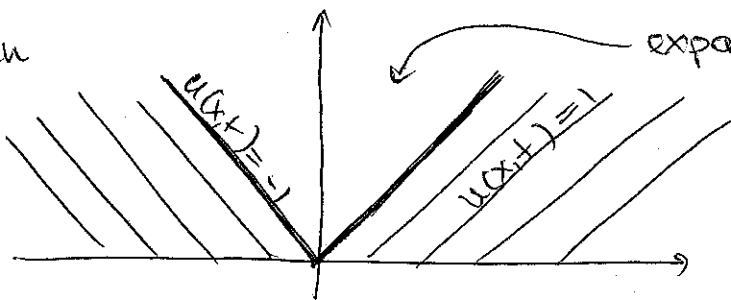
- if $|s| \gg \epsilon$ so when $s \gg \epsilon$ $u_0(s) \approx +1 \Rightarrow u(x, t) = 1$
 $s \ll -\epsilon$ $u_0(s) \approx -1 \Rightarrow u(x, t) \approx -1$

- if $s \ll \epsilon$ then $u_0(s) \approx \frac{s}{\epsilon}$ so we have

$$\begin{cases} x = \frac{s}{\epsilon}t + s \Rightarrow s = \frac{x}{\frac{t}{\epsilon} + 1} \\ u = \frac{s}{\epsilon} = \frac{x}{t + \epsilon} \approx \frac{x}{t} \end{cases}$$

- If we had used instead $u_0(s) = \begin{cases} +1 & \text{if } s > 0 \\ -1 & \text{if } s < 0 \end{cases}$

then



expansion shock, where

$$u(x, t) = G\left(\frac{x - 0}{\epsilon}\right)$$

$$G = \text{inverse of } F'(u) =$$

$$\rightarrow u(x, t) = \frac{x}{t}$$

as earlier.

$$4y^2 u_{xx} + 2(1-y^2) u_{xy} - u_{yy} - \frac{2y}{1+y^2} (20x - u_y) = 0$$

$$(a) \quad \delta = (1-y^2)^2 + 4y^2 = 1 - 2y^2 + y^4 + 4y^2 = 1 + 2y^2 + y^4 \\ = (1+y^2)^2 \quad \text{Hyperbolic}$$

$$\frac{dy}{dx} = \frac{b \pm \sqrt{b^2 - ac}}{4y^2}$$

$$\begin{cases} a = 4y^2 \\ b = (1-y^2) \\ c = -1 \end{cases}$$

$$= \frac{(1-y^2) \pm \sqrt{(1+y^2)^2}}{4y^2} = \begin{cases} 1-y^2 + (1+y^2) = 2 \\ 1-y^2 - (1+y^2) = -2y^2 \end{cases}$$

$$\frac{dy}{dx} = 2 \Rightarrow y = 2x + \xi \Rightarrow \boxed{\xi = y - 2x}$$

$$\frac{dy}{dx} = -2y^2 \Rightarrow -\frac{dy}{y^2} = 2dx \Rightarrow \frac{1}{y} = 2x + \eta \\ \boxed{\eta = \frac{1}{y} - 2x}$$

$$u_x = -2u_\xi + (-2)u_\eta = -2(u_\xi + u_\eta)$$

$$u_y = (1)u_\xi + \left(-\frac{1}{y^2}\right)u_\eta$$

$$u_{xx} = 4(u_{\xi\xi} + 2u_{\xi\eta} + u_{\eta\eta})$$

$$u_{xy} = \frac{\partial}{\partial x} \left(u_\xi - \frac{1}{y^2} u_\eta \right)$$

$$= \frac{\partial}{\partial x} (u_\xi) - \frac{1}{y^2} \frac{\partial}{\partial x} (u_\eta) = -2(u_{\xi\xi} + u_{\eta\xi}) + \frac{2}{y^2} (u_{\xi\eta} + u_{\eta\eta})$$

$$u_{yy} = \frac{\partial}{\partial y} \left(u_\xi - \frac{1}{y^2} u_\eta \right) = \frac{\partial}{\partial y} (u_\xi) + \frac{2}{y^3} u_\eta - \frac{1}{y^2} \frac{\partial}{\partial y} (u_\eta)$$

$$= u_{\xi\xi} - \frac{1}{y^2} u_{\xi\eta} + \frac{2}{y^3} u_\eta - \frac{1}{y^2} (u_{\xi\eta} - \frac{1}{y^2} u_{\eta\eta})$$

$$= u_{\xi\xi} - \frac{2}{y^2} u_{\xi\eta} + \frac{1}{y^4} u_{\eta\eta} + \frac{2}{y^3} u_\eta$$

PROBLEM 3

$$u_{tt} = c_s^2 \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) + \frac{\partial^2 u}{\partial z^2} \right]$$

- (a) $u(a, z, t) = 0 \quad \leftarrow$ zero velocity at $r=a$
 $u(r, 0, t) = u(r, L, t) = 0 \quad \leftarrow$ zero velocity at $z=0, L$
 $|u(r, z, t)| < +\infty \quad \leftarrow$ regularity condition

(b) $u(r, z, t) = A(r)B(z)C(t)$

$$AB C_{tt} = c_s^2 \left[\frac{BC}{r} \frac{\partial}{\partial r} \left(r \frac{\partial A}{\partial r} \right) + AC \frac{\partial^2 B}{\partial z^2} \right]$$

$$\rightarrow \frac{1}{C} C_{tt} = c_s^2 \left[\frac{1}{Ar} \frac{d}{dr} \left(r \frac{dA}{dr} \right) + \frac{1}{B} \frac{d^2 B}{dz^2} \right]$$

= constant. Expect oscillations so let it be a negative constant

$$= -\omega^2.$$

$$\Rightarrow \boxed{C_{tt} = -\omega^2 C}$$

$$\rightarrow \frac{1}{Ar} \frac{d}{dr} \left(r \frac{dA}{dr} \right) + \frac{1}{B} \frac{d^2 B}{dz^2} = -\frac{\omega^2}{c_s^2}$$

$$\rightarrow \frac{1}{Ar} \frac{d}{dr} \left(r \frac{dA}{dr} \right) + \frac{\omega^2}{c_s^2} = -\frac{1}{B} \frac{d^2 B}{dz^2} = \text{constant}$$

= Expect trapped modes with $B(0) = B(L) = 0$

\rightarrow need oscillatory functions so let this constant be > 0

$$= k^2.$$

→

$$B_{zz} = -k^2 B$$

So finally $\frac{1}{Ar} \frac{d}{dr} \left(r \frac{dA}{dr} \right) = k^2 - \frac{\omega^2}{c_s^2}$

$$\rightarrow \frac{1}{r} \frac{d}{dr} \left(r \frac{dA}{dr} \right) = \left(k^2 - \frac{\omega^2}{c_s^2} \right) A$$

(c) In the z -direction:

$$B(z) = \begin{cases} \cos kz \\ \sin kz \end{cases}$$

$B(0) = 0 \rightarrow$ no cosine

$B(L) = 0 \Rightarrow \sin(kL) = 0 \Rightarrow kL = n\pi \Rightarrow k = \frac{n\pi}{L}$

So we have n as the first index \rightarrow

z -eigenmodes are $B_n(z) = \sin\left(\frac{n\pi z}{L}\right)$

$$k_n = \frac{n\pi}{L}$$

(d) $\frac{1}{r} \frac{d}{dr} \left(r \frac{dA}{dr} \right) = \left(\frac{n^2 \pi^2}{L^2} - \frac{\omega^2}{c_s^2} \right) A$

Let's expand it \rightarrow

$$A_{rr} + \frac{A_r}{r} + \left(\frac{\omega^2}{c_s^2} - \frac{n^2 \pi^2}{L^2} \right) A = 0$$

becomes

$$r^2 A_{rr} + r A_r + r^2 \left(\frac{\omega^2}{c_s^2} - \frac{n^2 \pi^2}{L^2} \right) A = 0$$

if $\frac{\omega^2}{c_s^2} - \frac{n^2 \pi^2}{L^2} > 0$ then let

$$X^2 = r^2 \left(\frac{\omega^2}{c_s^2} - \frac{n^2 \pi^2}{L^2} \right)$$

$$X = r \sqrt{\frac{\omega^2}{c_s^2} - \frac{n^2 \pi^2}{L^2}}$$

$$\rightarrow x^2 A_{xx} + x A_x + x^2 = 0$$

$$\rightarrow A(x) = \begin{Bmatrix} J_0(x) \\ Y_0(x) \end{Bmatrix}$$

(e) Since $Y_0(x)$ is singular, we discard it

$$\Rightarrow A(r) = J_0\left(r \sqrt{\frac{\omega^2}{c_s^2} - \frac{n^2 \pi^2}{L^2}}\right)$$

Applying $A(a) = 0 \Rightarrow$

$$a \sqrt{\frac{\omega^2}{c_s^2} - \frac{n^2 \pi^2}{L^2}} = z_m$$

↑ mth 0 of the J_0 function.

$$\Rightarrow \frac{\omega^2}{c_s^2} - \frac{n^2 \pi^2}{L^2} = \frac{z_m^2}{a^2}$$

$$\Rightarrow \frac{\omega_{m,n}^2}{c_s^2} = \frac{n^2 \pi^2}{L^2} + \frac{z_m^2}{a^2} \quad \text{are the frequencies of the modes.}$$

$$\Rightarrow \omega_{mn} = c_s \sqrt{\frac{n^2 \pi^2}{L^2} + \frac{z_m^2}{a^2}}$$

And radial eigenmodes are $A_{mn}(r) = J_0\left(\frac{r z_m}{a}\right)$

(f) lowest frequency: $n=1$ and $z_1 \Rightarrow$

$$\omega_{11} = c_s \sqrt{\frac{\pi^2}{L^2} + \frac{z_1^2}{a^2}}$$

PROBLEM 4

$$T_t = ((1+x)^2 T_x)_x, \quad T(0,t) = T(L,t) = 0$$
$$T(x,0) = T_0(x)$$

(a) • $y = 1+x$

$\Rightarrow x = y - 1 \quad \frac{d}{dx} = \frac{d}{dy}$ so the equation easily becomes

$$T_t = (y^2 T_y)_y$$

• When $x=0 \quad y=1 \Rightarrow$ Boundary conditions become
 $x=L \quad y=1+L \quad T(1,t) = T(1+L,t) = 0.$

• $T(y,0) = T_0(\quad)$

(b) \rightarrow see below

(c) $(y^2 u_y)_y + \lambda u = 0 \quad u(1) = u(a) = 0$

Try a solution of the kind $u = y^\alpha$ then

$$\alpha(\alpha+1) + \lambda = 0 \Rightarrow \alpha^2 + \alpha + \lambda = 0$$

$$\Rightarrow \alpha = \frac{-1 \pm \sqrt{1-4\lambda}}{2}$$

so $u(y) = A y^{\left(-\frac{1}{2} + \sqrt{1-4\lambda}\right)} + B y^{\left(-\frac{1}{2} - \sqrt{1-4\lambda}\right)}$

to satisfy both bcs we will need oscillatory solutions $\rightarrow 1-4\lambda < 0 \Rightarrow u(y)$ also rewritten as

$$u(y) = y^{-\frac{1}{2}} \left[A y^{i\sqrt{4\lambda-1}} + B y^{-i\sqrt{4\lambda-1}} \right]$$

$$= y^{-\frac{1}{2}} \left[\hat{A} \cos(\sqrt{4\lambda-1} \ln y) + \hat{B} \sin(\sqrt{4\lambda-1} \ln y) \right]$$

since $y^\alpha = e^{\alpha \ln y}$

At $y=1$ need $u(y)=0 \Rightarrow$ cos term not needed

at $y=a$ need $u(a)=0 \Rightarrow \sin(\sqrt{4\lambda-1} \ln a) = 0$

$$\Rightarrow \sqrt{4\lambda-1} \ln a = n\pi$$

$$\Rightarrow 4\lambda-1 = \frac{n^2\pi^2}{\ln^2 a}$$

$$\Rightarrow \lambda_n = \frac{1}{4} \left(\frac{n^2\pi^2}{(\ln a)^2} + 1 \right)$$

and $v_n(y) = y^{-\frac{1}{2}} \sin\left(\frac{n\pi}{\ln a} \ln y\right)$

(b)
$$Q(u) = - \frac{\int_1^a u \cdot (y^2 u_y)_y dy}{\int_1^a u^2 dy}$$

$$= \frac{- \left[\cancel{u y^2 u_y} \right]_1^a + \int_1^a y^2 u_y^2 dy}{\int_1^a u^2 dy} \geq 0$$

because of bcs.

(d) Orthogonality:

$$\int_1^a v_n(y) v_m(y) dy = \delta_{nm} \|v_n\|^2$$

(e) $T_t = (y^2 T_y)_y \rightarrow$ by separation of variables let

$$T(y,t) = A(y)B(t) \Rightarrow \frac{1}{B} B_t = \frac{1}{A} (y^2 A_y)_y = -\lambda$$

Then using previous questions
$$\begin{cases} B_n(t) = e^{-\lambda_n t} \\ A_n(y) = v_n(y) \end{cases}$$

$$\Rightarrow T(y,t) = \sum_n B_n e^{-\lambda_n t} v_n(y)$$

with v_n, λ_n as above with $a=1+L$

$$T(y,t) = \sum_n \beta_n e^{-\frac{1}{4} \left(\frac{n^2 \pi^2}{[ln(1+L)]^2 + 1} \right) t} y^{-1/2} \sin \left(\frac{n\pi}{(1+L)} lny \right)$$

$$\left[T(x,t) = \sum_n \beta_n e^{-\frac{1}{4} \left(\frac{n^2 \pi^2}{[ln(1+L)]^2 + 1} \right) t} (1+x)^{-1/2} \sin \left(\frac{n\pi}{1+L} ln(1+x) \right) \right]$$

Applying initial conditions we have

$$T(x,0) = T_0(x) = \text{as above.} \quad \text{so} \quad T(y,0) = T_0(y-1).$$

$$\text{since } y = 1+x$$

\Rightarrow By orthogonality the β_n 's are given by

$$\beta_n = \frac{\langle T_0(y-1), v_n(y) \rangle}{\langle v_n(y), v_n(y) \rangle}$$