

Special case

Let's take the simplest possible example, that of constant sound-speed $c_s(r)$. Then

$$\frac{d}{dr} \left(r^2 \frac{dA}{dr} \right) - l(l+1)A = - \frac{\omega^2}{c_s^2} r^2 A$$

This is actually the equation for a spherical Bessel function.

Indeed, spherical Bessel functions satisfy

$$\frac{d}{dx} \left(x^2 \frac{dA}{dx} \right) - l(l+1)A + x^2 A = 0 \Rightarrow \text{as above if}$$

$$x = \frac{\omega}{c} r$$

$$A_l(x) = \begin{cases} j_l(x) \\ y_l(x) \end{cases}$$

The $y_l(x)$ functions are singular at $x=0$ \rightarrow discard

$$\text{At the surface, } A_l(x) = 0 \Rightarrow A_l\left(\frac{\omega}{c} R_{**}\right) = 0$$

\rightarrow this means that $\frac{\omega}{c} R_{**}$ are zeros of the Bessel $j_l(x)$ function. There is an infinite number of them, noted z_{ln} (the n -th zero of the $j_l(x)$ function)

$$\Rightarrow \omega_{ln} = \frac{z_{ln}}{R_{**}} c_s$$

\Rightarrow Finally, putting everything together we have

$$p(r, \theta, \phi, t) = \sum_{n, l, m} A_{ln}(r) B_l^m(\theta) C_m(\phi) D_{lnm}(t) \quad \text{where}$$

$$A_{ln}(r) = j_l\left(z_{ln} \frac{r}{R_{**}}\right)$$

$$C_m(\phi) B_l^m(\theta) = Y_l^m(\theta, \phi) \leftarrow \text{spherical harmonic}$$

$$D_{lnm}(t) = a_{lnm} \cos(\omega_{ln} t) + b_{lnm} \sin(\omega_{ln} t)$$

$$\text{where } \omega_{ln} = \frac{z_{ln}}{R_{**}} c_s$$

General case ($c_s^2(r)$ not known).

S-L theory can help us find out more about the system

There are an infinity of eigenmodes $A(r)$ and associated eigenvalues ω , which we can reference by the index n ($n \in \mathbb{N}$)

→ the modes are orthogonal, and form a basis for all functions in $(0, R)$ satisfying $|A(0)| < +\infty$, $A(R) = 0$.

→ Note how the equation depends on l but not on m : the frequencies of the modes ω depend only on n and l but not on m

The lowest frequency of oscillation ($n=0$, for a given l) is such that

$$\omega^2 = \inf_{u \in V} Q(u) = \inf \frac{\int_0^R \left[p(r) \left(\frac{du}{dr} \right)^2 - q(r) u^2(r) \right] dr}{\int_0^R w(r) u^2(r) dr}$$

↑
ensemble of all functions satisfying bcs

$$= \inf \frac{\int_0^R \left[r^2 \left(\frac{du}{dr} \right)^2 + l(l+1) u^2(r) \right] dr}{\int_0^R \frac{r^2}{c_s^2(r)} u^2(r) dr}$$

• For the sake of simplicity, assume $c_s^2(r) = \frac{C_0^2}{1 + \alpha \left(\frac{r}{R} \right)^2}$
(which is not too far from actual profile $C_0 = 4 \cdot 10^7$ cm/s, $\alpha \approx 12$.)

• To ensure regularity @ origin, need $u(r) \propto r^l$

To ensure $u=0$ @ $r=R$, need $u \propto (R-r)$

→ let $u(r) = r^l (R-r)$

$$\Rightarrow \frac{dU}{dr} = l r^{l-1} (R_0 - r) - r^l = r^{l-1} \{ l R_0 - (l+1)r \}$$

So $\omega^2 \approx \frac{\int_0^{R_0} r^{2l} (l R_0 - (l+1)r)^2 + l(l+1)r^{2l} (R_0 - r)^2 dr}{\int_0^{R_0} \frac{r^{2l}}{C_0^2} (R_0 - r)^2 (1 + \alpha (\frac{r}{R_0})^2) dr}$

$$= \frac{C_0^2 R_0^{2l+3} \int_0^1 x^{2l} (l - (l+1)x)^2 + l(l+1)x^{2l} (1-x)^2 dx}{R_0^{2l+5} \int_0^1 x^{2l+2} (1-x)^2 (1 + \alpha x^2) dx}$$

$$= \frac{C_0^2}{R_0^2} \frac{\int_0^1 x^{2l} [l(2l+1) - 4l(l+1)x + (l+1)(2l+1)x^2] dx}{\int_0^1 x^{2l+2} (1 - 2x + (1+\alpha)x^2 - 2\alpha x^3 + \alpha x^4) dx}$$

$$= \frac{C_0^2}{R_0^2} \left[\frac{l(2l+1)}{(2l+1)} - \frac{4l(l+1)}{2l+2} + \frac{(l+1)(2l+1)}{2l+3} \right]$$

$$\left[\frac{1}{2l+3} - \frac{2}{2l+4} + \frac{1+\alpha}{2l+5} - \frac{2\alpha}{2l+6} + \frac{\alpha}{2l+7} \right]$$

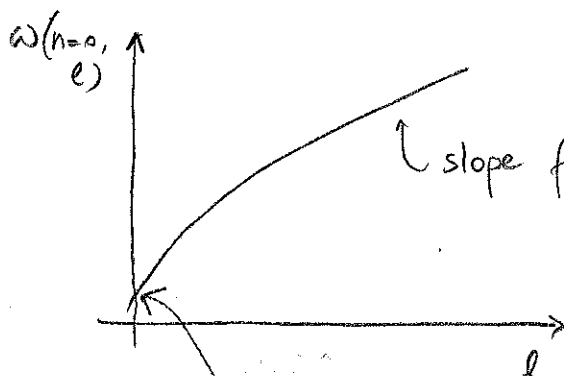
$$= \frac{C_0^2}{R_0^2} \frac{\frac{1}{2l+3}}{\frac{2}{(2l+3)(2l+4)(2l+5)} + \frac{2\alpha}{(2l+5)(2l+6)(2l+7)}}$$

As $l \rightarrow \infty$ then $\omega \approx \frac{C_0}{R_0} \frac{\sqrt{2l}}{1+\alpha}$

as $l=0$ $\omega \rightarrow \frac{C_0}{R_0} \frac{1}{\frac{1}{6} + \frac{\alpha}{35}}$

note: oscillation period is

$$T(l) = \frac{2\pi}{\omega}$$



low l behaviour gives other info on α and C_0

\Rightarrow The shape of $\omega(n=0, l)$ depends on C_0 and α in a way that can be fitted to data to infer C_0 and α
 \Rightarrow HELIOSEISMOLOGY

I Introduction

We now consider forced linear PDEs of the kind

$$\frac{\partial^2 v}{\partial t^2} - c^2 \frac{\partial^2 v}{\partial x^2} = F(x, t) \quad (\text{Forced Wave Equation})$$

$$\frac{\partial v}{\partial t} - k \frac{\partial^2 v}{\partial x^2} = F(x, t) \quad (\text{Forced Heat Equation})$$

$$\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} = F(x, y) \quad (\text{"Forced Laplace equation"} \\ = \text{Poisson equation})$$

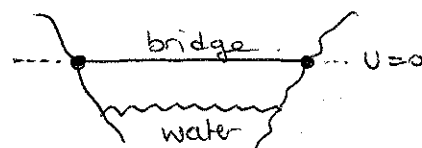
The method for solving these problems will be first illustrated through examples, then generalized in (II)

① Forced wave equation

Example: A bridge, suspended, and the wind forcing (cf Tacoma Narrows)

(in 2D: a metal plate, with some sand on it, and a speakerphone nearby; see Exploratorium).

$$\text{let } \begin{cases} \frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = F(x, t) \\ u(x, t=0) = 0 & u(0, t) = 0 \\ u_t(x, t=0) = 0 & u(L, t) = 0 \end{cases}$$



→ A forced string, pinned at the sides, initially at rest.

Method: 1. Find the spatial eigenmodes $A_n(x)$ homogeneous problem - with same bcs

$$\frac{\partial^2 v}{\partial t^2} - c^2 \frac{\partial^2 v}{\partial x^2} = 0$$

These will generally be mixtures of sines and cosines.

Here (see previous lectures)

$$A_n(x) = \sin\left(\frac{n\pi x}{L}\right)$$

2. Assume that the full solution can be written as

$$u(x,t) = \sum_{n=0}^{\infty} A_n(x) B_n(t)$$

and plug into PDE

$$\Rightarrow \sum_{n=0}^{\infty} A_n(x) \frac{d^2 B_n}{dt^2} - c^2 B_n(t) \frac{d^2 A_n}{dx^2} = F(x,t)$$

$$\Rightarrow \sum_{n=0}^{\infty} A_n(x) \frac{d^2 B_n}{dt^2} + \frac{c^2 n^2 \pi^2}{L^2} B_n(t) A_n(x) = F(x,t). \quad (*)$$

3. Note that $\int_0^L A_n(x) A_m(x) dx = 0 \quad \forall n \neq m$
 $= \frac{L}{2}$ if $n=m$

Aside: The orthogonality property of the eigenfunctions will be true for a wide class of problems, see next chapter.

So take (*) and multiply by $A_m(x)$, then integrate over $[0, L]$

$$\Rightarrow \frac{L}{2} \frac{d^2 B_m}{dt^2} + \frac{c^2 m^2 \pi^2}{L^2} \cdot \frac{L}{2} B_m = \int_0^L F(x,t) \sin\left(\frac{m\pi x}{L}\right) dx.$$

$$\Rightarrow \ddot{B}_m + \frac{c^2 m^2 \pi^2}{L^2} B_m = \frac{2}{L} \int_0^L F(x,t) \sin\left(\frac{m\pi x}{L}\right) dx \\ = f_m(t).$$

\Rightarrow we now get a set of independent ODEs, one for each value of m . These are forced, second-order linear ODEs. (which you should be able to solve...)

Simple example

$$\text{Suppose } F(x,t) = \sin\left(\frac{2\pi x}{L}\right) \cos(\omega t)$$

$$\text{then } f_m(t) = \int_0^L \frac{2}{L} \sin\left(\frac{2\pi x}{L}\right) \cos(\omega t) \sin\left(\frac{m\pi x}{L}\right) dx$$

$$= \begin{cases} \frac{2}{L} \cdot \frac{L}{2} \cdot \cos \omega t & \text{if } m=2 \\ 0 & \text{otherwise} \end{cases}$$

\Rightarrow we have 2 types of ODEs to solve:

$$\ddot{B}_2 + \frac{4c^2\pi^2}{L^2} B_2 = \cos \omega t$$

and $\ddot{B}_m + \frac{c^2 m^2 \pi^2}{L^2} B_m = 0 \quad \forall m \neq 2.$

For all of them, the solution to the homogeneous equation is

$$B_m(t) = \alpha_m \cos\left(\frac{cm\pi t}{L}\right) + \beta_m \sin\left(\frac{m\pi ct}{L}\right)$$

For the $B_2(t)$ function, we have to add a particular solution to the forced problem: here try

$$B_2^{\text{PS}}(t) = k \cos \omega t$$

\uparrow
a constant to be determined by plugging into equation

$$\Rightarrow -k\omega^2 + \frac{4c^2\pi^2}{L^2} k = 1$$

$$\Rightarrow k = \frac{1}{\frac{4c^2\pi^2}{L^2} - \omega^2}$$

$$\Rightarrow B_2(t) = \alpha_2 \cos\left(\frac{2c\pi t}{L}\right) + \beta_2 \sin\left(\frac{2c\pi t}{L}\right) + \frac{\cos(\omega t)}{\frac{4c^2\pi^2}{L^2} - \omega^2}$$

⇒ So finally, we have

$$u(x,t) = \sum_{n=1}^{\infty} A_n(x) B_n(t) \quad \text{where } A_n(x) = \sin\left(\frac{n\pi x}{L}\right)$$
$$B_n(t) = \alpha_n \cos\left(\frac{n\pi ct}{L}\right) + \beta_n \sin\left(\frac{n\pi ct}{L}\right) + \frac{c\omega\pi t}{4c^2\pi^2 - \omega^2} \delta_{n,2}$$

To find the arbitrary constants α_n, β_n , we fit the initial conditions:

$$u(x, 0) = 0$$

$$\Rightarrow \sum_{n=1}^{\infty} A_n(x) B_n(0) = 0$$

$$\Rightarrow \sum_{n=1}^{\infty} A_n(x) \left[\alpha_n + \frac{1}{\frac{4c^2\pi^2}{L^2} - \omega^2} \delta_{n,2} \right] = 0$$

$$\Rightarrow \alpha_n + \frac{1}{\frac{4c^2\pi^2}{L^2} - \omega^2} \delta_{n,2} = 0$$

$$\Rightarrow \begin{cases} \alpha_n = 0 & \text{if } n \neq 2 \\ \alpha_2 = -\frac{1}{\frac{4c^2\pi^2}{L^2} - \omega^2} \end{cases}$$

$$u_t(x, 0) = 0 \Rightarrow \sum_{n=1}^{\infty} A_n(x) \dot{B}_n(0) = 0$$

$$\Rightarrow \sum_{n=1}^{\infty} A_n(x) \left[\beta_n \frac{n\pi c}{L} \right] = 0$$

$$\Rightarrow \beta_n = 0 \quad \forall n.$$