

① Plug $v_0(\theta)$ and $v_1(\theta)$ into equation:

$$\frac{1}{\sin\theta} \frac{d}{d\theta} \left(\sin\theta \frac{dv_0}{d\theta} \right) = 0 = -\lambda_0 v_0 \Rightarrow \lambda_0 = 0$$

$$\frac{1}{\sin\theta} \frac{d}{d\theta} \left(\sin\theta \frac{dv_1}{d\theta} \right) = -\frac{1}{\sin\theta} \frac{d}{d\theta} (\sin^2\theta)$$

$$= -\frac{2\sin\theta \cos\theta}{\sin\theta} = -2\cos\theta = -\lambda_1 v_1$$

$$\Rightarrow \lambda_1 = 2$$

② • The boundary conditions are independent of ϕ
 \rightarrow we expect the solution to be independent of ϕ as well.

• The boundary conditions can be written as

$$\sum \alpha_n v_n(\theta) \quad \text{with} \quad v_n(\theta) =$$

some eigenfunctions
of the θ -operator

\Rightarrow we expect the solution to have the same property

$$\rightarrow T(r, \theta, \phi) = \tilde{T}(r, \theta) \quad \leftarrow \text{no } \phi \text{ dependence}$$

$$= f_0(r) v_0(\theta) + f_1(r) v_1(\theta)$$

$$= f_0(r) + f_1(r) \cos\theta.$$

Plugging this into the equation \Rightarrow

$$\frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{df_0}{dr} \right) + \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{df_1}{dr} \right) \cos\theta + \frac{1}{r^2} \frac{f_1(r)}{\sin\theta} \frac{d}{d\theta} \left(\sin\theta \frac{d\cos\theta}{d\theta} \right) = 0$$

$$\Rightarrow \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{df_0}{dr} \right) + \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{df_1}{dr} \right) \cos\theta - \frac{2}{r^2} f_1(r) \cos\theta = 0.$$

which implies $\left\{ \begin{array}{l} \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{df_0}{dr} \right) = 0 \\ \frac{1}{r^2} \frac{d}{dr} \left(r^2 \frac{df_1}{dr} \right) - \frac{2}{r^2} f_1 = 0 \end{array} \right.$

$$r^2 \frac{df_0}{dr} = \text{constant} = A$$

$$\Rightarrow \frac{df_0}{dr} = \frac{A}{r^2} \Rightarrow f_0 = -\frac{A}{r} + B$$

Solve for f_1 : try $f_1 = r^\alpha$: $\frac{d^2 f_1}{dr^2} + \frac{2}{r} \frac{df_1}{dr} - \frac{2}{r^2} f_1 = 0$

then $\alpha(\alpha-1) + 2\alpha - 2 = 0$

$$\Rightarrow \alpha(\alpha-1) + 2(\alpha-1) = 0$$

$$\Rightarrow (\alpha+2)(\alpha-1) = 0 \Rightarrow \begin{cases} \alpha = 1 \\ \alpha = -2 \end{cases}$$

So $f_1 = Cr + \frac{D}{r^2}$

So finally $T(r, \theta, \phi) = -\frac{A}{r} + B + \left(Cr + \frac{D}{r^2}\right) \cos \theta$

③ Fit up to boundary conditions:

$$T(a, \theta, \phi) = T_0 \Rightarrow$$

$$-\frac{A}{a} + B + \left(Ca + \frac{D}{a^2}\right) \cos \theta = T_0$$

$$\Rightarrow \begin{cases} -\frac{A}{a} + B = T_0 & (*) \\ Ca + \frac{D}{a^2} = 0 & (**) \end{cases}$$

$$T(b, \theta, \phi) = T_1 + T_2 \cos \theta \Rightarrow$$

$$-\frac{A}{b} + B + \left(Cb + \frac{D}{b^2}\right) \cos \theta = T_1 + T_2 \cos \theta$$

$$\Rightarrow \begin{cases} -\frac{A}{b} + B = T_1 & (†) \\ Cb + \frac{D}{b^2} = T_2 & (‡) \end{cases}$$

From (**) $\Rightarrow C = -\frac{D}{a^3}$

(‡) $\Rightarrow -\frac{Db}{a^3} + \frac{D}{b^2} = T_2 \Rightarrow D = \frac{T_2}{\frac{1}{b^2} - \frac{b}{a^3}}$

From (*) - (†) : $-\frac{A}{a} + \frac{A}{b} = T_0 - T_1$

$$\Rightarrow A = \frac{T_0 - T_1}{\frac{1}{a} - \frac{1}{b}} = \frac{ab(T_0 - T_1)}{b - a}$$

and finally $B = T_0 + \frac{A}{a} = T_0 + \frac{b(T_0 - T_1)}{a - b}$

$$\Rightarrow T(r, \theta, \phi) = -\frac{ab(T_0 - T_1)}{a - b} \frac{1}{r} + T_0 + \frac{b(T_0 - T_1)}{a - b} + \left(-\frac{1}{a^3} r + \frac{1}{r^2} \right) \left(\frac{T_2}{\frac{1}{b^2} - \frac{b}{a^3}} \right) \cos \theta$$

Note: simplify with $D = \frac{T_2 b^2 a^3}{a^3 - b^3}$

$$C = -\frac{D}{a^3} = \frac{T_2 b^2}{b^3 - a^3}$$

$$\begin{aligned} \Rightarrow T(r, \theta, \phi) &= T_0 + \frac{b(T_1 - T_0)}{b - a} \left(1 - \frac{a}{r} \right) \\ &+ \left(\frac{1}{r^2} - \frac{r}{a^3} \right) \frac{T_2 b^2 a^3}{a^3 - b^3} \cos \theta \\ &= T_0 + \frac{b(T_1 - T_0)}{b - a} \left(1 - \frac{a}{r} \right) \\ &+ \left(\frac{a^2}{r^2} - \frac{r}{a} \right) \frac{T_2 b^2 a}{a^3 - b^3} \cos \theta \end{aligned}$$

Check: at $r = a$: $T = T_0$ ✓

at $r = b$ $T = T_0 + \frac{b(T_1 - T_0)}{b - a} \left(1 - \frac{a}{b} \right)$

$$+ \left(\frac{a^2}{b^2} - \frac{b}{a} \right) \frac{T_2 b^2 a}{a^3 - b^3} \cos \theta$$

$$= T_0 + T_1 - T_0 + T_2 \cos \theta$$

$$= T_1 + T_2 \cos \theta \quad \checkmark$$